# Weierstraß-Institut für Angewandte Analysis und Stochastik <br> Leibniz-Institut im Forschungsverbund Berlin e. V. 

# Definition of fractional Laplacian for functions with polynomial growth 

Serena Dipierro ${ }^{1}$, Ovidiu Savin ${ }^{2}$, Enrico Valdinocil ${ }^{1,3,4,5}$

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| 1 | School of Mathematics and Statistics | 2 | Department of Mathematics |
| :--- | :--- | :--- | :--- |
| University of Melbourne | Columbia University | Weierstrass Institute |  |
| Richard Berry Building | 2990 Broadway | Mohrenstr. 39 |  |
| Parkville VIC 3010 | New York, NY 10027 | 10117 Berlin |  |
| Australia | USA | Germany |  |
| E-Mail: serydipierro@yahoo.it | E-Mail: savin@math.columbia.edu | E-Mail: enrico.valdinoci@wias-berlin.de |  |

4 Dipartimento di Matematica Università degli studi di Milano Via Saldini 50 20133 Milan Italy E-Mail: enrico@mat.uniroma3.it

5 Istituto di Matematica Applicata e Tecnologie Informatiche Consiglio Nazionale delle Ricerche Via Ferrata 1 27100 Pavia Italy

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[^0]Edited by
Weierstraß-Institut für Angewandte Analysis und Stochastik (WIAS)
Leibniz-Institut im Forschungsverbund Berlin e. V.
Mohrenstraße 39
10117 Berlin
Germany
Fax: $\quad+4930$ 20372-303

E-Mail: preprint@wias-berlin.de
World Wide Web: http://www.wias-berlin.de/


#### Abstract

We introduce a notion of fractional Laplacian for functions which grow more than linearly at infinity. In such case, the operator is not defined in the classical sense: nevertheless, we can give an ad-hoc definition which can be useful for applications in various fields, such as blowup and free boundary problems.

In this setting, when the solution has a polynomial growth at infinity, the right hand side of the equation is not just a function, but an equivalence class of functions modulo polynomials of a fixed order.

We also give a sharp version of the Schauder estimates in this framework, in which the full smooth Hölder norm of the solution is controlled in terms of the seminorm of the nonlinearity.

Though the method presented is very general and potentially works for general nonlocal operators, for clarity and concreteness we focus here on the case of the fractional Laplacian.


## 1 Introduction

As well known (see e.g. [7, 15, 20]), to define the fractional Laplacian of a function ${ }^{1}$ as

$$
\begin{equation*}
(-\Delta)^{s} u(x):=\lim _{\varepsilon \rightarrow 0} \int_{\mathbb{R}^{n} \backslash B_{\varepsilon}(x)} \frac{u(x)-u(y)}{|x-y|^{n+2 s}} d y \tag{1.1}
\end{equation*}
$$

with $s \in(0,1)$, two types of assumptions are needed, namely:
$\square$ the function $u$ needs to be sufficiently regular near $x$,
$\square$ the function $u$ needs to have a growth control at infinity.

The regularity condition is indeed needed in order to make the integral in (1.1) convergent near the singularity (possibly after cancellation). On the other hand, the growth condition at infinity is needed to make the tail of the integrand convergent: for this scope, usually the most general assumption on $u$ at infinity can be written in the form

$$
\begin{equation*}
\int_{\mathbb{R}^{n}} \frac{|u(y)|}{1+|y|^{n+2 s}} d y<+\infty \tag{1.2}
\end{equation*}
$$

The need of assumptions at infinity is a typical feature of fractional problems (of course, in the case of the classical Laplacian, there is no need to prescribe this kind of conditions in order to compute derivatives). In this sense, the study of nonlocal operators presents several conceptual difficulties with respect to the classical case, inherited from the fact that the behavior at infinity may deeply affect the value of the fractional Laplacian: see e.g. [8, 9] for rather general examples (in particular, roughly speaking, appropriate oscillations at infinity can make the fractional Laplacian vanish identically in a given ball, basically independently on the values of the function in such a ball).

In addition, conditions at infinity such as (1.2) often provide a series of additional difficulties in the regularity theories for fractional operators since this type of assumptions behaves badly with respect to scalings and blowups: as an example, one can consider a function which is bounded and quadratic near the origin and check that its blowup does not satisfy (1.2) (in spite of the fact that both the original function and its blowup may be as smooth as we wish).

[^1]The goal of this paper is to provide a natural setting to make sense of the fractional Laplacian under weaker conditions at infinity. Of course, some condition at infinity must be taken in order to avoid the examples in [8,9], nevertheless we give here a framework which is more flexible and compatible with scalings and blowups.

The basic idea for this is that, if the function grows too much at infinity, its fractional Laplacian diverges, but it can be written as a given function "plus a diverging sequence of polynomials ${ }^{2}$ of a given degree". For instance, if the function grows linearly at infinity and $s=1 / 2$, then condition (1.2) is violated and $\sqrt{-\Delta}$ cannot be defined in the usual sense. We will see that, in this case, a definition is possible, up to "a diverging sequence of constants".

From this, one is formally allowed to "take derivatives of the equation" and obtain regularity estimates: in the previous example, one would say that the derivatives of the constants play no role and, in case one has "polynomials of degree $k-1$ as a remainder", the equation will be well posed "up to derivatives of order $k$ " (which make these polynomials vanish). Clearly, a rather delicate argument will be used to check that this formal idea makes sense at all, since these additional "remainders" are divergent and so they do not obviously vanish after differentiation.

As a matter of fact, to introduce the general setting of possibly divergent fractional Laplacians and to develop the related regularity theory, we will use sequences of cutoffs to reduce the problem to the more usual setting and we will obtain uniform estimates in an appropriate sense. To this aim, we consider ${ }^{3}$ the family of cutoffs

$$
\chi_{R}(x):= \begin{cases}1 & \text { if } x \in B_{R}  \tag{1.3}\\ 0 & \text { otherwise }\end{cases}
$$

and we fix the following setting.
Definition 1.1. Let $s \in(0,1), k \in \mathbb{N}, u: \mathbb{R}^{n} \rightarrow \mathbb{R}$ and $f: B_{1} \rightarrow \mathbb{R}$. Assume that $u$ is continuous in $B_{1}$ and

$$
\begin{equation*}
\int_{\mathbb{R}^{n}} \frac{|u(y)|}{1+|y|^{n+2 s+k}} d y<+\infty \tag{1.4}
\end{equation*}
$$

We say that

$$
(-\Delta)^{s} u \stackrel{k}{=} f \quad \text { in } B_{1}
$$

if there exist a family of polynomials $P_{R}$, which have degree at most $k-1$, and functions $f_{R}: B_{1} \rightarrow \mathbb{R}$ such that

$$
\begin{equation*}
(-\Delta)^{s}\left(\chi_{R} u\right)=f_{R}+P_{R} \tag{1.5}
\end{equation*}
$$

in $B_{1}$ in the viscosity sense, with

$$
\begin{equation*}
\lim _{R \rightarrow+\infty} f_{R}(x)=f(x) \tag{1.6}
\end{equation*}
$$

for any $x \in B_{1}$.

We stress again the fact that a classical definition of $(-\Delta)^{s}$ is not available in the setting of Definition 1.1 (not even for smooth functions) unless one requires condition (1.2) (and, of course, the condition in (1.4) is weaker than the one in (1.2) when $k \geqslant 1$ ). In this sense, the notation $(-\Delta)^{s} u$ in the case of Definition 1.1 represents a "divergent" operator. Nevertheless, as we will see in the forthcoming Corollary 3.2, it is always possible to construct a function $f$ as requested by Definition 1.1 (in particular, the set of functions $u$ for which Definition 1.1 makes sense is non-void).

Also, as it will be discussed in Corollary 3.8, the notion given by Definition 1.1 reduces to the standard fractional Laplacian when $k=0$.

[^2]Moreover, it follows easily from Definition 1.1 that

$$
\begin{equation*}
\text { if }(-\Delta)^{s} u \stackrel{k}{=} f \text { in } B_{1} \text {, then }(-\Delta)^{s} u \stackrel{k+1}{=} f \text { in } B_{1} \tag{1.7}
\end{equation*}
$$

In terms of applications, we mention that condition (1.2) is often "too rigid" in the nonlocal framework: for instance, in many free boundary problems, it is important to look at blowup sequences with degree higher than one (say, $3 / 2$ ), and the blowup will not satisfy (1.2), see e.g. [4,10]. Some ad-hoc arguments have been sometimes exploited in the literature to overcome this type of difficulties, but we believe that a setting as the one in Definition 1.1 can provide technical simplifications and conceptual advantages when dealing with these cases.

We also observe that the function $f$ in Definition 1.1 is not uniquely determined, since any fixed polynomial can be added to $f_{R}$ (and subtracted to $P_{R}$ ) without affecting the setting in Definition 1.1, and so

$$
\begin{equation*}
\text { if }(-\Delta)^{s} u \stackrel{k}{=} f \text { in } B_{1} \text {, then }(-\Delta)^{s} u \stackrel{k}{=} f+P \text { in } B_{1} \text { for any polynomial of degree } k-1 \tag{1.8}
\end{equation*}
$$

Nevertheless, the multiplicity in (1.8) is exactly the one which characterizes $f$. Namely, we have that $f$ is determined up to polynomials of degree $k-1$, as pointed out by the following observation (whose simple proof is given in Section 2):

Lemma 1.2. Assume that $(-\Delta)^{s} u \stackrel{k}{=} f$ and $(-\Delta)^{s} u \stackrel{k}{=} \tilde{f}$ in $B_{1}$. Then, there exists a polynomial $P$ of degree at most $k-1$ such that $f-\tilde{f}=P$.

As an illustrative example of our setting, let us point out that one can compute $\sqrt{-\Delta} u$ when $u(x)=x^{2}$ in dimension $n=1$, using Definition 1.1 with $k=2$. Indeed by a direct computation, one sees that

$$
\begin{equation*}
\sqrt{-\Delta} x^{2} \stackrel{2}{=} 0 \tag{1.9}
\end{equation*}
$$

and in fact a more general result will be presented in Theorem 1.5 below.
Of course, from (1.9) and Lemma 1.2, a bunch of "curious" identities follows, such as

$$
\begin{array}{ccc}
\sqrt{-\Delta} x^{2} \stackrel{2}{=} 0, & \sqrt{-\Delta} x^{2} \stackrel{2}{=} 1, & \sqrt{-\Delta} x^{2} \stackrel{2}{=}-1 \\
\sqrt{-\Delta} x^{2} \stackrel{2}{=} x & \sqrt{-\Delta} x^{2} \stackrel{2}{=} a x+b \tag{1.10}
\end{array}
$$

for any $a, b \in \mathbb{R}$ (these identities indeed look funny at a first glance, nevertheless they are all correct in our setting).
A counterpart of our construction could be also discussed in terms of extension results and Dirichlet-to-Neumann operators. For instance, if one looks for the general harmonic function $U=U(x, y)$ in $\mathbb{R} \times(0,+\infty)$ with $U(x, 0)=$ $x^{2}$ and with at most quadratic growth at infinity, one has that $U(x, y)=x^{2}-y^{2}-a x y-b y$. In this sense, one is tempted (as usual) to identify $\sqrt{-\Delta} x^{2}$ with $-\partial_{y} U(x, 0)=a x+b$, for any $a, b \in \mathbb{R}$ which is indeed the last identity in (1.10).

As a matter of fact, an alternative approach to the one given in Definition 1.1 would consist in considering an extension problem (modulo polynomials), but we followed the procedure in Definition 1.1, since it can be applied to more general kernels.

Besides the intrinsic beauty of identities such as the ones in (1.10), in our framework, the usefulness of Definition 1.1 lies in its flexibility and possibility of applications to obtain sharp regularity estimates. In this sense, we give the following result, which can be seen as an optimal bound in Hölder spaces for the derivatives of the solution in terms of the seminorm of its (possibly divergent) fractional Laplacian and a weak control of the function at infinity, as given in (1.4).

To this aim, as usual, if $m \in \mathbb{N}, \theta \in(0,1)$ and $\gamma=m+\theta$, we use the notation

$$
\begin{aligned}
& \|f\|_{C^{m}\left(B_{1}\right)}:=\sum_{j=0}^{m}\left\|D^{j} f\right\|_{L^{\infty}\left(B_{1}\right)}, \\
& {[f]_{C^{\gamma}\left(B_{1}\right)}:=\sup _{x \neq y \in B_{1}} \frac{\left|D^{m} f(x)-D^{m} f(y)\right|}{|x-y|^{\theta}}} \\
& \text { and } \\
& \|f\|_{C^{\gamma}\left(B_{1}\right)}:=\|f\|_{C^{m}\left(B_{1}\right)}+[f]_{C^{\gamma}\left(B_{1}\right)} .
\end{aligned}
$$

It is also convenient to introduce the following $k$-convention on Hölder norms: we denote

$$
\begin{equation*}
[f]_{C^{\gamma}(\Omega ; k)}:=\inf [f-P]_{C^{\gamma}(\Omega)}, \tag{1.11}
\end{equation*}
$$

where the inf is taken over all the polynomials $P$ of degree at most $k-1$; of course, when $\gamma>k-1$, these polynomials disappear after derivation and we have that

$$
\begin{equation*}
[f]_{C^{\gamma}(\Omega ; k)}=[f]_{C^{\gamma}(\Omega)} \quad \text { if } \gamma>k-1 \tag{1.12}
\end{equation*}
$$

Notice that the setting in (1.11) is consistent with the multiplicity in (1.8), since, for any polynomial $Q$ of degree at most $k-1$, we have that

$$
[f+Q]_{C^{\gamma}(\Omega ; k)}=[f]_{C^{\gamma}(\Omega ; k)} .
$$

With this notation, the precise statement of our Schauder estimates ${ }^{4}$ is the following.
Theorem 1.3. [kth order Schauder estimates for divergent fractional Laplacians] Let $s \in(0,1), k \in \mathbb{N}$ and $u: \mathbb{R}^{n} \rightarrow \mathbb{R}$.

Assume that $u$ is continuous in $B_{1}$ and

$$
J_{u, k}:=\int_{B_{1 / 2}^{c}} \frac{|u(y)|}{|y|^{n+2 s+k}} d y<+\infty
$$

Suppose that

$$
(-\Delta)^{s} u \stackrel{k}{=} f \quad \text { in } B_{1}
$$

Then, for any $\gamma>0$ such that $\gamma \notin \mathbb{N}$ and $\gamma+2 s \notin \mathbb{N}$, and any $\ell \in \mathbb{N}$, it holds that

$$
\begin{equation*}
\|u\|_{C^{\gamma+2 s}\left(B_{1 / 2}\right)} \leqslant C\left([f]_{C^{\gamma}\left(B_{1} ; \ell\right)}+J_{u, \ell}\right) \tag{1.13}
\end{equation*}
$$

for some $C>0$, only depending on $n, s, \gamma, k$ and $\ell$.

We remark that, differently from the usual way of writing the Schauder estimates, the right hand side of (1.13) does not contain $\|u\|_{L^{\infty}\left(B_{1}\right)}$ nor $\|f\|_{C^{\gamma}\left(B_{1}\right)}$. That is, we can bound the whole norm $\|u\|_{C^{\gamma+2 s}\left(B_{1 / 2}\right)}$ with a contribution of $u$ coming from outside $B_{1 / 2}$, which is encoded in the term $J_{u, \ell}$, and the oscillation of $f$ in the seminorm $[f]_{C^{\gamma}\left(B_{1} ; \ell\right)}$. In this sense, Theorem 1.3 not only applies to divergent operators, but it is also a sharp version of the Schauder estimates for non-divergent operators (notice indeed that when $k=0$, the setting of Theorem 1.3 reduces to the one of the classical fractional Laplace equation, and in this case Theorem 1.3 provides already a sharp result, compare e.g. with Theorem 6 in [1], Theorem 1.1 in [18], Proposition 7.1 in [3] and the references therein).

A simple, but rather instructive consequence of Theorem 1.3 is a uniform bound on polynomial nonlinearities in which the nonlinearity does not appear explicitly on the right hand side (but it affects the size of $u$ near the boundary of the domain):

[^3]Corollary 1.4. Let $s \in(0,1), k \in \mathbb{N}$ and $u: \mathbb{R}^{n} \rightarrow \mathbb{R}$.
Assume that $u$ is continuous in $B_{1}$ and

$$
J_{u, k}:=\int_{B_{1 / 2}^{c}} \frac{|u(y)|}{|y|^{n+2 s+k}} d y<+\infty
$$

Suppose that $f$ is a polynomial of degree $d$ and

$$
(-\Delta)^{s} u \stackrel{k}{=} f \quad \text { in } B_{1}
$$

Then, for any $\gamma>0$ such that $\gamma \notin \mathbb{N}$ and $\gamma+2 s \notin \mathbb{N}$, it holds that

$$
\|u\|_{C^{\gamma+2 s}\left(B_{1 / 2}\right)} \leqslant C J_{u, d+1}
$$

for some $C>0$, only depending on $n, s, \gamma, k$ and $d$.

We observe that Corollary 1.4 is indeed an immediate consequence of Theorem 1.3, by taking $\ell:=d+1$ there. As a matter of fact, Corollary 1.4 is new, to the best of our knowledge, even in the case $k=0$ corresponding to the standard fractional Laplacian.

We also say that $(-\Delta)^{s} u \stackrel{k}{=} f$ in $\mathbb{R}^{n}$ if the setting of Definition 1.1 holds true in $B_{M}$ (instead of $B_{1}$ ), for all $M>0$. As a consequence of Theorem 1.3, we also obtain a rigidity and classification result for possibly divergent $s$-harmonic functions, as given here below.

Theorem 1.5. [Liouville Theorem for divergent fractional Laplacians] Let $s \in(0,1), k \in \mathbb{N}$ and $u: \mathbb{R}^{n} \rightarrow \mathbb{R}$.
Assume that $u$ is continuous and

$$
\int_{\mathbb{R}^{n}} \frac{|u(y)|}{1+|y|^{n+2 s+k}} d y<+\infty
$$

Let

$$
d(k, s):=\left\{\begin{array}{cl}
k+1 & \text { if } s \in\left(\frac{1}{2}, 1\right),  \tag{1.14}\\
k & \text { if } s \in\left(0, \frac{1}{2}\right] .
\end{array}\right.
$$

Then,

$$
(-\Delta)^{s} u \stackrel{k}{=} 0 \quad \text { in } \mathbb{R}^{n}
$$

if and only if $u$ is a polynomial of degree at most $d(k, s)$.

We recall that the study of rigidity properties for solutions of nonlocal equations and related Liouville results are a very active field of research, and this type of results has also important consequences on several aspects of the regularity theory, see e.g. $[6,11,13,14,18,20]$ and the references therein. As far as we know, Theorem 1.5 is the first result of this type which takes into account the case of possibly divergent operators.

We also point out that the notion given in Definition 1.1 is stable under limits, as given by the following result:
Theorem 1.6. [Stability of divergent fractional Laplacians] Let $s \in(0,1)$ and $k \in \mathbb{N}$. Let us consider sequences of functions $u_{m}: \mathbb{R}^{n} \rightarrow \mathbb{R}$ and $f_{m}: B_{1} \rightarrow \mathbb{R}$ such that $u_{m}$ and $f_{m}$ are continuous in $B_{1}$, and

$$
\begin{equation*}
(-\Delta)^{s} u_{m} \stackrel{k}{=} f_{m} \quad \text { in } B_{1} \tag{1.15}
\end{equation*}
$$

Assume that $u_{m} \rightarrow u$ in $L^{1}\left(B_{1}\right)$ and locally uniformly in $B_{1}$, and that $f_{m} \rightarrow f$ locally uniformly in $B_{1}$ as $m \rightarrow+\infty$, for some functions $u \in L^{1}\left(\mathbb{R}^{n}\right)$ and $f: B_{1} \rightarrow \mathbb{R}$.

Suppose also that

$$
\begin{equation*}
\sup _{m \in \mathbb{N}} \int_{\mathbb{R}^{n}} \frac{\left|u_{m}(y)\right|}{1+|y|^{n+2 s+k}} d y<+\infty \tag{1.16}
\end{equation*}
$$

and that $u_{m}$ converges to $u$ weakly in the following sense:

$$
\begin{equation*}
\lim _{m \rightarrow+\infty} \int_{\mathbb{R}^{n}} \frac{u_{m}(y) \varphi(y)}{1+|y|^{n+2 s+k}} d y=\int_{\mathbb{R}^{n}} \frac{u(y) \varphi(y)}{1+|y|^{n+2 s+k}} d y \tag{1.17}
\end{equation*}
$$

for any $\varphi \in L^{\infty}\left(\mathbb{R}^{n}\right)$.
Then, it holds that

$$
\begin{equation*}
(-\Delta)^{s} u \stackrel{k}{=} f \quad \text { in } B_{1} \tag{1.18}
\end{equation*}
$$

Theorem 1.6 is the counterpart, in our setting, of classical approximation and stability results in the fractional setting, see [5].

The rest of the paper is organized as follows. In Section 2, we recall some ancillary results on polynomials and we prove Lemma 1.2. In Section 3, we compute the fractional Laplacian of a cutoff function and we expand its possibly divergent behavior for a family of cutoffs, showing that this procedure is compatible with Definition 1.1 and we provide a series of consistency results between Definition 1.1 and the standard fractional Laplacian, when the two settings overlap.

Then, we provide the proof of Theorem 1.3 in Section 4. This in turn will allow us to prove Theorem 1.5 in Section 5. The proof of Theorem 1.6 is given in Section 6. The paper ends with some auxiliary appendices.

## 2 Some remarks on polynomials

Here we recall the following elementary, but useful, algebraic observations (the standard proofs, for the convenience of the reader, are given in Appendix B):

Lemma 2.1. Let $P^{(j)}$ be a sequence of polynomials of degree at most $d-1$. Assume that there exist a bounded, open set $U \subseteq \mathbb{R}^{n}$ and a function $F: U \rightarrow \mathbb{R}$ such that

$$
\begin{equation*}
\lim _{j \rightarrow+\infty} P^{(j)}(x)=F(x) \tag{2.1}
\end{equation*}
$$

for any $x \in U$. Then, $F$ is a polynomial of degree at most $d-1$ and the convergence in (2.1) holds in $C^{m}(U)$ for any $m \in \mathbb{N}$.

We also provide a variant of Lemma 2.1, which will be used in the proof of Theorem 1.6. For this, we introduce some notation: for any polynomial $P$, let $U \subseteq \mathbb{R}^{n}$ be a bounded, open set with smooth boundary and define

$$
\begin{equation*}
\|P\|_{\star}:=\sup _{\substack{\varphi \in C_{0}^{2}(U) \\\|\varphi\|_{C^{2}\left(\mathbb{R}^{n}\right)} \leqslant 1}} \int_{U} P(x) \varphi(x) d x . \tag{2.2}
\end{equation*}
$$

Then, we have the following convergence result:
Lemma 2.2. Let $P^{(j)}$ be a sequence of polynomials of degree at most $d-1$. Assume that $P^{(j)}$ is a Cauchy sequence in the norm $\|\cdot\|_{\star}$. Then, there exists a polynomial $P$ of degree at most $d-1$ such that $P^{(j)}$ converges to $P$ uniformly in $U$ as $j \rightarrow+\infty$.

With Lemma 2.1, we can give the proof of Lemma 1.2, by arguing as follows.

Proof of Lemma 1.2. From Definition 1.1, we know that there exist two families of polynomials $P_{R}$ and $\tilde{P}_{R}$, with degree at most $k-1$, such that, for any $x \in B_{1}$,

$$
\lim _{R \rightarrow+\infty}(-\Delta)^{s}\left(\chi_{R} u\right)(x)-P_{R}(x)=f(x)
$$

and

$$
\lim _{R \rightarrow+\infty}(-\Delta)^{s}\left(\chi_{R} u\right)(x)-\tilde{P}_{R}(x)=\tilde{f}(x)
$$

Accordingly,

$$
f(x)-\tilde{f}(x)=\lim _{R \rightarrow+\infty} P_{R}(x)-\tilde{P}_{R}(x)
$$

Since $P_{R}-\tilde{P}_{R}$ is a polynomial of degree at most $k-1$, we deduce from Lemma 2.1 that $f-\tilde{f}$ is also a polynomial of degree at most $k-1$, as desired.

We also give the following rigidity result (for general unique continuation principles in the nonlocal setting, see also [12]).

Lemma 2.3. Let $R>r>0$. Let $P$ be a polynomial and $u$ be a viscosity solution of $(-\Delta)^{s} u=P$ in $B_{R}$. Assume that $u=0$ in $B_{r}^{c}$. Then $u$ vanishes identically.

Proof. We argue by induction on the degree $d$ of $P$. If $d=-1$, then $P$ vanishes identically and the claim follows from the maximum principle.
Suppose now the claim true for all polynomials of degree $d-1$. Let $r^{\prime}, R^{\prime} \in(r, R)$ with $R^{\prime}>r^{\prime}$. For $\theta \in \mathbb{R}^{n}$, with $|\theta|$ sufficiently small, we see that the function $u^{(\theta)}(x):=u(x+\theta)-u(x)$ satisfies $(-\Delta)^{s} u^{(\theta)}=P^{(\theta)}$ in $B_{R^{\prime}}$, with $P^{(\theta)}(x):=P(x+\theta)-P(x)$, and $u^{(\theta)}=0$ outside $B_{r^{\prime}}$. We observe that $P^{(\theta)}$ is a polynomial of degree at most $d-1$, hence, by inductive hypothesis, it follows that $u^{(\theta)}$ is identically zero, and therefore $u$ is constant.
Since $u$ vanishes outside $B_{r}$, it thus follows that it vanishes everywhere, as desired.

## 3 The role of the cutoff for divergent fractional Laplacians

In this section, we show how a cutoff affects the computation of the fractional Laplacian for a function with prescribed growth at infinity. We will see that the identities obtained are compatible with the setting in Definition 1.1, namely the growth at infinity, combined with a cutoff, produces a family of polynomials of a fixed degree.
Theorem 3.1. Let $s \in(0,1), k \in \mathbb{N}$ and $u: \mathbb{R}^{n} \rightarrow \mathbb{R}$.
Assume that $u \in C_{\mathrm{loc}}^{\alpha}\left(B_{1}\right)$ for some $\alpha>2 s$ and

$$
\begin{equation*}
\int_{\mathbb{R}^{n}} \frac{|u(y)|}{1+|y|^{n+2 s+k}} d y<+\infty \tag{3.1}
\end{equation*}
$$

Let $\tau: \mathbb{R}^{n} \rightarrow \mathbb{R}$ be compactly supported and with $\tau=1$ in $B_{2}$. Then, there exist a function $f_{u, \tau}: \mathbb{R}^{n} \rightarrow \mathbb{R}$, and a polynomial $P_{u, \tau}$, which has degree at most $k-1$, such that

$$
\begin{equation*}
(-\Delta)^{s}(\tau u)=P_{u, \tau}+f_{u, \tau} \tag{3.2}
\end{equation*}
$$

in $B_{1}$.
In addition, $f_{u, \tau}$ can be written in the following form: there exists $\psi: B_{1} \times B_{2}^{c} \rightarrow \mathbb{R}$, with

$$
\begin{equation*}
\sup _{x \in B_{1}, y \in B_{2}^{c}}\left|\partial_{x}^{\gamma} \psi(x, y)\right|<+\infty \tag{3.3}
\end{equation*}
$$

for any $\gamma \in \mathbb{N}^{n}$, such that

$$
\begin{equation*}
f_{u, \tau}=f_{1, u}+f_{2, u}+f_{u, \tau}^{\star} \tag{3.4}
\end{equation*}
$$

where

$$
\begin{align*}
f_{1, u}(x) & :=\int_{B_{2}} \frac{u(x)-u(y)}{|x-y|^{n+2 s}} d y, \\
f_{2, u}(x) & :=\int_{B_{2}^{c}} \frac{u(x)}{|x-y|^{n+2 s}} d y  \tag{3.5}\\
\text { and } \quad f_{u, \tau}^{\star}(x) & :=\int_{B_{2}^{c}} \frac{\tau(y) u(y) \psi(x, y)}{|y|^{n+2 s+k}} d y .
\end{align*}
$$

Proof. We stress that the integral defining $f_{u, \tau}^{\star}$ is finite, thanks to (3.1).
Now we compute, for any $x \in B_{1}$,

$$
\begin{align*}
(-\Delta)^{s}(\tau u)(x) & =\int_{B_{2}} \frac{u(x)-u(y)}{|x-y|^{n+2 s}} d y+\int_{B_{2}^{c}} \frac{u(x)-(\tau u)(y)}{|x-y|^{n+2 s}} d y \\
& =f_{1, u}(x)+f_{2, u}(x)-\int_{B_{2}^{c}} \frac{(\tau u)(y)}{|x-y|^{n+2 s}} d y  \tag{3.6}\\
& =f_{1, u}(x)+f_{2, u}(x)-\int_{B_{2}^{c}} \frac{(\tau u)(y)}{|y|^{n+2 s}\left|x_{y}-y_{y}\right|^{n+2 s}} d y
\end{align*}
$$

where the short notation $x_{y}:=x /|y|$ and $y_{y}:=y /|y|$ has been exploited.
Now, for any $e \in \partial B_{1}$ and any $z \in B_{1 / 2}$, we set

$$
g_{e}(z):=|z-e|^{-n-2 s} .
$$

We consider a Taylor expansion of $g_{e}$ in the vicinity of the origin, and we write

$$
\begin{equation*}
g_{e}(z)=\sum_{|\alpha| \leqslant k-1} c_{\alpha, e} z^{\alpha}+\sum_{|\alpha|=k} \varrho_{\alpha}(e, z) z^{\alpha} \tag{3.7}
\end{equation*}
$$

with

$$
\begin{equation*}
\sup _{\substack{|\alpha| \leqslant k-1 \\ e \in \partial B_{1}}} c_{\alpha, e}+\sup _{\substack{| | \mid=k \\ e \in \partial B_{1} \\ z \in B_{1 / 2}}}\left|\partial_{z}^{\gamma} \varrho_{\alpha}(e, z)\right| \leqslant C_{\gamma}, \tag{3.8}
\end{equation*}
$$

for some $C_{\gamma}>0$, which depends only on $n, s$ and $\gamma \in \mathbb{N}^{n}$.
As a consequence, we have

$$
\begin{align*}
\frac{(\tau u)(y)}{|y|^{n+2 s}\left|x_{y}-y_{y}\right|^{n+2 s}} & =\frac{(\tau u)(y)}{|y|^{n+2 s}} g_{y_{y}}\left(x_{y}\right) \\
& =\frac{(\tau u)(y)}{|y|^{n+2 s}}\left[\sum_{|\alpha| \leqslant k-1} c_{\alpha, y_{y}} x_{y}^{\alpha}+\sum_{|\alpha|=k} \varrho_{\alpha}\left(y_{y}, x_{y}\right) x_{y}^{\alpha}\right]  \tag{3.9}\\
& =\frac{(\tau u)(y)}{|y|^{n+2 s}}\left[\sum_{|\alpha| \leqslant k-1} \frac{c_{\alpha, y_{y}} x^{\alpha}}{|y|^{|\alpha|}}+\sum_{|\alpha|=k} \frac{\varrho_{\alpha}\left(y_{y}, x_{y}\right) x^{\alpha}}{|y|^{k}}\right] .
\end{align*}
$$

Thus, we set

$$
\kappa_{\tau, \alpha}:=-\int_{B_{2}^{c}} \frac{(\tau u)(y)}{|y|^{n+2 s+|\alpha|}} c_{\alpha, y_{y}} d y
$$

and we consider the polynomial of degree at most $k-1$

$$
P_{u, \tau}(x):=\sum_{|\alpha| \leqslant k-1} \kappa_{\tau, \alpha} x^{\alpha} .
$$

We also define

$$
\begin{equation*}
\psi(x, y):=-\sum_{|\alpha|=k} \varrho_{\alpha}\left(y_{y}, x_{y}\right) x^{\alpha} \tag{3.10}
\end{equation*}
$$

Notice that (3.3) follows from (3.8). Also, with this notation, we deduce from (3.9) that

$$
\int_{B_{2}^{c}} \frac{(\tau u)(y)}{|y|^{n+2 s}\left|x_{y}-y_{y}\right|^{n+2 s}}=-P_{u, \tau}(x)-f_{u, \tau}^{\star}(x) .
$$

This and (3.6) imply (3.2).

Then, we have the following consequence of Theorem 3.1:
Corollary 3.2. Let $s \in(0,1), k \in \mathbb{N}$ and $u: \mathbb{R}^{n} \rightarrow \mathbb{R}$.
Assume that $u \in C_{\mathrm{loc}}^{\alpha}\left(B_{1}\right)$ for some $\alpha>2 s$ and

$$
\begin{equation*}
\int_{\mathbb{R}^{n}} \frac{|u(y)|}{1+|y|^{n+2 s+k}} d y<+\infty \tag{3.11}
\end{equation*}
$$

Let $\tau_{R}: \mathbb{R}^{n} \rightarrow[0,1]$ be supported in $B_{R}$ and such that

$$
\begin{equation*}
\lim _{R \rightarrow+\infty} \tau_{R}=1 \quad \text { a.e. in } \mathbb{R}^{n} . \tag{3.12}
\end{equation*}
$$

Then, there exist a function $f_{u}: \mathbb{R}^{n} \rightarrow \mathbb{R}$, and a family of polynomials $P_{u, \tau_{R}}$, which have degree at most $k-1$, such that, for any $x \in B_{1}$, it holds that

$$
\begin{equation*}
\lim _{R \rightarrow+\infty}\left[(-\Delta)^{s}\left(\tau_{R} u\right)(x)-P_{u, \tau_{R}}(x)\right]=f_{u}(x) \tag{3.13}
\end{equation*}
$$

More precisely, we have that

$$
\begin{equation*}
f_{u}=f_{1, u}+f_{2, u}+f_{3, u} \tag{3.14}
\end{equation*}
$$

where $f_{1, u}$ and $f_{2, u}$ are as in (3.5) and

$$
\begin{equation*}
f_{3, u}(x):=\int_{B_{2}^{c}} \frac{u(y) \psi(x, y)}{|y|^{n+2 s+k}} d y \tag{3.15}
\end{equation*}
$$

with $\psi$ satisfying (3.3).

Proof. The idea of the proof is to use Theorem 3.1 with $\tau:=\tau_{R}$ for any fixed $R$, and then send $R \rightarrow+\infty$. Indeed, by (3.3), for any $x \in B_{1}$ and $y \in B_{2}^{c}$,

$$
\frac{\left(\tau_{R} u\right)(y) \psi(x, y)}{|y|^{n+2 s+k}} \leqslant \frac{C|u(y)|}{|y|^{n+2 s+k}}
$$

for some $C>0$, and the latter function of $y$ lies in $L^{1}\left(B_{2}^{c}\right)$, thanks to (3.11).
Consequently, by (3.12) and the Dominated Convergence Theorem,

$$
\lim _{R \rightarrow+\infty} f_{u, \tau_{R}}^{\star}(x)=\lim _{R \rightarrow+\infty} \int_{B_{2}^{c}} \frac{\left(\tau_{R} u\right)(y) \psi(x, y)}{|y|^{n+2 s+k}} d y=\int_{B_{2}^{c}} \frac{u(y) \psi(x, y)}{|y|^{n+2 s+k}} d y=f_{3, u}(x)
$$

Then, (3.13) follows by taking the limit in (3.2).

Remark 3.3. We stress that, in view of (3.7) and (3.10), the function $\psi$ does not depend on $u$ and thus the quantity in (3.3) is universal.

Remark 3.4. It is interesting to notice that, from (3.4) and (3.14),

$$
f_{u, \tau}=f_{u}-f_{3, u}+f_{u, \tau}^{\star}
$$

Remark 3.5. From Definition 1.1 and Corollary 3.2 (used here with $\tau_{R}:=\chi_{R}$, in the notation of (1.3)), we can write $(-\Delta)^{s} u \stackrel{k}{=} f_{u}$ in $B_{1}$, for any $u \in C_{\mathrm{loc}}^{\alpha}\left(B_{1}\right)$ (for some $\alpha>2 s$ ) that satisfies the weak growth condition in (3.11).

Remark 3.6. From Corollary 3.2 and Remark 3.5, it also follows that, for any $u \in C_{\text {loc }}^{\alpha}\left(B_{1}\right)$ (for some $\alpha>2 s$ ), the family of cutoffs $\chi_{R}$ used in Definition 1.1 can be replaced by another family of cutoffs $\tau_{R}$, without changing the explicit expression of $f_{u}$.

Another useful consequence of Theorem 3.1 is that the pointwise convergence of $f_{R}$ in Definition 1.1 can be strengthen according to the following result:

Corollary 3.7. Let $k \in \mathbb{N}, u$ and $f_{R}$ be as in Definition 1.1. Then, for any $m \geqslant 0$, if $R^{\prime}>R$ we have that

$$
\begin{equation*}
\inf \left\|D^{m}\left(f_{R^{\prime}}-f_{R}-P\right)\right\|_{L^{\infty}\left(B_{1}\right)} \leqslant C \int_{B_{R}^{c}} \frac{|u(y)|}{|y|^{n+2 s+k}} d y \tag{3.16}
\end{equation*}
$$

with $C>0$ only depending on $n$, $s$ and $m$, where the inf is taken over all the polynomials $P$ with degree at most $k-1$.

Proof. We define $v:=\left(1-\chi_{2}\right) u$. Obviously, $v=0$ in $B_{2}$ and $|v| \leqslant|u|$, so

$$
\begin{equation*}
v \in C_{\mathrm{loc}}^{\alpha}\left(B_{1}\right) \text { for some } \alpha>2 s \text { and } J_{v, k} \leqslant J_{u, k}<+\infty \tag{3.17}
\end{equation*}
$$

Moreover, if $R>2$,

$$
\left(\chi_{R}-\chi_{2}\right) u=\left(\chi_{R}-\chi_{2}\right) v
$$

Hence, from (1.5),

$$
\begin{equation*}
(-\Delta)^{s}\left(\left(\chi_{R}-\chi_{2}\right) v\right)=(-\Delta)^{s}\left(\left(\chi_{R}-\chi_{2}\right) u\right)=f_{R}-f_{2}+P_{R}-P_{2}=f_{R}-f_{2}+\tilde{P}_{R} \tag{3.18}
\end{equation*}
$$

where $\tilde{P}_{R}:=P_{R}-P_{2}$ is a polynomial of degree at most $k-1$, and the equation holds in $B_{1}$ in the sense of viscosity.

On the other hand, (3.17) allows us to use Theorem 3.1 on the function $v$ (with $\tau:=\chi_{R}$ and $\tau:=\chi_{2}$ ). We thus obtain that

$$
\begin{aligned}
& (-\Delta)^{s}\left(\left(\chi_{R}-\chi_{2}\right) v\right)=P_{v, \chi_{R}}-P_{v, \chi_{2}}+f_{v, \chi_{R}}-f_{v, \chi_{2}} \\
& \quad=\bar{P}_{v, \chi_{R}}+\left(f_{1, v}+f_{2, v}+f_{v, \chi_{R}}^{\star}\right)-\left(f_{1, v}+f_{2, v}+f_{v, \chi_{2}}^{\star}\right)=\bar{P}_{v, \chi_{R}}+f_{v, \chi_{R}}^{\star}-f_{v, \chi_{2}}^{\star} \\
& \quad=\bar{P}_{v, \chi_{R}}+\int_{B_{R} \backslash B_{2}} \frac{u(y) \psi(x, y)}{|y|^{n+2 s+k}} d y
\end{aligned}
$$

in $B_{1}$ in the viscosity sense, where $\bar{P}_{v, \chi_{R}}:=P_{v, \chi_{R}}-P_{v, \chi_{2}}$ is a polynomial of degree at most $k-1$.
Comparing this identity with (3.18), we obtain that in $B_{1}$

$$
f_{R}=f_{2}+P_{R}^{\star}+\int_{B_{R} \backslash B_{2}} \frac{u(y) \psi(x, y)}{|y|^{n+2 s+k}} d y
$$

where $P_{R}^{\star}:=\bar{P}_{v, \chi_{R}}-\tilde{P}_{R}$ is a polynomial of degree at most $k-1$.
Therefore, for any $m \geqslant 0$ and any large $R^{\prime}>R$,

$$
\begin{equation*}
\left\|D^{m}\left(f_{R^{\prime}}-P_{R^{\prime}}^{\star}-f_{R}+P_{R}^{\star}\right)\right\|_{L^{\infty}\left(B_{1}\right)}=\left\|D^{m} \Psi_{R^{\prime}, R}\right\|_{L^{\infty}\left(B_{1}\right)} \tag{3.19}
\end{equation*}
$$

where

$$
\Psi_{R^{\prime}, R}(x):=\int_{B_{R^{\prime}} \backslash B_{R}} \frac{u(y) \psi(x, y)}{|y|^{n+2 s+k}} d y
$$

From (1.4) and (3.3), we know that

$$
\left\|\Psi_{R^{\prime}, R}\right\|_{C^{m}\left(B_{1}\right)} \leqslant C \int_{B_{R^{\prime}} \backslash B_{R}} \frac{|u(y)|}{|y|^{n+2 s+k}} d y \leqslant C \int_{B_{R}^{c}} \frac{|u(y)|}{|y|^{n+2 s+k}} d y
$$

for some $C>0$ possibly depending on $m$. This and (3.19) imply that

$$
\begin{equation*}
\left\|D^{m}\left(f_{R^{\prime}}-P_{R^{\prime}}^{\star}-f_{R}+P_{R}^{\star}\right)\right\|_{L^{\infty}\left(B_{1}\right)} \leqslant C \int_{B_{R}^{c}} \frac{|u(y)|}{|y|^{n+2 s+k}} d y \tag{3.20}
\end{equation*}
$$

which gives (3.16).

As a consequence of Corollary 3.7, we have the following consistency result when $k=0$ :
Corollary 3.8. Let $u: \mathbb{R}^{n} \rightarrow \mathbb{R}$ be bounded and continuous in $B_{1}$ and such that

$$
\begin{equation*}
\int_{\mathbb{R}^{n}} \frac{|u(y)|}{1+|y|^{n+2 s}} d y<+\infty \tag{3.21}
\end{equation*}
$$

Let $f$ be bounded and continuous in $B_{1}$.
Then

$$
(-\Delta)^{s} u=f \text { in } B_{1} \text { in the viscosity sense }
$$

is equivalent to

$$
(-\Delta)^{s} u \stackrel{0}{=} f \text { in } B_{1} \text { in the sense of Definition 1.1. }
$$

Proof. We take cutoffs as in (1.3). Suppose first that $(-\Delta)^{s} u=f$ in $B_{1}$ in the viscosity sense. Then, for $R>10$,

$$
\begin{equation*}
(-\Delta)^{s}\left(\chi_{R / 2} u\right)=f+\int_{\mathbb{R}^{n}} \frac{\left(1-\chi_{R / 2}(y)\right) u(y)}{|x-y|^{n+2 s}} d y \tag{3.22}
\end{equation*}
$$

in $B_{1}$ in the viscosity sense. Now, we set

$$
w:=\left(\chi_{R}-\chi_{R / 2}\right) u
$$

Notice that $w$ vanishes outside $B_{R}$, hence

$$
\chi_{R} w=w
$$

Also, $w=0$ in $B_{2}$, so we can exploit Theorem 3.1 to $w$ with $k=0$ and get that, for any $x \in B_{1}$,

$$
\begin{align*}
& (-\Delta)^{s}\left(\left(\chi_{R}-\chi_{R / 2}\right) u\right)(x)=(-\Delta)^{s} w(x)=(-\Delta)^{s}\left(\chi_{R} w\right)(x) \\
& \quad=f_{1, w}(x)+f_{2, w}(x)+f_{w, \chi_{R}}^{\star}(x)=\int_{B_{R} \backslash B_{2}} \frac{w(y) \psi(x, y)}{|y|^{n+2 s}} d y=\int_{B_{R} \backslash B_{R / 2}} \frac{u(y) \psi(x, y)}{|y|^{n+2 s}} d y \tag{3.23}
\end{align*}
$$

Since $w$ is smooth in $B_{1}$, this identity also holds in the viscosity sense. Hence, from (3.22) and (3.23), we find that

$$
\begin{aligned}
(-\Delta)^{s}\left(\chi_{R} u\right) & =(-\Delta)^{s}\left(\left(\chi_{R}-\chi_{R / 2}\right) u\right)+(-\Delta)^{s}\left(\chi_{R / 2} u\right) \\
& =\int_{B_{R} \backslash B_{R / 2}} \frac{u(y) \psi(x, y)}{|y|^{n+2 s}} d y+f+\int_{\mathbb{R}^{n}} \frac{\left(1-\chi_{R / 2}(y)\right) u(y)}{|x-y|^{n+2 s}} d y \\
& =: f_{R}
\end{aligned}
$$

in $B_{1}$, in the sense of viscosity. We remark that $f_{R} \rightarrow f$ in $B_{1}$ as $R \rightarrow+\infty$, thanks to (3.3) and (3.21). Hence, we are in the setting of Definition 1.1 (here with $k=0$ and $P_{R}:=0$ ), and so we conclude that $(-\Delta)^{s} u \xlongequal{0} f$ in $B_{1}$, as desired.
Viceversa, we now suppose that $(-\Delta)^{s} u \stackrel{0}{=} f$ in $B_{1}$. From Definition 1.1 and the fact that $k=0$, we have that $P_{R}$ is always zero, and so we can write that $(-\Delta)^{s}\left(\chi_{R} u\right)=f_{R}$ in $B_{1}$ in the sense of viscosity, with $f_{R} \rightarrow f$ in $B_{1}$ as $R \rightarrow+\infty$.

We observe that $\chi_{R} u$ approaches $u$ locally uniformly in $\mathbb{R}^{n}$. Also, we can use here Corollary 3.7: since in this case $k=0$, we have that (3.16) reduces to

$$
\left\|D^{m}\left(f_{R^{\prime}}-f_{R}\right)\right\|_{L^{\infty}\left(B_{1}\right)} \leqslant C \int_{B_{R}^{c}} \frac{|u(y)|}{|y|^{n+2 s}} d y
$$

for any $m \geqslant 0$. In particular, taking $m=0$ and sending $R^{\prime} \rightarrow+\infty$, we obtain that, for any $x \in B_{1}$,

$$
\left|f(x)-f_{R}(x)\right|=\lim _{R^{\prime} \rightarrow+\infty}\left|f_{R^{\prime}}(x)-f_{R}(x)\right| \leqslant \lim _{R^{\prime} \rightarrow+\infty}\left\|f_{R^{\prime}}-f_{R}\right\|_{L^{\infty}\left(B_{1}\right)} \leqslant C \int_{B_{R}^{c}} \frac{|u(y)|}{|y|^{n+2 s}} d y
$$

As a consequence, we have that $f_{R}$ converges to $f$ uniformly in $B_{1}$ as $R \rightarrow+\infty$.
From this, we can exploit Lemma 5 in [5] and conclude that $(-\Delta)^{s} u=f$ in the viscosity sense in $B_{1}$, as desired.

Another consistency result is that if $(-\Delta)^{s} u \stackrel{k}{=} f$ and $u$ has growth at infinity better than the one required by Definition 1.1, then it satisfies the same equation "in a better class, up to the invariance allowed by Definition 1.1". The precise result is as follows:

Lemma 3.9. Let the setting of Definition 1.1 hold true and let $(-\Delta)^{s} u \stackrel{k}{=} f$ in $B_{1}$. Suppose that

$$
\begin{equation*}
\int_{\mathbb{R}^{n}} \frac{|u(y)|}{1+|y|^{n+2 s+j}} d y<+\infty \tag{3.24}
\end{equation*}
$$

for some $j \in \mathbb{N}$, with $j \leqslant k$. Then, there exist a function $\bar{f}$ and a polynomial $P$ of degree at most $k-1$, such that $\bar{f}=f+P$ and $(-\Delta)^{s} u \stackrel{j}{=} \bar{f}$ in $B_{1}$.

Proof. Let $v:=\left(1-\chi_{4}\right) u$ and $w:=\chi_{4} u$. Of course, $v$ is zero (and thus smooth) in $B_{1}$ and, from (3.24), we have that

$$
\int_{\mathbb{R}^{n}} \frac{|v(y)|}{1+|y|^{n+2 s+j}} d y<+\infty
$$

So, we can apply Remark 3.5 with $k$ replaced with $j$ and find that

$$
(-\Delta)^{s} v \stackrel{j}{=} f_{v}=\int_{B_{4}^{c}} \frac{u(y) \psi(x, y)}{|y|^{n+2 s+j}} d y
$$

thanks to (3.14). By definition, this means that

$$
\begin{equation*}
(-\Delta)^{s}\left(\chi_{R} v\right)=\int_{B_{4}^{c}} \frac{u(y) \psi(x, y)}{|y|^{n+2 s+j}} d y+\varphi_{R}+Q_{R} \tag{3.25}
\end{equation*}
$$

in the viscosity sense in $B_{1}$, for some $\varphi_{R}$ such that $\varphi_{R} \rightarrow 0$ in $B_{1}$ as $R \rightarrow+\infty$ and a polynomial $Q_{R}$ of degree at most $j-1$.

On the other hand, from Definition 1.1, we have that

$$
\begin{equation*}
(-\Delta)^{s}\left(\chi_{R} u\right)=f+\phi_{R}+P_{R} \tag{3.26}
\end{equation*}
$$

in the viscosity sense in $B_{1}$, for some $\phi_{R}$ such that $\phi_{R} \rightarrow 0$ in $B_{1}$ as $R \rightarrow+\infty$ and a polynomial $P_{R}$ of degree less than or equal to $k-1$.

By subtracting (3.25) to (3.26), we obtain
$f+\phi_{R}+P_{R}-\int_{B_{4}^{c}} \frac{u(y) \psi(x, y)}{|y|^{n+2 s+j}} d y-\varphi_{R}-Q_{R}=(-\Delta)^{s}\left(\chi_{R}(u-v)\right)=(-\Delta)^{s}\left(\chi_{R} w\right)=(-\Delta)^{s}\left(\chi_{4} w\right)$
in the viscosity sense in $B_{1}$. This says that the following limit exists:

$$
\lim _{R \rightarrow+\infty}\left(\phi_{R}+P_{R}-\varphi_{R}-Q_{R}\right)
$$

which in turn boils down to the existence of the limit

$$
\lim _{R \rightarrow+\infty}\left(P_{R}-Q_{R}\right)
$$

As a consequence, from Lemma 2.1, we know that

$$
\lim _{R \rightarrow+\infty}\left(P_{R}-Q_{R}\right)=P,
$$

for some polynomial $P$ of degree at most $k-1$. That is, we take $\bar{f}:=f+P$ and $\Phi_{R}:=\phi_{R}+P_{R}-Q_{R}-P$, and we see that $\Phi_{R} \rightarrow 0$ as $R \rightarrow+\infty$ and, from (3.26),

$$
(-\Delta)^{s}\left(\chi_{R} u\right)=\bar{f}+\Phi_{R}+Q_{R}
$$

in $B_{1}$, in the viscosity sense. Since the degree of $Q_{R}$ is at most $j-1$, this says that $(-\Delta)^{s} u \stackrel{j}{=} \bar{f}$ in $B_{1}$, as desired.

For us, Lemma 3.9 is useful since it allows to take fixed cutoffs in Definition 1.1 and reduce to the case of the standard fractional Laplacian, as formalized by the following result:

Corollary 3.10. Let the setting of Definition 1.1 hold true and let $(-\Delta)^{s} u \stackrel{k}{=} f$ in $B_{1}$. Let also $\rho \geqslant 1$ and $w:=\chi_{\rho} u$. Then, there exists a polynomial $P$ of degree at most $k-1$ such that

$$
\begin{equation*}
(-\Delta)^{s} w=\bar{f}+\int_{B_{2} \cap B_{\rho}^{c}} \frac{u(y)}{|x-y|^{n+2 s}} d y-\int_{B_{2}^{c} \cap B_{\rho}^{c}} \frac{u(y) \psi(x, y)}{|y|^{n+2 s+k}} d y \tag{3.27}
\end{equation*}
$$

in $B_{1}$ in the sense of viscosity, where $\bar{f}:=f+P$.

Proof. From Definition 1.1, we can write, in $B_{1}$ and in the viscosity sense,

$$
(-\Delta)^{s}\left(\chi_{R} u\right)=f+\phi_{R}+P_{R}
$$

where $P_{R}$ is a polynomial with degree at most $k-1$ and $\phi_{R} \rightarrow 0$ as $R \rightarrow+\infty$. We also set $v:=\left(1-\chi_{\rho}\right) u$. Notice that $v=0$ in $B_{1}$. We can apply Remark 3.5 to $v$ and find that, in $B_{1}$,

$$
\begin{aligned}
(-\Delta)^{s} v & \stackrel{k}{=} f_{v}=-\int_{B_{2}} \frac{v(y)}{|x-y|^{n+2 s}} d y+\int_{B_{2}^{c}} \frac{v(y) \psi(x, y)}{|y|^{n+2 s+k}} d y \\
& =-\int_{B_{2} \backslash B_{\rho}} \frac{u(y)}{|x-y|^{n+2 s}} d y+\int_{B_{2}^{c} \cap B_{\rho}^{c}} \frac{u(y) \psi(x, y)}{|y|^{n+2 s+k}} d y
\end{aligned}
$$

where we used the obvious notation $B_{2} \backslash B_{\rho}=\varnothing$ if $\rho \geqslant 2$.
That is, in $B_{1}$ and in the viscosity sense,

$$
(-\Delta)^{s}\left(\chi_{R} v\right)=-\int_{B_{2} \backslash B_{\rho}} \frac{u(y)}{|x-y|^{n+2 s}} d y+\int_{B_{2}^{c} \cap B_{\rho}^{c}} \frac{u(y) \psi(x, y)}{|y|^{n+2 s+k}} d y+\tilde{\phi}_{R}+\tilde{P}_{R}
$$

where $\tilde{P}_{R}$ is a polynomial with degree at most $k-1$ and $\tilde{\phi}_{R} \rightarrow 0$ as $R \rightarrow+\infty$. Consequently,

$$
\begin{aligned}
(-\Delta)^{s}\left(\chi_{R} w\right) & =(-\Delta)^{s}\left(\chi_{R} u\right)-(-\Delta)^{s}\left(\chi_{R} v\right) \\
& =f+\int_{B_{2} \backslash B_{\rho}} \frac{u(y)}{|x-y|^{n+2 s}} d y-\int_{B_{2}^{c} \cap B_{\rho}^{c}} \frac{u(y) \psi(x, y)}{|y|^{n+2 s+k}} d y+\phi_{R}-\tilde{\phi}_{R}+P_{R}-\tilde{P}_{R}
\end{aligned}
$$

which means that, in $B_{1}$,

$$
\begin{equation*}
(-\Delta)^{s} w \stackrel{k}{=} f+\int_{B_{2} \backslash B_{\rho}} \frac{u(y)}{|x-y|^{n+2 s}} d y-\int_{B_{2}^{c} \cap B_{\rho}^{c}} \frac{u(y) \psi(x, y)}{|y|^{n+2 s+k}} d y \tag{3.28}
\end{equation*}
$$

We remark that $w$ is a compactly supported function, hence (3.24) holds true for $j=0$. Thus, from (3.28) and Lemma 3.9, we obtain that

$$
(-\Delta)^{s} w \stackrel{0}{=} f+\int_{B_{2} \backslash B_{\rho}} \frac{u(y)}{|x-y|^{n+2 s}} d y-\int_{B_{2}^{c} \cap B_{\rho}^{c}} \frac{u(y) \psi(x, y)}{|y|^{n+2 s+k}} d y+P
$$

in $B_{1}$, where $P$ is a polynomial of degree at most $k-1$. This and Corollary 3.8 imply (3.27), as desired.

It is interesting to point out that, in the setting of Definition 1.1 , the functions $f_{R}$ and $f$ are not necessarily smooth, hence one cannot deduce from Corollary 3.7 that " $f_{R}$ converges to $f$ in $C^{m}\left(B_{1}\right)$ ". Also, in principle, one cannot get rid of the additional polynomials in Corollary 3.7, since they come from the polynomial invariance of Definition 1.1.

In spite of this, it is possible to give a sharper version of Corollary 3.7, by introducing a notion of "optimal representative" for the functions $f_{R}$ in Definition 1.1, which, in principle, are only "well defined up to polynomials of degree $k-1$ ". This will be accomplished by looking at "projection over the orthogonal space to polynomials". Namely, for any $g \in L^{2}\left(B_{1}\right)$ we look at the minimum of $\|g+P\|_{L^{2}\left(B_{1}\right)}$ among all the polynomials $P$ of degree at most $k-1$. We remark that such minimum exists, since the space of polynomials is finite dimensional, and it is unique, due to the strict convexity of the norm, so we define the minimizing polynomial as $P_{g}^{\sharp}$.
Then we set

$$
\begin{equation*}
g^{\sharp}:=g+P_{g}^{\sharp} . \tag{3.29}
\end{equation*}
$$

In this setting, we have:

Lemma 3.11. Let the setting of Definition 1.1 hold true. Then

$$
\begin{equation*}
\lim _{R \rightarrow+\infty} f_{R}^{\sharp}=f^{\sharp} \tag{3.30}
\end{equation*}
$$

a.e. in $B_{1}$. Also,

$$
\begin{equation*}
f^{\sharp}-f \text { is a polynomial of degree at most } k-1 \text {. } \tag{3.31}
\end{equation*}
$$

Furthermore, for any $m \geqslant 0$, we have that

$$
\begin{equation*}
\left\|f^{\sharp}-f_{R}^{\sharp}\right\|_{C^{m}\left(B_{1}\right)} \leqslant C \int_{B_{R}^{c}} \frac{|u(y)|}{|y|^{n+2 s+k}} d y, \tag{3.32}
\end{equation*}
$$

with $C>0$ only depending on $n, s$ and $m$.

Proof. We set

$$
\nu_{R}:=\int_{B_{R}^{c}} \frac{|u(y)|}{|y|^{n+2 s+k}} d y
$$

We claim that

$$
\begin{equation*}
\left\|f_{R}^{\sharp}-f^{\sharp}\right\|_{L^{2}\left(B_{1}\right)} \leqslant C \nu_{R} . \tag{3.33}
\end{equation*}
$$

For this, we observe that, for any function $g$ and any polynomial $P$ with degree at most $k-1$, we have that

$$
\begin{equation*}
(g+P)^{\sharp}=g^{\sharp} . \tag{3.34}
\end{equation*}
$$

Also, from the minimizing property of $P_{g}^{\sharp}$ we see that $g^{\sharp}$ is orthogonal in $L^{2}\left(B_{1}\right)$ to all the polynomials of degree at most $k-1$ and therefore, for any functions $g$ and $h$, we have that

$$
\begin{align*}
\| g- & h\left\|_{L^{2}\left(B_{1}\right)}^{2}=\right\|\left(g^{\sharp}-h^{\sharp}\right)-\left(P_{g}^{\sharp}-P_{h}^{\sharp}\right) \|_{L^{2}\left(B_{1}\right)}^{2}  \tag{3.35}\\
& =\left\|g^{\sharp}-h^{\sharp}\right\|_{L^{2}\left(B_{1}\right)}^{2}+\left\|P_{g}^{\sharp}-P_{h}^{\sharp}\right\|_{L^{2}\left(B_{1}\right)}^{2} \geqslant\left\|g^{\sharp}-h^{\sharp}\right\|_{L^{2}\left(B_{1}\right)}^{2} .
\end{align*}
$$

Now, for $R^{\prime}>R$, let $P_{R^{\prime}, R}$ be such that

$$
\left\|f_{R^{\prime}}-f_{R}-P_{R^{\prime}, R}\right\|_{L^{\infty}\left(B_{1}\right)}=\min \left\|f_{R^{\prime}}-f_{R}-P\right\|_{L^{\infty}\left(B_{1}\right)}
$$

where the minimization is meant over all the polynomials $P$ of degree at most $k-1$. From (3.16) (used here with $m=0$ ), we know that

$$
\left\|f_{R^{\prime}}-f_{R}-P_{R^{\prime}, R}\right\|_{L^{2}\left(B_{1}\right)} \leqslant\left\|f_{R^{\prime}}-f_{R}-P_{R^{\prime}, R}\right\|_{L^{\infty}\left(B_{1}\right)} \leqslant C \nu_{R}
$$

Hence, in view of (3.35), we have that

$$
\left\|f_{R^{\prime}}^{\sharp}-\left(f_{R}+P_{R^{\prime}, R}\right)^{\sharp}\right\|_{L^{2}\left(B_{1}\right)} \leqslant C \nu_{R} .
$$

This and (3.34) give that

$$
\begin{equation*}
\left\|f_{R^{\prime}}^{\sharp}-f_{R}^{\sharp}\right\|_{L^{2}\left(B_{1}\right)} \leqslant C \nu_{R} . \tag{3.36}
\end{equation*}
$$

Thus, we can pass to the limit as $R^{\prime} \rightarrow+\infty$ and use Fatou's Lemma to obtain (3.33), as desired.
Notice that, from (3.33), up to a subsequence we obtain (3.30).
Then, from (3.30), we have that, a.e. in $B_{1}$,

$$
f^{\sharp}-f=\lim _{R \rightarrow+\infty}\left(f_{R}^{\sharp}-f_{R}\right)=\lim _{R \rightarrow+\infty} P_{f_{R}}^{\sharp} .
$$

This and Lemma 2.1 imply that $f^{\sharp}-f$ is a polynomial of degree at most $k-1$, and this proves (3.31). Then, in view of (1.8) and (3.31), we have that $(-\Delta)^{s} u \stackrel{k}{=} f^{\sharp}$.
This fact and (3.30) give that we can use Corollary 3.7 with the function $f_{R}^{\sharp}$ : in this way, we fix

$$
\begin{equation*}
m \geqslant k+n+2 \tag{3.37}
\end{equation*}
$$

and we have from (3.16) that, for any $R^{\prime}>R$,

$$
\begin{equation*}
\left\|D^{m}\left(f_{R^{\prime}}^{\sharp}-f_{R}^{\sharp}\right)\right\|_{L^{\infty}\left(B_{1}\right)} \leqslant C \nu_{R} . \tag{3.38}
\end{equation*}
$$

Now we recall the Gagliardo-Nirenberg Interpolation Inequality (see e.g. pages 125-126 in [16]), namely, for any $i \leqslant$ $m \in \mathbb{N}$,

$$
\left\|D^{i} \varphi\right\|_{L^{2}\left(B_{1}\right)} \leqslant C\left(\|\varphi\|_{L^{2}\left(B_{1}\right)}^{1-\frac{i}{m}}\left\|D^{m} \varphi\right\|_{L^{2}\left(B_{1}\right)}^{\frac{i}{m}}+\|\varphi\|_{L^{2}\left(B_{1}\right)}\right)
$$

for some $C>0$. Taking $\varphi:=f_{R^{\prime}}^{\sharp}-f_{R}^{\sharp}$ and using (3.36) and (3.38), we conclude that, for $R^{\prime}>R$ large enough,

$$
\begin{equation*}
\left\|D^{i}\left(f_{R^{\prime}}^{\sharp}-f_{R}^{\sharp}\right)\right\|_{L^{2}\left(B_{1}\right)} \leqslant C \nu_{R}, \tag{3.39}
\end{equation*}
$$

for any $i \in\{0, \ldots, m\}$, up to renaming $C>0$.
Now, since we do not know if $f_{R}^{\sharp}$ is sufficiently smooth, we perform a technical argument to take limits. Namely, we set

$$
\begin{equation*}
\xi_{R}:=f_{R}^{\sharp}-f^{\sharp} \tag{3.40}
\end{equation*}
$$

From (3.33) and (3.39), for any $\phi \in C_{0}^{\infty}\left(B_{1}\right)$ and any $\iota \in \mathbb{N}^{n}$ with $|\iota|=i \in\{0, \ldots, m\}$, we have that

$$
\begin{aligned}
\int_{B_{1}} & D^{\iota} \xi_{R} \phi=(-1)^{i} \int_{B_{1}} \xi_{R} D^{\iota} \phi=(-1)^{i} \int_{B_{1}}\left(f_{R}^{\sharp}-f^{\sharp}\right) D^{\iota} \phi \\
\quad= & \lim _{R^{\prime} \rightarrow+\infty}(-1)^{i} \int_{B_{1}}\left(f_{R}^{\sharp}-f_{R^{\prime}}^{\sharp}\right) D^{\iota} \phi=\lim _{R^{\prime} \rightarrow+\infty} \int_{B_{1}} D^{\iota}\left(f_{R}^{\sharp}-f_{R^{\prime}}^{\sharp}\right) \phi \\
& \leqslant C \nu_{R} \int_{B_{1}}|\phi| \leqslant C \nu_{R}\|\phi\|_{L^{2}\left(B_{1}\right)} .
\end{aligned}
$$

Then, by the density of $C_{0}^{\infty}\left(B_{1}\right)$ in $L^{2}\left(B_{1}\right)$, this inequality holds for any $\phi \in L^{2}\left(B_{1}\right)$, and thus

$$
\left\|D^{\iota} \xi_{R}\right\|_{L^{2}\left(B_{1}\right)}=\sup _{0 \neq \phi \in L^{2}\left(B_{1}\right)} \frac{\int_{B_{1}} D^{\iota} \xi_{R} \phi}{\|\phi\|_{L^{2}\left(B_{1}\right)}} \leqslant C \nu_{R}
$$

Accordingly, since this is valid for all $|\iota|=i \in\{0, \ldots, m\}$,

$$
\left\|\xi_{R}\right\|_{W^{m, 2}\left(B_{1}\right)} \leqslant C \nu_{R}
$$

up to renaming constants.
From this and the Sobolev Inequality, recalling also (3.40), it follows ${ }^{5}$ that

$$
\left\|f_{R}^{\sharp}-f^{\sharp}\right\|_{C^{m^{\prime}\left(B_{1}\right)}}=\left\|\xi_{R}\right\|_{C^{m^{\prime}\left(B_{1}\right)}} \leqslant C \nu_{R},
$$

with $m^{\prime}=m-\left\lfloor\frac{n}{2}\right\rfloor-1$, up to renaming $C>0$. This is the desired result in (3.32), up to renaming $m$ in the statement of Lemma 3.11.

[^4]
## 4 Schauder estimates for divergent fractional Laplacians

This section is devoted to the proof of Theorem 1.3. For this, we first give a uniform bound for solutions, as stated in the following result:

Lemma 4.1. Let $\beta \in(0,1), m \in \mathbb{N}, s \in(0,1)$ and $u: \mathbb{R}^{n} \rightarrow \mathbb{R}$.
Assume that $u$ is continuous in $B_{1}$ and that

$$
J_{u, 0}:=\int_{B_{1 / 2}^{c}} \frac{|u(y)|}{|y|^{n+2 s}} d y<+\infty
$$

Suppose that

$$
(-\Delta)^{s} u=f \quad \text { in } B_{1}
$$

in the viscosity sense. Then

$$
\|u\|_{L^{\infty}\left(B_{9 / 10}\right)}+\|f\|_{C^{m}\left(B_{99 / 100}\right)} \leqslant C\left([f]_{C^{m+\beta}\left(B_{1}\right)}+J_{u, 0}\right)
$$

for some $C>0$, only depending on $n, s, m$ and $\beta$.

Proof. By contradiction, we can suppose that there exist sequences of functions $u_{j}$ and $f_{j}$ such that $(-\Delta)^{s} u_{j}=$ $f_{j}$ in $B_{1}$, with

$$
\begin{equation*}
\Theta_{j}:=\left\|u_{j}\right\|_{L^{\infty}\left(B_{9 / 10}\right)}+\left\|f_{j}\right\|_{C^{m}\left(B_{99 / 100}\right)}>j\left(\left[f_{j}\right]_{C^{m+\beta}\left(B_{1}\right)}+J_{u_{j}, 0}\right) . \tag{4.1}
\end{equation*}
$$

We define

$$
\tilde{u}_{j}:=\frac{u_{j}}{\Theta_{j}} \quad \text { and } \quad \tilde{f}_{j}:=\frac{f_{j}}{\Theta_{j}}
$$

Then,

$$
\begin{equation*}
(-\Delta)^{s} \tilde{u}_{j}=\tilde{f}_{j} \quad \text { in } B_{1} \tag{4.2}
\end{equation*}
$$

Also,

$$
\begin{equation*}
\left\|\tilde{f}_{j}\right\|_{C^{m}\left(B_{99 / 100}\right)}=\frac{\left\|f_{j}\right\|_{C^{m}\left(B_{99 / 100}\right)}}{\Theta_{j}} \leqslant 1 \tag{4.3}
\end{equation*}
$$

and

$$
\begin{equation*}
\left[\tilde{f}_{j}\right]_{C^{m+\beta}\left(B_{1}\right)}=\frac{\left[f_{j}\right]_{C^{m+\beta}\left(B_{1}\right)}}{\Theta_{j}} \leqslant \frac{1}{j}, \tag{4.4}
\end{equation*}
$$

due to (4.1).
In particular, we have that $\left\|\tilde{f}_{j}\right\|_{C^{m+\beta}\left(B_{99 / 100}\right)} \leqslant 2$. From this, up to a subsequence, we may suppose that

$$
\begin{equation*}
\tilde{f}_{j} \text { converges to some } \tilde{f} \text { in } C^{m+\beta}\left(B_{99 / 100}\right) . \tag{4.5}
\end{equation*}
$$

We also remark that

$$
[\tilde{f}]_{C^{m+\beta}\left(B_{99 / 100}\right)} \leqslant\left[\tilde{f}-\tilde{f}_{j}\right]_{C^{m+\beta}\left(B_{99 / 100}\right)}+\left[\tilde{f}_{j}\right]_{C^{m+\beta}\left(B_{99 / 100}\right)} \leqslant\left\|\tilde{f}-\tilde{f}_{j}\right\|_{C^{m+\beta}\left(B_{99 / 100}\right)}+\frac{1}{j}
$$

which goes to zero as $j \rightarrow+\infty$. This means that $D^{m} \tilde{f}$ is constant in $B_{99 / 100}$, hence $D^{m+1} \tilde{f}$ vanishes in $B_{99 / 100}$ and

$$
\begin{equation*}
\tilde{f} \text { is a polynomial of degree } m \text {. } \tag{4.6}
\end{equation*}
$$

Moreover,

$$
\begin{equation*}
J_{\tilde{u}_{j}, 0}=\frac{J_{u_{j}, 0}}{\Theta_{j}} \leqslant \frac{1}{j} \tag{4.7}
\end{equation*}
$$

thanks to (4.1).
Now, from (4.2) and Lemma 5.2 in [3] (see also the remark after it), we have that

$$
\begin{equation*}
\left\|\tilde{u}_{j}\right\|_{L^{\infty}\left(B_{97 / 100}\right)} \leqslant C\left(\left\|\tilde{f}_{j}\right\|_{L^{\infty}\left(B_{99 / 100}\right)}+J_{\tilde{u}_{j}, 0}\right) \tag{4.8}
\end{equation*}
$$

for some $C>0$.
Also, by Proposition 7.1(a) in [3], we have that, for any fixed $\alpha \in(0,2 s)$,

$$
\left\|\tilde{u}_{j}\right\|_{C^{\alpha}\left(B_{9 / 10}\right)} \leqslant C\left(\left\|\tilde{f}_{j}\right\|_{L^{\infty}\left(B_{97 / 100}\right)}+\left\|\tilde{u}_{j}\right\|_{L^{\infty}\left(B_{97 / 100}\right)}+J_{\tilde{u}_{j}, 0}\right)
$$

for some $C>0$. Hence, making use of (4.3), (4.7) and (4.8), we conclude that $\left\|\tilde{u}_{j}\right\|_{C^{\alpha}\left(B_{9 / 10}\right)}$ is bounded uniformly in $j$ and so, up to a subsequence, we may assume that $\tilde{u}_{j}$ converges to some $\tilde{u}$ in $L^{\infty}\left(B_{9 / 10}\right)$.

As a matter of fact, from (4.7), we also know that $\tilde{u}_{j}$ converges to zero a.e. outside $B_{1 / 2}$, hence we can extend $\tilde{u}$ to be zero outside $B_{9 / 10}$ and write that

$$
\begin{equation*}
\lim _{j \rightarrow+\infty}\left\|\tilde{u}_{j}-\tilde{u}\right\|_{L^{\infty}\left(B_{9 / 10}\right)}+\int_{\mathbb{R}^{n}} \frac{\left|\tilde{u}_{j}(y)-\tilde{u}(y)\right|}{1+|y|^{n+2 s}} d y=0 \tag{4.9}
\end{equation*}
$$

with

$$
\begin{equation*}
\tilde{u}=0 \text { outside } B_{1 / 2} \tag{4.10}
\end{equation*}
$$

Hence, exploiting (4.5), (4.9) and Lemma 5 in [5], we can pass (4.2) to the limit and find that

$$
\begin{equation*}
(-\Delta)^{s} \tilde{u}=\tilde{f} \quad \text { in } B_{9 / 10} \tag{4.11}
\end{equation*}
$$

From this, (4.6), (4.10) and Lemma 2.3, we obtain that $\tilde{u}$ vanishes identically.
This and (4.11) give that $\tilde{f}=0$ in $B_{9 / 10}$ (and in fact, from (4.6), we have that $\tilde{f}=0$ in $B_{99 / 100}$ ). Consequently, recalling (4.5) and (4.9),

$$
\begin{aligned}
1= & \lim _{j \rightarrow+\infty} \frac{\left\|u_{j}\right\|_{L^{\infty}\left(B_{9 / 10}\right)}+\left\|f_{j}\right\|_{C^{m}\left(B_{99 / 100}\right)}}{\Theta_{j}}=\lim _{j \rightarrow+\infty}\left\|\tilde{u}_{j}\right\|_{L^{\infty}\left(B_{9 / 10}\right)}+\left\|\tilde{f}_{j}\right\|_{C^{m}\left(B_{99 / 100}\right)} \\
& =\lim _{j \rightarrow+\infty}\left\|\tilde{u}_{j}-\tilde{u}\right\|_{L^{\infty}\left(B_{9 / 10}\right)}+\left\|\tilde{f}_{j}-\tilde{f}\right\|_{C^{m}\left(B_{99 / 100}\right)}=0
\end{aligned}
$$

which is, of course, a contradiction.

To address the Schauder estimates of Theorem 1.3, we now provide a simpler, suboptimal version (this result can be obtained by a suitable iteration argument from the existing literature, but we give the precise statement and the details of the proof for the reader's convenience):

Lemma 4.2. Let $s \in(0,1)$, $u$ be continuous in $B_{1}$, with $u \in L^{\infty}\left(\mathbb{R}^{n}\right), f: B_{1} \rightarrow \mathbb{R}$ and suppose that

$$
(-\Delta)^{s} u=f \quad \text { in } B_{1}
$$

in the viscosity sense. Then, for any $\gamma>0$ for which $\gamma \notin \mathbb{N}$ and $\gamma+2 s \notin \mathbb{N}$,

$$
\|u\|_{C^{\gamma+2 s}\left(B_{1 / 2}\right)} \leqslant C\left(\|f\|_{C^{\gamma}\left(B_{1}\right)}+\|u\|_{L^{\infty}\left(\mathbb{R}^{n}\right)}\right)
$$

for some $C>0$, only depending on $n, s$ and $\gamma$.

Proof. We write $\gamma=m+\theta$, with $m:=\lfloor\gamma\rfloor$ and $\theta \in(0,1)$. The proof is by induction over $m$. When $m=0$, the claim follows from Proposition 7.2(b) in [3] (or Corollary 3.5 in [18]).
Now suppose that the claim is true for some $m \in \mathbb{N}$ and we prove it for $m+1$. That is, we assume, recursively, that

$$
\begin{equation*}
\|u\|_{C^{m+\theta+2 s}\left(B_{1 / 2}\right)} \leqslant C\left(\|f\|_{C^{m+\theta}\left(B_{1}\right)}+\|u\|_{L^{\infty}\left(\mathbb{R}^{n}\right)}\right) \tag{4.12}
\end{equation*}
$$

and we prove the same statement for $m+1$ in the place of $m$ (up to renaming $C$ and possibly resizing balls).
For the sake of simplicity, let us first deal with the case

$$
\begin{equation*}
\theta+2 s>1 \tag{4.13}
\end{equation*}
$$

For this, we take an incremental quotient of order $m+1$, that is we fix $\omega_{1}, \ldots, \omega_{m+1} \in S^{n-1}$ and we let $v:=$ $D_{h}^{\left(\omega_{1}, \ldots, \omega_{m+1}\right)} u$ and $g:=D_{h}^{\left(\omega_{1}, \ldots, \omega_{m+1}\right)} f$ (recall the notation of finite differences in Appendix A. Then, for small $h$, we have that

$$
(-\Delta)^{s} v=g \quad \text { in } \quad B_{9 / 10}
$$

in the viscosity sense. Then, we take $\phi \in C_{0}^{\infty}\left(B_{1 / 4}\right)$ with $\phi=1$ in $B_{1 / 8}$ and we define $w:=\phi v$. In this way, we obtain that, for any $x \in B_{1 / 16}$,

$$
\begin{align*}
& (-\Delta)^{s} w(x)=\int_{\mathbb{R}^{n}} \frac{v(x)-(\phi v)(y)}{|x-y|^{n+2 s}} d y=g(x)+\int_{\mathbb{R}^{n}} \frac{(1-\phi(y)) v(y)}{|x-y|^{n+2 s}} d y \\
& \quad=g(x)+\int_{\mathbb{R}^{n}} \frac{(1-\phi(y)) D_{h}^{\left(\omega_{1}, \ldots, \omega_{m+1}\right)} u(y)}{|x-y|^{n+2 s}} d y \tag{4.14}
\end{align*}
$$

Notice that, if, for any $x \in B_{1 / 16}$, we set

$$
\Psi^{(x)}(y):=\frac{1-\phi(y)}{|x-y|^{n+2 s}}
$$

we have that $\Psi^{(x)}$ vanishes in $B_{1 / 8}$ and so $\Psi^{(x)} \in L^{1}\left(\mathbb{R}^{n}\right)$. Therefore, by Lemma A.2,

$$
\begin{gathered}
\int_{\mathbb{R}^{n}} \frac{(1-\phi(y)) D_{h}^{\left(\omega_{1}, \ldots, \omega_{m+1}\right)} u(y)}{|x-y|^{n+2 s}} d y=\int_{\mathbb{R}^{n}} \Psi^{(x)}(y) D_{h}^{\left(\omega_{1}, \ldots, \omega_{m+1}\right)} u(y) d y \\
=\int_{\mathbb{R}^{n}} D_{h}^{\left(-\omega_{1}, \ldots,-\omega_{m+1}\right)} \Psi^{(x)}(y) u(y) d y=: G(x)
\end{gathered}
$$

with

$$
\|G\|_{C^{1}\left(B_{1 / 16}\right)} \leqslant C h^{m+1}\|u\|_{L^{\infty}\left(\mathbb{R}^{n}\right)}
$$

Hence, (4.14) gives that $(-\Delta)^{s} w=H$ in $B_{1 / 16}$, with $H:=g+G$ and, by Lemma A.1, we have

$$
\|H\|_{C^{\theta}\left(B_{1 / 16}\right)} \leqslant\|g\|_{C^{\theta}\left(B_{1 / 16}\right)}+\|G\|_{C^{\theta}\left(B_{1 / 16}\right)} \leqslant C h^{m+1}\left(\|f\|_{C^{m+1+\theta}\left(B_{1 / 8}\right)}+\|u\|_{L^{\infty}\left(\mathbb{R}^{n}\right)}\right)
$$

That is, using the claim with $m=0$ and once more Lemma A.1,

$$
\begin{aligned}
\left\|D_{h}^{\left(\omega_{1}, \ldots, \omega_{m+1}\right)} u\right\|_{C^{\theta+2 s}\left(B_{1 / 32}\right)} & =\|w\|_{C^{\theta+2 s}\left(B_{1 / 32}\right)} \\
& \leqslant C\left(\|H\|_{C^{\theta}\left(B_{1 / 16}\right)}+\|w\|_{L^{\infty}\left(\mathbb{R}^{n}\right)}\right) \\
& \leqslant C h^{m+1}\left(\|f\|_{C^{m+1+\theta}\left(B_{1 / 8}\right)}+\|u\|_{L^{\infty}\left(\mathbb{R}^{n}\right)}+\|u\|_{C^{m+1}\left(B_{1 / 4}\right)}\right)
\end{aligned}
$$

Dividing by $h^{m+1}$, sending $h \rightarrow 0$ and recalling again Lemma A.1, we thus find that

$$
\left\|D^{m+1} u\right\|_{C^{\theta+2 s}\left(B_{1 / 32}\right)} \leqslant C\left(\|f\|_{C^{m+1+\theta}\left(B_{1 / 8}\right)}+\|u\|_{L^{\infty}\left(\mathbb{R}^{n}\right)}+\|u\|_{C^{m+1}\left(B_{1 / 4}\right)}\right)
$$

This, together with (4.12) and (4.13), gives that

$$
\|u\|_{C^{m+1+\theta+2 s}\left(B_{1 / 32}\right)} \leqslant C\left(\|f\|_{C^{m+1+\theta}\left(B_{1}\right)}+\|u\|_{L^{\infty}\left(\mathbb{R}^{n}\right)}\right)
$$

up to renaming $C>0$, which is the iterative version of (4.12) (up to renaming constants and resizing balls), as desired.
If, on the other hand, the condition in (4.13) does not hold, i.e. $\theta+2 s \in(0,1)$, then the previous proof must be done step by step, namely, one takes $\bar{N} \in \mathbb{N}$ so large that $\bar{\alpha}:=1 / \bar{N}<\theta+2 s$. Then one considers the functions

$$
\begin{aligned}
v(x) & :=D_{h}^{\left(\omega_{1}, \ldots, \omega_{m}\right)} u\left(x+\omega_{m+1}\right)-D_{h}^{\left(\omega_{1}, \ldots, \omega_{m}\right)} u(x) \\
\text { and } \quad g(x) & :=D_{h}^{\left(\omega_{1}, \ldots, \omega_{m}\right)} f\left(x+\omega_{m+1}\right)-D_{h}^{\left(\omega_{1}, \ldots, \omega_{m}\right)} f(x) .
\end{aligned}
$$

Then, the argument above would give a bound like

$$
\|u\|_{C^{m+\bar{\alpha}+\theta+2 s}\left(B_{1 / 32}\right)} \leqslant C\left(\|f\|_{C^{m+\bar{\alpha}+\theta}\left(B_{1}\right)}+\|u\|_{L^{\infty}\left(\mathbb{R}^{n}\right)}\right)
$$

Hence, one repeats this argument over and over to get

$$
\|u\|_{C^{m+j \bar{\alpha}+\theta+2 s}\left(B_{r_{j}}\right)} \leqslant C\left(\|f\|_{C^{m+j \bar{\alpha}+\theta}\left(B_{1}\right)}+\|u\|_{L^{\infty}\left(\mathbb{R}^{n}\right)}\right)
$$

for every $j \in\{1, \ldots, \bar{N}\}$, which gives the desired result in the end.

Now, we deal with the Schauder estimates in the case of the non-divergent fractional Laplacian, corresponding to $k:=0$ in Theorem 1.3. This case is dealt with explicitly in the following result:

Proposition 4.3. [Sharp Schauder estimates for the classical fractional Laplacian] Let $s \in(0,1), u: \mathbb{R}^{n} \rightarrow \mathbb{R}$ and $f: B_{1} \rightarrow \mathbb{R}$.

Assume that $u$ is continuous in $B_{1}$ and that

$$
J_{u, 0}:=\int_{B_{1 / 2}^{c}} \frac{|u(y)|}{|y|^{n+2 s}} d y<+\infty
$$

Suppose that

$$
(-\Delta)^{s} u=f \quad \text { in } B_{1}
$$

in the viscosity sense. Then, for any $\gamma>0$ for which $\gamma \notin \mathbb{N}$ and $\gamma+2 s \notin \mathbb{N}$,

$$
\begin{equation*}
\|u\|_{C^{\gamma+2 s}\left(B_{1 / 2}\right)} \leqslant C\left([f]_{C^{\gamma}\left(B_{1}\right)}+J_{u, 0}\right) \tag{4.15}
\end{equation*}
$$

for some $C>0$, only depending on $n, s$ and $\gamma$.
Proof. Since we are dealing with interior estimates, up to resizing balls, we will assume that

$$
\begin{equation*}
(-\Delta)^{s} u=f \quad \text { in } B_{4} \tag{4.16}
\end{equation*}
$$

We take $\tau \in C_{0}^{\infty}\left(B_{3},[0,1]\right)$ with $\tau=1$ in $B_{2}$ and we set $v:=\tau u$. We also define

$$
\begin{aligned}
\tilde{f}(x) & :=\int_{\mathbb{R}^{n}} \frac{(1-\tau(y)) u(y)}{|x-y|^{n+2 s}} d y=\int_{B_{2}^{c}} \frac{(1-\tau(y)) u(y)}{|x-y|^{n+2 s}} d y \\
\text { and } \quad g(x) & :=f(x)+\tilde{f}(x) .
\end{aligned}
$$

Hence, from (4.16), we see that, for any $x \in B_{3 / 2}$,

$$
(-\Delta)^{s} v(x)=\int_{\mathbb{R}^{n}} \frac{u(x)-\tau(y) u(y)}{|x-y|^{n+2 s}}=g(x)
$$

Then, from Lemma 4.2, we know that

$$
\begin{equation*}
\|v\|_{C^{\gamma+2 s}\left(B_{1}\right)} \leqslant C\left(\|v\|_{L^{\infty}\left(\mathbb{R}^{n}\right)}+\|g\|_{C^{\gamma}\left(B_{3 / 2}\right)}\right) \tag{4.17}
\end{equation*}
$$

for some $C>0$.
Now we observe that, from (4.16) and Lemma 4.1,

$$
\begin{equation*}
\|v\|_{L^{\infty}\left(\mathbb{R}^{n}\right)}=\|v\|_{L^{\infty}\left(B_{3}\right)} \leqslant\|u\|_{L^{\infty}\left(B_{3}\right)} \leqslant C\left([f]_{C^{\gamma}\left(B_{4}\right)}+\int_{B_{2}^{c}} \frac{|u(y)|}{|y|^{n+2 s}} d y\right) \tag{4.18}
\end{equation*}
$$

up to renaming $C>0$.
Also, for any $m \in \mathbb{N}$ and any $x, \bar{x} \in B_{3 / 2}$,

$$
\begin{aligned}
& \quad\left|D^{m} \tilde{f}(x)\right| \leqslant C \int_{B_{2}^{c}} \frac{|u(y)|}{|x-y|^{n+2 s+m}} d y \\
& \text { and } \quad\left|D^{m} \tilde{f}(x)-D^{m} \tilde{f}(\bar{x})\right| \leqslant C|x-\bar{x}| \int_{B_{2}^{c}} \frac{|u(y)|}{|x-y|^{n+2 s+m+1}} d y
\end{aligned}
$$

with $C>0$ depending on $m$. As a consequence,

$$
\|\tilde{f}\|_{C^{\gamma}\left(B_{3 / 2}\right)} \leqslant C \int_{B_{2}^{c}} \frac{|u(y)|}{|y|^{n+2 s}} d y
$$

and therefore

$$
\begin{equation*}
\|g\|_{C^{\gamma}\left(B_{3 / 2}\right)} \leqslant\|f\|_{C^{\gamma}\left(B_{3 / 2}\right)}+\|\tilde{f}\|_{C^{\gamma}\left(B_{3 / 2}\right)} \leqslant\|f\|_{C^{\gamma}\left(B_{3 / 2}\right)}+C \int_{B_{2}^{c}} \frac{|u(y)|}{|y|^{n+2 s}} d y \tag{4.19}
\end{equation*}
$$

We also observe that $u=v$ in $B_{1}$ and thus

$$
\begin{equation*}
\|v\|_{C^{\gamma+2 s}\left(B_{1}\right)}=\|u\|_{C^{\gamma+2 s}\left(B_{1}\right)} \tag{4.20}
\end{equation*}
$$

So, we insert (4.18), (4.19) and (4.20) into (4.17) and we conclude that

$$
\begin{equation*}
\|u\|_{C^{\gamma+2 s}\left(B_{1}\right)} \leqslant C\left(\|f\|_{C^{\gamma}\left(B_{3 / 2}\right)}+[f]_{C^{\gamma}\left(B_{4}\right)}+\int_{B_{2}^{c}} \frac{|u(y)|}{|y|^{n+2 s}} d y\right) \tag{4.21}
\end{equation*}
$$

for some $C>0$.
Also, from (4.16) and Lemma 4.1, if we write $\gamma=m+\beta$, with $m:=\lfloor\gamma\rfloor$ and $\beta \in(0,1)$, we have that

$$
\|f\|_{C^{m}\left(B_{3 / 2}\right)} \leqslant C\left([f]_{C^{m+\beta}\left(B_{4}\right)}+\int_{B_{2}^{c}} \frac{|u(y)|}{|y|^{n+2 s}} d y\right)
$$

Therefore, summing $[f]_{C^{m+\beta}\left(B_{3 / 2}\right)}=[f]_{C^{\gamma}\left(B_{3 / 2}\right)}$ to both sides of this inequality, we find that

$$
\|f\|_{C^{\gamma}\left(B_{3 / 2}\right)} \leqslant C\left([f]_{C^{\gamma}\left(B_{4}\right)}+\int_{B_{2}^{c}} \frac{|u(y)|}{|y|^{n+2 s}} d y\right)
$$

So, we plug this information into (4.21) and we conclude that

$$
\|u\|_{C^{\gamma+2 s}\left(B_{1}\right)} \leqslant C\left([f]_{C^{\gamma}\left(B_{4}\right)}+\int_{B_{2}^{c}} \frac{|u(y)|}{|y|^{n+2 s}} d y\right)
$$

up to renaming $C>0$, and this is (4.15), after resizing balls.
From Proposition 4.3, we obtain a Schauder estimate for the cutoff equation, as detailed in the following result:
Proposition 4.4. Let $s \in(0,1), k \in \mathbb{N}$ and $u: \mathbb{R}^{n} \rightarrow \mathbb{R}$.
Assume that $u \in C_{\text {loc }}^{\alpha}\left(B_{1}\right)$ for some $\alpha>2 s$ and that

$$
J_{u, k}:=\int_{B_{1 / 2}^{c}} \frac{|u(y)|}{|y|^{n+2 s+k}} d y<+\infty
$$

Let $f_{u}$ be as in Corollary 3.2. Let also

$$
\begin{equation*}
\gamma>k-1 \tag{4.22}
\end{equation*}
$$

such that $\gamma \notin \mathbb{N}$ and $\gamma+2 s \notin \mathbb{N}$. Then, it holds that

$$
\begin{equation*}
\|u\|_{C^{\gamma+2 s}\left(B_{1 / 2}\right)} \leqslant C\left(\left[f_{u}\right]_{C^{\gamma}\left(B_{1}\right)}+J_{u, k}\right) \tag{4.23}
\end{equation*}
$$

for some $C>0$, only depending on $n, s, \gamma$ and $k$.
Proof. We write $\gamma=m+\theta$, with $m \in \mathbb{N}$ and $\theta \in(0,1)$. From (4.22), we infer that

$$
\begin{equation*}
m \geqslant k-1 \tag{4.24}
\end{equation*}
$$

We take a family of cutoffs $\chi_{R}$ as in (1.3) and we exploit Theorem 3.1 with $\tau:=\chi_{4}$. Then, if we set $v:=\chi_{4} u$, we obtain that, for any $x \in B_{1}$,

$$
\begin{equation*}
(-\Delta)^{s} v(x)=P_{u, \chi_{4}}(x)+f_{u, \chi_{4}}(x) \tag{4.25}
\end{equation*}
$$

and $P_{u, \chi_{4}}$ is a polynomial of degree at most $k-1$.
In particular, from (4.24), we see that $\left[D^{m} P_{u, \chi_{4}}\right]_{C^{\theta}\left(B_{1}\right)}$ vanishes. Thus, from (4.25) and (4.15), we find that

$$
\begin{align*}
\|u\|_{C^{\gamma+2 s}\left(B_{1 / 2}\right)} & =\|v\|_{C^{\gamma+2 s}\left(B_{1 / 2}\right)} \\
& \leqslant C\left(\left[P_{u, \chi_{4}}+f_{u, \chi_{4}}\right]_{C^{\gamma}\left(B_{1}\right)}+J_{v, 0}\right)  \tag{4.26}\\
& =C\left(\left[f_{u, \chi_{4}}\right]_{C^{\gamma}\left(B_{1}\right)}+J_{v, 0}\right)
\end{align*}
$$

Now we set

$$
\tilde{f}(x):=\int_{B_{2}^{c}} \frac{\left(\chi_{4}(y)-1\right) u(y) \psi(x, y)}{|y|^{n+2 s+k}} d y
$$

where $\psi$ is as in Theorem 3.1. Notice that

$$
D^{m} \tilde{f}(x)=\int_{B_{2}^{c}} \frac{\left(\chi_{4}(y)-1\right) u(y) D^{m} \psi(x, y)}{|y|^{n+2 s+k}} d y
$$

and therefore

$$
\begin{equation*}
[\tilde{f}]_{C^{\gamma}\left(B_{1}\right)} \leqslant C \int_{B_{2}^{c}} \frac{|u(y)|}{|y|^{n+2 s+k}} d y \leqslant C J_{u, k} \tag{4.27}
\end{equation*}
$$

for some $C>0$ (notice that the dependence of $C$ on $\psi$ here is inessential, due to Remark 3.3).
Also, from Remark 3.4, (3.5) and (3.15), we know that

$$
f_{u, \chi_{4}}=f_{u}-f_{3, u}+f_{u, \chi_{4}}^{\star}=f_{u}+\tilde{f}
$$

This and (4.27) imply that

$$
\begin{equation*}
\left[f_{u, \chi_{4}}\right]_{C^{\gamma}\left(B_{1}\right)} \leqslant\left[f_{u}\right]_{C^{\gamma}\left(B_{1}\right)}+C J_{u, k} \tag{4.28}
\end{equation*}
$$

Furthermore,

$$
\begin{aligned}
J_{v, 0}= & \int_{B_{1 / 2}^{c}} \frac{\left|\left(\chi_{4} u\right)(y)\right|}{|y|^{n+2 s}} d y \leqslant \int_{B_{4} \backslash B_{1 / 2}} \frac{\left|\left(\chi_{4} u\right)(y)\right|}{|y|^{n+2 s}} d y \\
& \leqslant C \int_{B_{4} \backslash B_{1 / 2}} \frac{\left|\left(\chi_{4} u\right)(y)\right|}{|y|^{n+2 s+k}} d y \leqslant C J_{u, k}
\end{aligned}
$$

So, we insert this and (4.28) into (4.26) and we obtain the desired result.

By combining Definition 1.1 and Proposition 4.4, we obtain:
Corollary 4.5. Let $s \in(0,1), k \in \mathbb{N}, u: \mathbb{R}^{n} \rightarrow \mathbb{R}$ and $f: B_{1} \rightarrow \mathbb{R}$.
Assume that $u$ is continuous in $B_{1}$ and

$$
J_{u, k}:=\int_{B_{1 / 2}^{c}} \frac{|u(y)|}{|y|^{n+2 s+k}} d y<+\infty
$$

Suppose that

$$
\begin{equation*}
(-\Delta)^{s} u \stackrel{k}{=} f \quad \text { in } B_{1} \tag{4.29}
\end{equation*}
$$

Then, for any

$$
\begin{equation*}
\gamma>k-1 \tag{4.30}
\end{equation*}
$$

such that $\gamma \notin \mathbb{N}$ and $\gamma+2 s \notin \mathbb{N}$, it holds that

$$
\begin{equation*}
\|u\|_{C^{\gamma+2 s}\left(B_{1 / 2}\right)} \leqslant C\left([f]_{C^{\gamma}\left(B_{1}\right)}+J_{u, k}\right) \tag{4.31}
\end{equation*}
$$

for some $C>0$, only depending on $n, s, \gamma$ and $k$.
Proof. First of all, we prove the result under the additional assumption that

$$
\begin{equation*}
u \in C_{\mathrm{loc}}^{\alpha}\left(B_{1}\right) \text { for some } \alpha>2 s \tag{4.32}
\end{equation*}
$$

In this case, we fall under the assumptions of Remark 3.5, and so we have that

$$
\begin{equation*}
(-\Delta)^{s} u \stackrel{k}{=} f_{u} \quad \text { in } B_{1} \tag{4.33}
\end{equation*}
$$

Also,

$$
\begin{equation*}
(-\Delta)^{s} u \stackrel{k}{=} f \quad \text { in } B_{1} \tag{4.34}
\end{equation*}
$$

Consequently, by (4.34) and (4.33), in view of Lemma 1.2, it follows that $f-f_{u}$ is a polynomial $P_{u}$ of degree at most $k-1$.
From this and (4.30), we obtain that $\left[f_{u}\right]_{C^{\gamma}\left(B_{1}\right)}=[f]_{C^{\gamma}\left(B_{1}\right)}$. This and (4.23) imply (4.31).
Now we consider the general case. For this, we take $\rho \in C_{0}^{\infty}\left(B_{1}\right)$ and consider the mollifier $\rho_{\varepsilon}(x):=\varepsilon^{-n} \rho(x / \varepsilon)$. We consider the convolutions $u_{\varepsilon}:=u * \rho_{\varepsilon}$ and $f_{\varepsilon}:=f * \rho_{\varepsilon}$ and we know (see e.g. formula (3.2) in [19]) that $(-\Delta)^{s} u_{\varepsilon}=f_{\varepsilon}$ in $B_{99 / 100}$, as long as $\varepsilon$ is small enough. Since (4.32) is satisfied by $u_{\varepsilon}$, we can apply the result already established and conclude that, up to resizing balls,

$$
\begin{equation*}
\left\|u_{\varepsilon}\right\|_{C^{\gamma+2 s}\left(B_{9 / 10}\right)} \leqslant C\left(\left[f_{\varepsilon}\right]_{C^{\gamma}\left(B_{9 / 10}\right)}+\int_{B_{3 / 4}^{c}} \frac{\left|u_{\varepsilon}(y)\right|}{|y|^{n+2 s+k}} d y\right) \tag{4.35}
\end{equation*}
$$

for some $C>0$. In particular, $u_{\varepsilon}$ converges to $u$ in $C^{\gamma+2 s}\left(B_{1 / 2}\right)$ and, by taking limits, we have that

$$
\begin{equation*}
\lim _{\varepsilon \rightarrow 0}\left\|u_{\varepsilon}\right\|_{C^{\gamma+2 s}\left(B_{9 / 10}\right)} \geqslant\|u\|_{C^{\gamma+2 s}\left(B_{1 / 2}\right)} \quad \text { and } \quad \lim _{\varepsilon \rightarrow 0}\left[f_{\varepsilon}\right]_{C^{\gamma}\left(B_{9 / 10}\right)} \leqslant[f]_{C^{\gamma}\left(B_{1}\right)} \tag{4.36}
\end{equation*}
$$

Furthermore, if $y \in B_{3 / 4}^{c}$ and $\xi \in B_{\varepsilon}(y)$, we have that

$$
|\xi| \leqslant|y|+|\xi-y| \leqslant|y|+\varepsilon \leqslant 2|y|
$$

and therefore

$$
\begin{align*}
\int_{B_{3 / 4}^{c}} & \frac{\left|u_{\varepsilon}(y)\right|}{|y|^{n+2 s+k}} d y \leqslant \int_{B_{3 / 4}^{c}}\left[\int_{B_{\varepsilon}(y)} \frac{|u(\xi)|\left|\rho_{\varepsilon}(y-\xi)\right|}{|y|^{n+2 s+k}} d \xi\right] d y \\
& \leqslant C \int_{B_{3 / 4}^{c}}\left[\int_{B_{\varepsilon}(y)} \frac{|u(\xi)|\left|\rho_{\varepsilon}(y-\xi)\right|}{|\xi|^{n+2 s+k}} d \xi\right] d y \leqslant C \int_{B_{1 / 2}^{c}}\left[\int_{\mathbb{R}^{n}} \frac{|u(\xi)|\left|\rho_{\varepsilon}(y-\xi)\right|}{|\xi|^{n+2 s+k}} d y\right] d \xi  \tag{4.37}\\
& =C \int_{B_{1 / 2}^{c}} \frac{|u(\xi)|}{|\xi|^{n+2 s+k}} d \xi=C J_{u, k}
\end{align*}
$$

So we plug (4.36) and (4.37) into (4.35) and we obtain (4.31).

With this we are now in the position of giving the proof of Theorem 1.3:

Proof of Theorem 1.3. We claim that

$$
\begin{equation*}
\|u\|_{C^{\gamma+2 s}\left(B_{1 / 2}\right)} \leqslant C\left([f]_{C^{\gamma}\left(B_{1} ; k\right)}+J_{u, k}\right) \tag{4.38}
\end{equation*}
$$

for some $C>0$. We observe that when $\gamma>k-1$ the claim in (4.38) follows from Corollary 4.5 and (1.12). Hence, we can now focus on the case in which

$$
\begin{equation*}
\gamma<k-1 \tag{4.39}
\end{equation*}
$$

We take $v$ to be a solution of

$$
\begin{equation*}
(-\Delta)^{s} v=f \quad \text { in } B_{1} \tag{4.40}
\end{equation*}
$$

with $v=0$ in $B_{1}^{c}$.
Then, from Proposition 1.1 in [17], we have that

$$
\begin{equation*}
\|v\|_{C^{s}\left(\mathbb{R}^{n}\right)} \leqslant C\|f\|_{L^{\infty}\left(B_{1}\right)} \tag{4.41}
\end{equation*}
$$

for some $C>0$.

Also, from Proposition 4.3,

$$
\begin{equation*}
\|v\|_{C^{\gamma+2 s}\left(B_{1 / 2}\right)} \leqslant C\left([f]_{C^{\gamma}\left(B_{1}\right)}+J_{v, 0}\right) \tag{4.42}
\end{equation*}
$$

Since, from (4.41),

$$
\begin{equation*}
J_{v, 0} \leqslant C\|v\|_{L^{\infty}\left(\mathbb{R}^{n}\right)} \leqslant C\|f\|_{L^{\infty}\left(B_{1}\right)} \tag{4.43}
\end{equation*}
$$

we deduce from (4.42) that

$$
\begin{equation*}
\|v\|_{C^{\gamma+2 s}\left(B_{1 / 2}\right)} \leqslant C\left([f]_{C^{\gamma}\left(B_{1}\right)}+\|f\|_{L^{\infty}\left(B_{1}\right)}\right) . \tag{4.44}
\end{equation*}
$$

Also, from (4.40) and Corollary 3.8, we have that $(-\Delta)^{s} v \stackrel{0}{=} f$ in $B_{1}$.
From this and (1.7), we conclude that $(-\Delta)^{s} v \stackrel{k}{=} f$ in $B_{1}$.
So, we define $w:=u-v$ and we have that $(-\Delta)^{s} w \stackrel{k}{=} 0$ in $B_{1}$. Hence, we take $\bar{\gamma}:=k-1+\varepsilon$, for a fixed, small $\varepsilon>0$, and we are in the position of using Corollary 4.5 (notice indeed that $\bar{\gamma}$ satisfies (4.30)). In this way, we obtain that

$$
\begin{equation*}
\|w\|_{C_{\bar{\gamma}+2 s}\left(B_{1 / 2}\right)} \leqslant C J_{w, k} . \tag{4.45}
\end{equation*}
$$

We also point out that

$$
\begin{equation*}
J_{w, k} \leqslant J_{u, k}+J_{v, k} \leqslant J_{u, k}+C\|f\|_{L^{\infty}\left(B_{1}\right)} \tag{4.46}
\end{equation*}
$$

where (4.43) has been used once again.
Also, $\bar{\gamma}+2 s \geqslant \gamma+2 s$, due to (4.39), and so

$$
\|w\|_{C^{\bar{\gamma}+2 s}\left(B_{1 / 2}\right)} \geqslant\|w\|_{C^{\gamma+2 s}\left(B_{1 / 2}\right)} \geqslant\|u\|_{C^{\gamma+2 s}\left(B_{1 / 2}\right)}-\|v\|_{C^{\gamma+2 s}\left(B_{1 / 2}\right)}
$$

Using this, (4.45) and (4.46), we find

$$
\|u\|_{C^{\gamma+2 s}\left(B_{1 / 2}\right)} \leqslant C\left(\|v\|_{C^{\gamma+2 s}\left(B_{1 / 2}\right)}+J_{u, k}+\|f\|_{L^{\infty}\left(B_{1}\right)}\right)
$$

This and (4.44) imply that

$$
\|u\|_{C^{\gamma+2 s}\left(B_{1 / 2}\right)} \leqslant C\left([f]_{C^{\gamma}\left(B_{1}\right)}+\|f\|_{L^{\infty}\left(B_{1}\right)}+J_{u, k}\right)
$$

Now, since this estimate is valid for $f$ satisfying $(-\Delta)^{s} u \stackrel{k}{=} f$, it must be valid also for $f+P$, for any polynomial $P$ of degree $k-1$ (recall (1.8)). Consequently, we can write

$$
\|u\|_{C^{\gamma+2 s}\left(B_{1 / 2}\right)} \leqslant C \inf \left([f+P]_{C^{\gamma}\left(B_{1}\right)}+\|f+P\|_{L^{\infty}\left(B_{1}\right)}+J_{u, k}\right)
$$

From this and Lemma C.1, it follows that (4.38) holds true, as desired.
We remark that (4.38) is indeed the desired result in (1.13), except that we wish to replace $[f]_{C^{\gamma}\left(B_{1} ; k\right)}$ with $[f]_{C^{\gamma}\left(B_{1} ; \ell\right)}$ and $J_{u, k}$ with $J_{u, \ell}$.
For this, we observe that both $[f]_{C^{\gamma}\left(B_{1} ; j\right)}$ and $J_{u, j}$ are decreasing in $j \in \mathbb{N}$ (up to multiplicative constants). Hence, when $\ell \leqslant k$, then (1.13) follows directly from (4.38).
On the other hand, when $\ell>k$ we see that $(-\Delta)^{s} u \stackrel{\ell}{=} f$ in $B_{1}$, thanks to (1.7). So we can apply (4.38) with $\ell$ replacing $k$, which is the desired result in (1.13).

## 5 Liouville Theorem for divergent fractional Laplacians

By using the Schauder estimates in Theorem 1.3 at any scale, we can now give the proof of Theorem 1.5.

Proof of Theorem 1.5. We first suppose that $(-\Delta)^{s} u \stackrel{k}{=} 0$ in $\mathbb{R}^{n}$ and we show that $u$ is necessarily a polynomial of degree at most $d(k, s)$. For this, we take

$$
\gamma:= \begin{cases}k+2-2 s & \text { if } s \in\left(\frac{1}{2}, 1\right), \\ k+1-2 s & \text { if } s \in\left(0, \frac{1}{2}\right] .\end{cases}
$$

Notice that $\gamma+2 s>k$ and

$$
m:=\lfloor\gamma+2 s\rfloor= \begin{cases}k+2 & \text { if } s \in\left(\frac{1}{2}, 1\right), \\ k+1 & \text { if } s \in\left(0, \frac{1}{2}\right\rfloor .\end{cases}
$$

In particular, we have that

$$
\begin{equation*}
m \geqslant k+2 s \tag{5.1}
\end{equation*}
$$

Now, for any $j \in \mathbb{N}, j \geqslant 1$, we define $u_{j}(x):=u(j x)$. Then, $(-\Delta)^{s} u_{j} \stackrel{k}{=} 0$ in $B_{1}$, hence Theorem 1.3 gives that

$$
\begin{aligned}
& \left\|D^{m} u\right\|_{L^{\infty}\left(B_{j / 2}\right)}=j^{-m}\left\|D^{m} u_{j}\right\|_{L^{\infty}\left(B_{1 / 2}\right)} \leqslant j^{-m}\left\|u_{j}\right\|_{C^{\gamma+2 s}\left(B_{1 / 2}\right)} \leqslant C j^{-m} J_{u_{j}, k} \\
& =C j^{2 s+k-m} \int_{B_{j / 2}^{c}} \frac{|u(y)|}{|y|^{n+2 s+k}} d y .
\end{aligned}
$$

So we can send $j \rightarrow+\infty$ and use (5.1) to see that $D^{m} u$ vanishes identically, hence $u$ is a polynomial of degree less than or equal to $m-1$, as desired.

Now, we prove the converse statement. Namely, we show that

$$
\begin{align*}
& \text { all the polynomials } P \text { of degree at most } d(k, s) \\
& \text { satisfy }(-\Delta)^{s} P \stackrel{k}{=} 0 \text { in } \mathbb{R}^{n} \text {. } \tag{5.2}
\end{align*}
$$

The proof of this is by induction over $k$. If $k=0$, then $d(k, s)=1$ if $s \in\left(\frac{1}{2}, 1\right)$ and $d(k, s)=0$ if $s \in\left(0, \frac{1}{2}\right]$. Hence, if $P$ has degree at most $d(k, s)$, it follows that $P$ is affine if $s \in\left(\frac{1}{2}, 1\right)$ and constant if $s \in\left(0, \frac{1}{2}\right]$, and

$$
\int_{\mathbb{R}^{n}} \frac{|P(y)|}{1+|y|^{n+2 s}} d y<+\infty
$$

In any case, $(-\Delta)^{s} P$ is well defined in the standard sense, and $(-\Delta)^{s} P=0$ in $\mathbb{R}^{n}$. Accordingly, by Corollary 3.8, we have that $(-\Delta)^{s} P \stackrel{0}{=} 0$ in $\mathbb{R}^{n}$.

This is the desired result when $k=0$. Hence, we now suppose recursively that the claim in (5.2) holds true for $k-1$ and we prove it for $k$.

For this, we take a polynomial $P$ with degree at most $d(k, s)$ and, for any fixed $i \in\{1, \ldots, n\}$, we set $Q_{i}:=\partial_{i} P$. Notice that $Q_{i}$ is a polynomial with degree at most $d(k, s)-1=d(k-1, s)$. Therefore, by the inductive hypothesis we know that

$$
\begin{equation*}
(-\Delta)^{s} Q_{i} \stackrel{k-1}{=} 0 \quad \text { in } \mathbb{R}^{n} . \tag{5.3}
\end{equation*}
$$

Furthermore, by Theorem 3.1 and Remark 3.4 (recall also Remark 3.6), we know that, fixed $M>0$, for any large $R>0$,

$$
\begin{equation*}
(-\Delta)^{s}\left(\tau_{R} P\right)=f_{P}+g_{R}+P_{R} \quad \text { in } B_{M} \tag{5.4}
\end{equation*}
$$

where $\tau_{R} \in C_{0}^{\infty}\left(B_{R},[0,1]\right)$ with $\tau_{R}=1$ in $B_{R-1}$ and $\left\|\nabla \tau_{R}\right\|_{L^{\infty}\left(\mathbb{R}^{n}\right)} \leqslant 4, P_{R}$ is a polynomial of degree $k-1$ and

$$
g_{R}(x):=\int_{B_{R-1}^{c}} \frac{\left(\tau_{R}(y)-1\right) P(y) \psi(x, y)}{|y|^{n+2 s+k}} d y
$$

We define

$$
\zeta_{R, i}:=(-\Delta)^{s}\left(\partial_{i} \tau_{R} P\right)
$$

We claim that

$$
\begin{align*}
& \zeta_{R, i}=\tilde{P}_{R, i}+\tilde{\zeta}_{R, i}, \text { where } \tilde{P}_{R, i} \text { is a polynomial of degree } k-2 \\
& \text { and } \tilde{\zeta}_{R, i} \rightarrow 0 \text { in } B_{M} \text { as } R \rightarrow+\infty . \tag{5.5}
\end{align*}
$$

To check this, we observe that

$$
\partial_{i} \tau_{R} P=\tau_{R+1} \partial_{i} \tau_{R} P
$$

Thus, fixed $M$, we can use Theorem 3.1 (with $\tau:=\tau_{R+1}, u:=\partial_{i} \tau_{R} P$ and $k$ replaced by $k-1$ ) and find that, for any $x \in B_{M}$,

$$
\begin{aligned}
(-\Delta)^{s}\left(\partial_{i} \tau_{R} P\right)(x)= & (-\Delta)^{s}\left(\tau_{R+1} \partial_{i} \tau_{R} P\right)(x) \\
= & \tilde{P}_{R, i}(x)+\int_{B_{2 M}} \frac{\left(\partial_{i} \tau_{R} P\right)(x)-\left(\partial_{i} \tau_{R} P\right)(y)}{|x-y|^{n+2 s}} d y+\int_{B_{2 M}^{c}} \frac{\left(\partial_{i} \tau_{R} P\right)(x)}{|x-y|^{n+2 s}} d y \\
& \quad+\int_{B_{2 M}^{c}} \frac{\tau_{R+1}(y)\left(\partial_{i} \tau_{R} P\right)(y) \psi(x, y)}{|y|^{n+2 s+k-1}} d y
\end{aligned}
$$

for some polynomial $\tilde{P}_{R, i}$, which has degree at most $k-2$. Now, for large $R$, the terms supported in $B_{2 M}$ vanish, namely we can write that

$$
(-\Delta)^{s}\left(\partial_{i} \tau_{R} P\right)(x)=\tilde{P}_{R, i}(x)+\int_{B_{R} \backslash B_{R-1}} \frac{\tau_{R+1}(y)\left(\partial_{i} \tau_{R} P\right)(y) \psi(x, y)}{|y|^{n+2 s+k-1}} d y=\tilde{P}_{R, i}(x)+\tilde{\zeta}_{R, i}(x)
$$

with

$$
\tilde{\zeta}_{R, i}(x):=\int_{B_{R} \backslash B_{R-1}} \frac{\tau_{R+1}(y)\left(\partial_{i} \tau_{R} P\right)(y) \psi(x, y)}{|y|^{n+2 s+k-1}} d y
$$

Hence, to prove (5.5), we need to show that

$$
\begin{equation*}
\tilde{\zeta}_{R, i} \rightarrow 0 \quad \text { in } B_{M} \quad \text { as } R \rightarrow+\infty \tag{5.6}
\end{equation*}
$$

To this aim, we recall (3.3) and we compute, for large $R$,

$$
\begin{gathered}
\left|\int_{B_{R} \backslash B_{R-1}} \frac{\tau_{R+1}(y)\left(\partial_{i} \tau_{R} P\right)(y) \psi(x, y)}{|y|^{n+2 s+k-1}} d y\right| \leqslant C \int_{B_{R} \backslash B_{R-1}} \frac{|P(y)|}{|y|^{n+2 s+k-1}} d y \\
\leqslant C \int_{B_{R} \backslash B_{R-1}} \frac{R^{d(k, s)}}{|y|^{n+2 s+k-1}} d y \leqslant C R^{d(k, s)-2 s-k}
\end{gathered}
$$

up to renaming $C$ at any step. The latter quantity is infinitesimal as $R \rightarrow+\infty$, thanks to (1.14). This establishes (5.6), and so (5.5).

Notice also that

$$
\partial_{i}(-\Delta)^{s}\left(\tau_{R} P\right)=(-\Delta)^{s}\left(\partial_{i} \tau_{R} P\right)+(-\Delta)^{s}\left(\tau_{R} \partial_{i} P\right)=(-\Delta)^{s}\left(\partial_{i} \tau_{R} P\right)+(-\Delta)^{s}\left(\tau_{R} Q_{i}\right)
$$

Accordingly, by (5.4) and (5.5), we obtain that, in $B_{M}$,

$$
\begin{equation*}
(-\Delta)^{s}\left(\tau_{R} Q_{i}\right)=\partial_{i}(-\Delta)^{s}\left(\tau_{R} P\right)-(-\Delta)^{s}\left(\partial_{i} \tau_{R} P\right)=\partial_{i} f_{P}+\partial_{i} g_{R}+\partial_{i} P_{R}-\tilde{P}_{R, i}-\tilde{\zeta}_{R, i} \tag{5.7}
\end{equation*}
$$

Notice that, in view of (3.3), we have that $\partial_{i} g_{R} \rightarrow 0$. Also, $\partial_{i} P_{R}$ is a polynomial of degree $k-2$. In consequence of these observations and (5.7), we have that $(-\Delta)^{s} Q_{i} \stackrel{k-1}{=} \partial_{i} f_{P}$ in $B_{M}$. From this, (5.3) and Lemma 1.2, we obtain that there exists a polynomial $Q_{i}^{\star}$ of degree at most $k-2$ such that $\partial_{i} f_{P}=Q_{i}^{\star}$.
This implies that, in $B_{M}$,

$$
\begin{equation*}
f_{P} \text { is a polynomial of degree at most } k-1 . \tag{5.8}
\end{equation*}
$$

On the other hand, from Remark 3.5, we know that $(-\Delta)^{s} P \stackrel{k}{=} f_{P}$ in $B_{M}$. Using this and (5.8), and recalling (1.8), we can write $(-\Delta)^{s} P \stackrel{k}{=} 0$ in $B_{M}$. Since $M>0$ is arbitrary, it follows that $(-\Delta)^{s} P \stackrel{k}{=} 0$ in $\mathbb{R}^{n}$, as desired.

## 6 Stability of divergent fractional Laplacians

The goal of this section is to prove Theorem 1.6, namely that the divergent fractional Laplacian is stable under limits that are compatible with the viscosity setting. For this, we first consider the simpler case in which the functions vanish in $B_{1}$ (the advantage of this setting being that the smoothness assumption in Remark 3.5 is obviously satisfied). The precise result goes as follows:

Lemma 6.1. Let $s \in(0,1)$ and $k \in \mathbb{N}$. Let us consider sequences of functions $v_{m}: \mathbb{R}^{n} \rightarrow \mathbb{R}$ and $g_{m}: B_{1} \rightarrow \mathbb{R}$ such that $v_{m}=0$ in $B_{1}$ and $g_{m}$ is continuous in $B_{1}$, with

$$
\begin{equation*}
\sup _{m \in \mathbb{N}} \int_{\mathbb{R}^{n}} \frac{\left|v_{m}(y)\right|}{1+|y|^{n+2 s+k}} d y<+\infty \tag{6.1}
\end{equation*}
$$

and

$$
\begin{equation*}
(-\Delta)^{s} v_{m} \stackrel{k}{=} g_{m} \quad \text { in } B_{1} \tag{6.2}
\end{equation*}
$$

Assume that $g_{m} \rightarrow g$ a.e. in $B_{1}$ as $m \rightarrow+\infty$, for some function $g: B_{1} \rightarrow \mathbb{R}$.
Suppose also that

$$
\begin{equation*}
\lim _{m \rightarrow+\infty} \int_{B_{1}^{c}} \frac{v_{m}(y) \varphi(y)}{|y|^{n+2 s+k}} d y=\int_{B_{1}^{c}} \frac{v(y) \varphi(y)}{|y|^{n+2 s+k}} d y \tag{6.3}
\end{equation*}
$$

for any $\varphi \in L^{\infty}\left(B_{1}^{c}\right)$, for some function $v: \mathbb{R}^{n} \rightarrow \mathbb{R}$ with $v=0$ in $B_{1}$.
Then, it holds that

$$
\begin{equation*}
(-\Delta)^{s} v \stackrel{k}{=} g \quad \text { in } B_{1} \tag{6.4}
\end{equation*}
$$

Proof. We can use Remark 3.5 and (3.14) and find that, for any $x \in B_{1}$,

$$
(-\Delta)^{s} v_{m}(x) \stackrel{k}{=} f_{v_{m}}(x)=-\int_{B_{2} \backslash B_{1}} \frac{v_{m}(y)}{|x-y|^{n+2 s}} d y+\int_{B_{2}^{c}} \frac{v_{m}(y) \psi(x, y)}{|y|^{n+2 s+k}} d y
$$

From this, (6.2) and Lemma 1.2, we obtain that

$$
g_{m}(x)=-\int_{B_{2} \backslash B_{1}} \frac{v_{m}(y)}{|x-y|^{n+2 s}} d y+\int_{B_{2}^{c}} \frac{v_{m}(y) \psi(x, y)}{|y|^{n+2 s+k}} d y+P_{m}(x)
$$

where $P_{m}$ is a polynomial of degree at most $k-1$.

We stress that, fixed $x \in B_{1}$,

$$
\inf _{y \in B_{2} \backslash B_{1}}|x-y| \geqslant \inf _{y \in B_{2} \backslash B_{1}}|y|-|x|=1-|x|,
$$

and so the function $y \mapsto \frac{1}{|x-y|^{n+2 s}}$ belongs to $L^{\infty}\left(B_{2} \backslash B_{1}\right)$. Thus, in view of (3.3) and (6.3), we have that, for any fixed $x \in B_{1}$,

$$
\lim _{m \rightarrow+\infty} P_{m}(x)=g(x)+\int_{B_{2} \backslash B_{1}} \frac{v(y)}{|x-y|^{n+2 s}} d y-\int_{B_{2}^{c}} \frac{v(y) \psi(x, y)}{|y|^{n+2 s+k}} d y
$$

This and Lemma 2.1 imply that there exists a polynomial $P$ of degree at most $k-1$ such that

$$
\begin{equation*}
P(x)=g(x)+\int_{B_{2} \backslash B_{1}} \frac{v(y)}{|x-y|^{n+2 s}} d y-\int_{B_{2}^{c}} \frac{v(y) \psi(x, y)}{|y|^{n+2 s+k}} d y \tag{6.5}
\end{equation*}
$$

Also, using (6.3) with $\varphi:=\chi_{(0,+\infty)}(v(y))$, we see that

$$
\int_{B_{1}^{c}} \frac{v_{+}(y)}{|y|^{n+2 s+k}} d y=\lim _{m \rightarrow+\infty} \int_{B_{1}^{c}} \frac{v_{m}(y) \chi_{(0,+\infty)}(v(y))}{|y|^{n+2 s+k}} d y \leqslant \sup _{m \in \mathbb{N}} \int_{B_{1}^{c}} \frac{\left|v_{m}(y)\right|}{|y|^{n+2 s+k}} d y
$$

which is finite, thanks to (6.1). With a similar computation on $v_{-}$, we thus conclude that

$$
\int_{B_{1}^{c}} \frac{|v(y)|}{|y|^{n+2 s+k}} d y<+\infty
$$

So, we can use Remark 3.5 on $v$ and obtain

$$
(-\Delta)^{s} v(x) \stackrel{k}{=} f_{v}(x)=-\int_{B_{2} \backslash B_{1}} \frac{v(y)}{|x-y|^{n+2 s}} d y+\int_{B_{2}^{c}} \frac{v(y) \psi(x, y)}{|y|^{n+2 s+k}} d y
$$

From this, (1.8) and (6.5), we deduce that $(-\Delta)^{s} v(x) \stackrel{k}{=} g$, as desired.

With this preliminary result, we can complete the proof of the stability theorem, by arguing as follows:

Proof of Theorem 1.6. We set

$$
\begin{aligned}
& v_{m}:=\left(1-\chi_{1}\right) u_{m}, \quad w_{m}:=\chi_{1} u_{m} \\
& v:=\left(1-\chi_{1}\right) u \quad \text { and } \quad w:=\chi_{1} u .
\end{aligned}
$$

By construction, $v_{m} \rightarrow v$ and $w_{m} \rightarrow w$ locally uniformly in $B_{1}$, as $m \rightarrow+\infty$.
In light of (1.15) and Corollary 3.10 (used here with $\rho:=1$ ), we know that

$$
\begin{equation*}
(-\Delta)^{s} w_{m}=\bar{f}_{m}+\int_{B_{2} \backslash B_{1}} \frac{u_{m}(y)}{|x-y|^{n+2 s}} d y-\int_{B_{2}^{c}} \frac{u_{m}(y) \psi(x, y)}{|y|^{n+2 s+k}} d y=: h_{m} \tag{6.6}
\end{equation*}
$$

in $B_{1}$ in the sense of viscosity, where

$$
\begin{equation*}
\bar{f}_{m}:=f_{m}+P_{m} \tag{6.7}
\end{equation*}
$$

and $P_{m}$ is a polynomial of degree at most $k-1$. Thus, from Corollary 3.8 and (1.7) we obtain that

$$
(-\Delta)^{s} w_{m} \stackrel{k}{=} \bar{f}_{m}+\int_{B_{2} \backslash B_{1}} \frac{u_{m}(y)}{|x-y|^{n+2 s}} d y-\int_{B_{2}^{c}} \frac{u_{m}(y) \psi(x, y)}{|y|^{n+2 s+k}} d y
$$

Hence, in view of (1.8), we obtain that

$$
(-\Delta)^{s} w_{m} \stackrel{k}{=} f_{m}+\int_{B_{2} \backslash B_{1}} \frac{u_{m}(y)}{|x-y|^{n+2 s}} d y-\int_{B_{2}^{c}} \frac{u_{m}(y) \psi(x, y)}{|y|^{n+2 s+k}} d y
$$

As a consequence, for any $x \in B_{1}$,

$$
\begin{align*}
& (-\Delta)^{s} v_{m}(x)=(-\Delta)^{s} u_{m}(x)-(-\Delta)^{s} w_{m}(x) \\
& \quad \stackrel{k}{=} f_{m}(x)-\left(f_{m}(x)+\int_{B_{2} \backslash B_{1}} \frac{u_{m}(y)}{|x-y|^{n+2 s}} d y-\int_{B_{2}^{c}} \frac{u_{m}(y) \psi(x, y)}{|y|^{n+2 s+k}} d y\right)  \tag{6.8}\\
& \quad=-\int_{B_{2} \backslash B_{1}} \frac{u_{m}(y)}{|x-y|^{n+2 s}} d y+\int_{B_{2}^{c}} \frac{u_{m}(y) \psi(x, y)}{|y|^{n+2 s+k}} d y=: g_{m}(x) .
\end{align*}
$$

Let also

$$
g(x):=-\int_{B_{2} \backslash B_{1}} \frac{u(y)}{|x-y|^{n+2 s}} d y+\int_{B_{2}^{c}} \frac{u(y) \psi(x, y)}{|y|^{n+2 s+k}} d y
$$

Notice that, by (3.3) and (1.17), we have that $g_{m} \rightarrow g$ pointwise in $B_{1}$.
Also, fixed any $\rho \in(0,1)$, by (3.3),

$$
\begin{aligned}
\sup _{x \in B_{\rho}}\left|\nabla g_{m}(x)\right| & \leqslant \sup _{x \in B_{\rho}} C\left(\int_{B_{2} \backslash B_{1}} \frac{\left|u_{m}(y)\right|}{|x-y|^{n+2 s+1}} d y+\int_{B_{2}^{c}} \frac{\left|u_{m}(y)\right||\nabla \psi(x, y)|}{|y|^{n+2 s+k}} d y\right) \\
& \leqslant C\left(\int_{B_{2} \backslash B_{1}} \frac{\left|u_{m}(y)\right|}{(1-\rho)^{n+2 s+1}} d y+\int_{B_{2}^{c}} \frac{\left|u_{m}(y)\right|}{|y|^{n+2 s+k}} d y\right)
\end{aligned}
$$

which is bounded uniformly in $m$, thanks to (1.16). Accordingly, by the Theorem of Ascoli,

$$
\begin{equation*}
g_{m} \rightarrow g \text { locally uniformly in } B_{1} . \tag{6.9}
\end{equation*}
$$

Thus, from (6.8) and Lemma 6.1, we conclude that

$$
\begin{equation*}
(-\Delta)^{s} v \stackrel{k}{=} g \quad \text { in } B_{1} \tag{6.10}
\end{equation*}
$$

Now we prove that

$$
\begin{equation*}
(-\Delta)^{s} w \stackrel{k}{=} f-g \quad \text { in } B_{1} \tag{6.11}
\end{equation*}
$$

For this, we take $\varphi \in C_{0}^{\infty}\left(B_{1}\right)$. We let $U \subseteq B_{1}$ be the support of $\varphi$ and we fix $\varepsilon>0$ suitably small (also in dependence of $U$ and $\left.B_{1}\right)$. We take $\rho \in C_{0}^{\infty}\left(B_{1}\right)$ and $\rho_{\varepsilon}(x):=\varepsilon^{-n} \rho(x / \varepsilon)$. We consider the convolutions $w_{m, \varepsilon}:=w_{m} * \rho_{\varepsilon}$ and $h_{m, \varepsilon}:=h_{m} * \rho_{\varepsilon}$. Notice that $w_{m, \varepsilon}$ is smooth and compactly supported in $B_{11 / 10}$. Then (see e.g. formula (3.2) in [19]) we have that $(-\Delta)^{s} w_{m, \varepsilon}=h_{m, \varepsilon}$ in $U$ in the smooth sense. Therefore we can write that

$$
\begin{aligned}
\int_{U} h_{m, \varepsilon} \varphi=\int_{U}(-\Delta)^{s} w_{m, \varepsilon} \varphi & =\int_{\mathbb{R}^{n}}(-\Delta)^{s} w_{m, \varepsilon} \varphi \\
=\int_{\mathbb{R}^{n}} w_{m, \varepsilon}(-\Delta)^{s} \varphi & =\int_{B_{11 / 10}} w_{m, \varepsilon}(-\Delta)^{s} \varphi .
\end{aligned}
$$

Hence, for any $m^{\prime}, m \in \mathbb{N}$,

$$
\left|\int_{U}\left(h_{m, \varepsilon}-h_{m^{\prime}, \varepsilon}\right) \varphi\right| \leqslant \int_{B_{11 / 10}}\left|w_{m, \varepsilon}-w_{m^{\prime}, \varepsilon}\right|\left|(-\Delta)^{s} \varphi\right| .
$$

Since $w_{m} \in L^{1}\left(\mathbb{R}^{n}\right)$, by sending $\varepsilon \rightarrow 0$, we thus obtain that

$$
\begin{align*}
& \left|\int_{U}\left(h_{m}-h_{m^{\prime}}\right) \varphi\right| \leqslant \int_{B_{11 / 10}}\left|w_{m}-w_{m^{\prime}}\right|\left|(-\Delta)^{s} \varphi\right|  \tag{6.12}\\
& \quad=\int_{B_{1}}\left|w_{m}-w_{m^{\prime}}\right|\left|(-\Delta)^{s} \varphi\right| \leqslant C\left\|w_{m}-w_{m^{\prime}}\right\|_{L^{1}\left(B_{1}\right)}\|\varphi\|_{C^{2}\left(\mathbb{R}^{n}\right)}
\end{align*}
$$

From the convergence of $u_{m}$ in $L^{1}\left(B_{1}\right)$, we also have that

$$
\begin{equation*}
\lim _{m \rightarrow+\infty}\left\|w_{m}-\chi_{1} u\right\|_{L^{1}\left(B_{1}\right)}=\lim _{m \rightarrow+\infty}\left\|u_{m}-u\right\|_{L^{1}\left(B_{1}\right)}=0 \tag{6.13}
\end{equation*}
$$

From (6.12) and (6.13), it follows that $h_{m}$ is a Cauchy sequence in the norm $\|\cdot\|_{\star}$ introduced in (2.2). From the uniform convergence, we also know that $f_{m}$ is a Cauchy sequence in the norm $\|\cdot\|_{\star}$. Moreover, by (6.9), we have that $g_{m}$ is also a Cauchy sequence in the norm $\|\cdot\|_{\star}$.
Since

$$
\begin{equation*}
P_{m}=g_{m}+h_{m}-f_{m} \tag{6.14}
\end{equation*}
$$

these observations imply that $P_{m}$ is also a Cauchy sequence in the norm $\|\cdot\|_{\star}$ and so, in consequence of Lemma 2.2, we obtain that $P_{m}$ converges uniformly to some polynomial $P$ of degree at most $k-1$ in $U$, for any $U \Subset B_{1}$.
This and (6.7) imply that $\bar{f}_{m}$ converges locally uniformly in $B_{1}$. Hence, writing $h_{m}=\bar{f}_{m}-g_{m}$, we conclude that $h_{m}$ also converges locally uniformly in $B_{1}$ to some function $h$.
We are therefore in the position to use Lemma 5 in [5] and deduce from (6.6) that $(-\Delta)^{s} w=h$ in $B_{1}$ in the sense of viscosity. Hence, by Corollary 3.8, we can write $(-\Delta)^{s} w \stackrel{0}{=} h$ in $B_{1}$.

Passing to the limit in (6.14), we obtain that

$$
P=g+h-f
$$

and so $(-\Delta)^{s} w \stackrel{0}{=} f-g+P$ in $B_{1}$.
From this, (1.7) and (1.8), we conclude that (6.11) holds true, as desired.
Now, by (6.10) and (6.11), we obtain that

$$
(-\Delta)^{s} u=(-\Delta)^{s} v+(-\Delta)^{s} w \stackrel{k}{=} g+(f-g)=f
$$

as desired.

A useful consequence of Theorem 1.6 is also a stability result under convolution, which goes as follows:
Proposition 6.2. Let $k \in \mathbb{N}, s \in(0,1)$. Assume that $u$ and $f$ are continuous functions in $B_{1}$, with

$$
\begin{equation*}
\int_{\mathbb{R}^{n}} \frac{|u(y)|}{1+|y|^{n+2 s+k}}<+\infty \tag{6.15}
\end{equation*}
$$

and

$$
(-\Delta)^{s} u \stackrel{k}{=} f \quad \text { in } B_{1}
$$

Let $\varepsilon>0, \rho \in C_{0}^{\infty}\left(B_{1}\right)$ and $\rho_{\varepsilon}(x):=\varepsilon^{-n} \rho(x / \varepsilon)$. Let $u_{\varepsilon}:=u * \rho_{\varepsilon}$ and $f_{\varepsilon}:=f * \rho_{\varepsilon}$. Then

$$
(-\Delta)^{s} u_{\varepsilon} \stackrel{k}{=} f_{\varepsilon} \quad \text { in } B_{99 / 100}
$$

as long as $\varepsilon$ is small enough.

Proof. We know that

$$
(-\Delta)^{s}\left(\chi_{R} u\right)=f+\eta_{R}+P_{R}
$$

in $B_{1}$, in the viscosity sense, with $\eta_{R} \rightarrow 0$ in $B_{1}$ as $R \rightarrow+\infty$ and $P_{R}$ is a polynomial of degree at most $k-1$. As a matter of fact, by choosing the "optimal representative" in Lemma 3.11, we can also suppose that

$$
\begin{equation*}
\eta_{R} \rightarrow 0 \text { uniformly in } B_{1} . \tag{6.16}
\end{equation*}
$$

Let also

$$
v_{R, \varepsilon}(x):=\left(\chi_{R} u\right) * \rho_{\varepsilon}(x)
$$

Hence (see e.g. formula (3.2) in [19]) in $B_{99 / 100}$ we have that

$$
(-\Delta)^{s} v_{R, \varepsilon}=f_{\varepsilon}+\eta_{R} * \rho_{\varepsilon}+P_{R} * \rho_{\varepsilon}
$$

Hence, by Corollary 3.8,

$$
(-\Delta)^{s} v_{R, \varepsilon} \stackrel{0}{=} f_{\varepsilon}+\eta_{R} * \rho_{\varepsilon}+P_{R} * \rho_{\varepsilon}
$$

So, by (1.7), we have that

$$
\begin{equation*}
(-\Delta)^{s} v_{R, \varepsilon} \stackrel{k}{=} f_{\varepsilon}+\eta_{R} * \rho_{\varepsilon}+P_{R} * \rho_{\varepsilon} \tag{6.17}
\end{equation*}
$$

Now we check that

$$
\begin{equation*}
P_{R} * \rho_{\varepsilon} \text { is a polynomial of degree at most } k-1 \tag{6.18}
\end{equation*}
$$

For this, we can reduce to the case of monomials, and compute, for any $\alpha \in \mathbb{N}^{n}$ with $|\alpha| \leqslant k-1$, that

$$
x^{\alpha} * \rho_{\varepsilon}=\int_{\mathbb{R}^{n}}(x-y)^{\alpha} \rho_{\varepsilon}(y) d y=\sum_{\beta \leqslant \alpha}\binom{\alpha}{\beta} x^{\beta} \int_{\mathbb{R}^{n}}(-y)^{\alpha-\beta} \rho_{\varepsilon}(y) d y
$$

which is a polynomial of degree at most $k-1$. This observation proves (6.18).
Then, from (1.8), (6.17) and (6.18), we conclude that

$$
\begin{equation*}
(-\Delta)^{s} v_{R, \varepsilon} \stackrel{k}{=} f_{\varepsilon}+\eta_{R} * \rho_{\varepsilon} \tag{6.19}
\end{equation*}
$$

Our objective is now to send $R \rightarrow+\infty$ and use the stability result in Theorem 1.6. To this aim, we define

$$
v_{\varepsilon}^{\star}(x):=\int_{\mathbb{R}^{n}}|u(y)| \rho_{\varepsilon}(x-y) d y
$$

We observe that

$$
\begin{equation*}
\int_{B_{99 / 100}^{c}} \frac{v_{\varepsilon}^{\star}(y)}{|y|^{n+2 s+k}} d y<+\infty \tag{6.20}
\end{equation*}
$$

see (4.37). Moreover, we have that

$$
\begin{equation*}
v_{R, \varepsilon}(x) \leqslant \int_{\mathbb{R}^{n}}\left|\left(\chi_{R} u\right)(y)\right| \rho_{\varepsilon}(x-y) d y \leqslant v_{\varepsilon}^{\star}(x) \tag{6.21}
\end{equation*}
$$

In addition

$$
\left|\left(\chi_{R} u\right)(y)\right| \rho_{\varepsilon}(x-y) \leqslant \varepsilon^{-n}|u(y)| \chi_{B_{\varepsilon}(x)}(y) \leqslant(|x|+1)^{n+2 s+k} \frac{|u(y)|}{\varepsilon^{n}|y|^{n+2 s+k}}
$$

This and (6.15) allow us to use the Dominated Convergence Theorem and take the limit as $R \rightarrow+\infty$ (for a fixed $\varepsilon>0$ ). In this way, we see that, for any fixed $x \in \mathbb{R}^{n}$,

$$
\lim _{R \rightarrow+\infty} v_{R, \varepsilon}(x)=\int_{\mathbb{R}^{n}} \lim _{R \rightarrow+\infty}\left(\chi_{R} u\right)(y) \rho_{\varepsilon}(x-y) d y=u_{\varepsilon}(x)
$$

This, (6.20) and (6.21) allow us to use again the Dominated Convergence Theorem to take the limit as $R \rightarrow+\infty$ and obtain that

$$
\begin{equation*}
\lim _{R \rightarrow+\infty} \int_{B_{99 / 100}^{c}} \frac{\left|v_{R, \varepsilon}(x)-u_{\varepsilon}(x)\right|}{|x|^{n+2 s+k}} d x=0 . \tag{6.22}
\end{equation*}
$$

Also, $v_{R, \varepsilon} \rightarrow u_{\varepsilon}$ and, in view of (6.16), $f_{\varepsilon}+\eta_{R} * \rho_{\varepsilon} \rightarrow f_{\varepsilon}$ locally uniformly in $B_{99 / 100}$ as $R \rightarrow+\infty$. From this, (6.21) and (6.22), we can exploit Theorem 1.6 and deduce from (6.19) that

$$
(-\Delta)^{s} u_{\varepsilon} \stackrel{k}{=} f_{\varepsilon}
$$

in $B_{99 / 100}$, as desired.

## A Appendix A. Summary of the finite differences method

We recall here the classical method of the finite differences (or incremental quotients). Given $\omega \in \mathbb{R}^{n}$, we consider the shift operator acting on functions, namely $T_{\omega} f(x):=f(x+\omega)$. Of course, if $\omega=0$, this operator boils down to the identity operator, which will be denoted by $I$.

For any $h \in(0,1)$ and $\omega \in S^{n-1}$, we set

$$
D_{h}^{\omega}:=T_{h \omega}-I
$$

Then, for any $\left(\omega_{1}, \ldots, \omega_{d}\right) \in\left(S^{n-1}\right)^{d}$ and any $h \in(0,1)$ we consider the finite difference operator

$$
D_{h}^{\left(\omega_{1}, \ldots, \omega_{d}\right)}:=D_{h}^{\omega_{1}} \ldots D_{h}^{\omega_{d}}
$$

Notice that, since the shift operators commute with themselves, we also have that $D_{h}^{\left(\omega_{1}, \ldots, \omega_{d}\right)}=D_{h}^{\omega_{d}} \ldots D_{h}^{\omega_{1}}$.
The finite differences of order $d$ approximate the derivatives of order $d$ (after a renormalization of size $h^{d}$ ), as pointed out in the following result:
Lemma A.1. There exists $\xi: \mathbb{R}^{n} \rightarrow[0,1]^{d}$ such that

$$
h^{-d} D_{h}^{\left(\omega_{1}, \ldots, \omega_{d}\right)} f(x)=\sum_{1 \leqslant i_{1}, \ldots i_{d} \leqslant n} \frac{\partial^{d} f}{\partial x_{i_{1}} \ldots \partial x_{i_{d}}}\left(x+h \xi_{1}(x) \omega_{1}+\cdots+h \xi_{d}(x) \omega_{d}\right) \omega_{1 i_{1}} \ldots \omega_{d i_{d}}
$$

Proof. We argue by induction over $d$. When $d=1$, we use the Mean Value Theorem and we see that

$$
D_{h}^{\omega_{1}} f(x)=f\left(x+h \omega_{1}\right)-f(x)=\nabla f\left(x+h \xi_{1}(x) \omega_{1}\right) \cdot\left(h \omega_{1}\right)
$$

for some $\xi_{1}: \mathbb{R}^{n} \rightarrow[0,1]$.
This is the desired claim when $d=1$. Hence, we now suppose that the claim is true for $d-1$ and we prove it for $d$. For this, we assume that

$$
\begin{aligned}
& h^{1-d} D_{h}^{\left(\omega_{1}, \ldots, \omega_{d-1}\right)} f(x) \\
& \sum_{1 \leqslant i_{1}, \ldots i_{d-1} \leqslant n} \frac{\partial^{d-1} f}{\partial x_{i_{1}} \ldots \partial x_{i_{d-1}}}\left(x+h \xi_{1}(x) \omega_{1}+\cdots+h \xi_{d-1}(x) \omega_{d-1}\right) \omega_{1 i_{1}} \ldots \omega_{d-1 i_{d-1}}
\end{aligned}
$$

and we use the Mean Value Theorem to see that

$$
\begin{array}{r}
\frac{\partial^{d-1} f}{\partial x_{i_{1}} \ldots \partial x_{i_{d-1}}}\left(x+h \xi_{1}(x) \omega_{1}+\cdots+h \xi_{d-1}(x) \omega_{d-1}+h \omega_{d}\right) \\
-\frac{\partial^{d-1} f}{\partial x_{i_{1}} \ldots \partial x_{i_{d-1}}}\left(x+h \xi_{1}(x) \omega_{1}+\cdots+h \xi_{d-1}(x) \omega_{d-1}\right) \\
=\sum_{i_{d}=1}^{n} \frac{\partial^{d} f}{\partial x_{i_{1}} \ldots \partial x_{i_{d}}}\left(x+h \xi_{1}(x) \omega_{1}+\cdots+h \xi_{d}(x) \omega_{d}\right)\left(h \omega_{d i_{d}}\right),
\end{array}
$$

for some $\xi_{d}: \mathbb{R}^{n} \rightarrow[0,1]$. These observations easily imply the desired claim.

We also give the following integration by parts formula:
Lemma A.2. Let $f \in L^{1}\left(\mathbb{R}^{n}\right)$ and $g \in L^{\infty}\left(\mathbb{R}^{n}\right)$. Then

$$
\int_{\mathbb{R}^{n}} D_{h}^{\left(\omega_{1}, \ldots, \omega_{d}\right)} f(x) g(x) d x=\int_{\mathbb{R}^{n}} f(x) D_{h}^{\left(-\omega_{1}, \ldots,-\omega_{d}\right)} g(x) d x
$$

Proof. We argue by induction on $d$. If $d=1$, then

$$
\begin{array}{rl}
\int_{\mathbb{R}^{n}} D_{h}^{\omega_{1}} & f(x) g(x) d x=\int_{\mathbb{R}^{n}} f\left(x+h \omega_{1}\right) g(x) d x-\int_{\mathbb{R}^{n}} f(x) g(x) d x \\
\quad=\int_{\mathbb{R}^{n}} f(x) g\left(x-h \omega_{1}\right) d x-\int_{\mathbb{R}^{n}} f(x) g(x) d x=\int_{\mathbb{R}^{n}} f(x) D_{h}^{-\omega_{1}} g(x) d x
\end{array}
$$

as desired.
For the inductive step, we compute recursively that

$$
\begin{aligned}
& \int_{\mathbb{R}^{n}} D_{h}^{\left(\omega_{1}, \ldots, \omega_{d}\right)} f(x) g(x) d x=\int_{\mathbb{R}^{n}} D_{h}^{\left(\omega_{1}, \ldots, \omega_{d-1}\right)} D_{h}^{\omega_{d}} f(x) g(x) d x \\
&=\int_{\mathbb{R}^{n}} D_{h}^{\omega_{d}} f(x) D_{h}^{\left(-\omega_{1}, \ldots,-\omega_{d-1}\right)} g(x) d x=\int_{\mathbb{R}^{n}} f(x) D_{h}^{-\omega_{d}} D_{h}^{\left(-\omega_{1}, \ldots,-\omega_{d-1}\right)} g(x) d x \\
&=\int_{\mathbb{R}^{n}} f(x) D_{h}^{\left(-\omega_{1}, \ldots,-\omega_{d}\right)} g(x) d x
\end{aligned}
$$

which is the desired result.

## B Appendix B. Proof of Lemmata 2.1 and 2.2

One proof of Lemma 2.1 can be done by exploiting the finite incremental quotients of order $d$ (as discussed in Appendix A), to show that $D^{d} F$ vanishes.

Another simple, and more geometric, argument is based on the idea that polynomials are, after all, a finite dimensional space, and finite dimensional spaces are closed, with respect to any equivalent norm. The details are the following.

Proof of Lemma 2.1. Up to a translation, we suppose that

$$
\begin{equation*}
0 \in U \tag{B.1}
\end{equation*}
$$

Also, without loss of generality, we can suppose that

$$
\begin{equation*}
m \text { in the statement of Lemma } 2.1 \text { is larger than } d \text {. } \tag{B.2}
\end{equation*}
$$

We define $N$ to be the number of multi-indices $\mu \in \mathbb{N}^{n}$ for which $|\mu|:=\mu_{1}+\cdots+\mu_{n} \leqslant d-1$. In this way, we can endow $\mathbb{R}^{N}$ with an ordering and consider the map $T$ from $\mathbb{R}^{N}$ to the space of polynomials of degree at most $d-1$, which is given by

$$
\mathbb{R}^{N} \ni a=\left\{a_{\mu}\right\}_{|\mu| \leqslant d-1} \longmapsto T(a):=\sum_{|\mu| \leqslant d-1} a_{\mu} x^{\mu}
$$

We fix distinct points $q_{1}, \ldots, q_{d} \in U \subseteq \mathbb{R}^{n}$. Then, on $\mathbb{R}^{N}$, we consider the two norms

$$
\begin{aligned}
\|a\|_{1} & :=\sum_{i=1}^{d}\left|T(a)\left(q_{i}\right)\right| \\
\text { and } \quad\|a\|_{2} & :=\|T(a)\|_{C^{m}(U)}
\end{aligned}
$$

It is interesting to remark that $\|\cdot\|_{1}$ is indeed a norm. For this, suppose that $\|a\|_{1}=0$. Then, it follows that $T(a)\left(q_{i}\right)=$ 0 for any $i=1, \ldots, d$, hence the polynomial $T(a)$, which has degree at most $d-1$, vanishes on $d$ different points, and so it has to be zero, which in turn implies that $a=0$.

We also write

$$
P^{(j)}=\sum_{|\mu| \leqslant d-1} a_{\mu}^{(j)} x^{\mu}
$$

with $a^{(j)}=\left\{a_{\mu}^{(j)}\right\}_{|\mu| \leqslant d-1}$. We remark that

$$
T\left(a^{(j)}\right)=P^{(j)}
$$

Therefore, given $\eta>0$, if $j, j^{\prime} \in \mathbb{N}$ are sufficiently large (possibly in dependence of $\eta$ ), we have that

$$
\left\|a^{(j)}-a^{\left(j^{\prime}\right)}\right\|_{1} \leqslant \eta
$$

thanks to (2.1), and so $a^{(j)}$ is a Cauchy sequence in $\mathbb{R}^{N}$, with respect to the norm $\|\cdot\|_{1}$.
From the equivalence of the norms in $\mathbb{R}^{N}$, it thus follows that $a^{(j)}$ is a Cauchy sequence in $\mathbb{R}^{N}$, with respect to the norm $\|\cdot\|_{2}$. Consequently, given $\eta>0$, if $j, j^{\prime} \in \mathbb{N}$ are sufficiently large,

$$
\eta \geqslant\left\|a^{(j)}-a^{\left(j^{\prime}\right)}\right\|_{2}=\left\|P^{(j)}-P^{\left(j^{\prime}\right)}\right\|_{C^{m}(U)}
$$

Therefore, we have that $P^{(j)}$ is a sequence of functions that is of Cauchy type in $C^{m}(U)$, and so it converges to some function $P^{\star}$ in $C^{m}(U)$.
In particular, the sequence $P^{(j)}$ is bounded in $C^{m}(U)$. From this and (B.2) we obtain that, for any $\mu \in \mathbb{N}^{n}$ with $|\mu| \leqslant d-1$,

$$
\sup _{j \in \mathbb{N}}\left\|P^{(j)}\right\|_{C^{m}(U)} \geqslant \sup _{j \in \mathbb{N}}\left\|D^{\mu} P^{(j)}\right\|_{L^{\infty}(U)} \geqslant\left|D^{\mu} P^{(j)}(0)\right|=\mu!\left|a_{\mu}^{(j)}\right|
$$

thanks to (B.1). Hence, for any $\mu \in \mathbb{N}^{n}$ with $|\mu| \leqslant d-1$, up to a subsequence, we have that $a_{\mu}^{(j)} \rightarrow a_{\mu}^{\star}$ as $j \rightarrow+\infty$, for some $a_{\mu}^{\star} \in \mathbb{R}$. Thus, possibly passing to a subsequence and using (2.1), we have that, for any $x \in U$,

$$
F(x)=\lim _{j \rightarrow+\infty} P^{(j)}(x)=\lim _{j \rightarrow+\infty} \sum_{|\mu| \leqslant d-1} a_{\mu}^{(j)} x^{\mu}=\sum_{|\mu| \leqslant d-1} a_{\mu}^{\star} x^{\mu}
$$

that is the desired result.

Proof of Lemma 2.2. We use the setting given by the proof of Lemma 2.1, and we define the norm in $\mathbb{R}^{N}$ given, for $a=\left\{a_{\mu}\right\}_{|\mu| \leqslant d-1}$, by

$$
\|a\|_{3}:=\sup _{\substack{\varphi \in C_{0}^{2}(U) \\\|\varphi\|_{C^{2}(U)} \leqslant 1}} \int_{U} \sum_{|\mu| \leqslant d-1} a_{\mu} x^{\mu} \varphi(x) d x
$$

We see that $a_{\mu}^{(j)}$ is a Cauchy sequence with respect to the norm $\|\cdot\|_{3}$ and so it converges to some $a^{\star}=$ $\left\{a_{\mu}^{\star}\right\}_{|\mu| \leqslant d-1} \in \mathbb{R}^{N}$, with respect to the norm $\|\cdot\|_{3}$.
From the equivalence of the norms in $\mathbb{R}^{N}$, we conclude that

$$
0=\lim _{j \rightarrow+\infty}\left\|a_{\mu}^{(j)}-a_{\mu}^{\star}\right\|_{2}=\lim _{j \rightarrow+\infty}\left\|P^{(j)}-T\left(a^{\star}\right)\right\|_{C^{m}(U)}
$$

which implies the desired result.

## C Appendix C. Reabsorbing lower order norms

The scope of this appendix is to show the following result:
Lemma C.1. Let $k \in \mathbb{N}, \gamma \in(0,+\infty) \backslash \mathbb{N}$, with

$$
\begin{equation*}
\lfloor\gamma\rfloor \leqslant k-1 \tag{C.1}
\end{equation*}
$$

and $f \in C^{\gamma}\left(B_{1}\right)$. Then

$$
\inf \|f-P\|_{L^{\infty}\left(B_{1}\right)}+[f-P]_{C^{\gamma}\left(B_{1}\right)} \leqslant C[f]_{C^{\gamma}\left(B_{1} ; k\right)},
$$

where the inf is taken over all the polynomials $P$ of degree $k-1$, and $C>0$ depends on $n$, $\gamma$ and $k$.

Proof. We write $\gamma=m+\theta$, with $m:=\lfloor\gamma\rfloor \in \mathbb{N}$ and $\theta \in(0,1)$. We set

$$
\begin{aligned}
T_{f}(x) & :=\sum_{|\alpha| \leqslant m} \frac{\partial^{\alpha} f(0)}{\alpha!} x^{\alpha}, \\
G_{f, \alpha}(x) & :=m \int_{0}^{1}(1-t)^{m-1}\left(\partial^{\alpha} f(t x)-\partial^{\alpha} f(0)\right) d t \\
\text { and } \quad R_{f}(x) & :=\sum_{|\alpha|=m} G_{f, \alpha}(x) \frac{x^{\alpha}}{\alpha!} .
\end{aligned}
$$

We observe that $T_{f}, G_{f, \alpha}$ and $R_{f}$ are linear with respect to $f$ and, in particular,

$$
R_{f+g}=R_{f}+R_{g}
$$

for any functions $f$ and $g$.
Notice also that, if $|\alpha|=m$,

$$
\left[G_{f, \alpha}\right]_{C^{\theta}\left(B_{1}\right)} \leqslant C\left[D^{m} f\right]_{C^{\theta}\left(B_{1}\right)} \leqslant C[f]_{C^{\gamma}\left(B_{1}\right)}
$$

Moreover, a Taylor expansion of $f$ gives that

$$
f=T_{f}+R_{f} .
$$

Fix also a generic polynomial $P$ of degree at most $k-1$ of the form

$$
\begin{array}{ll} 
& P(x)=P_{1}(x)+P_{2}(x), \\
\text { with } & P_{1}(x):=\sum_{|\alpha| \leqslant m} p_{\alpha} x^{\alpha} \\
\text { and } & P_{2}(x):=\sum_{|\alpha| \in[m+1, k-1]} p_{\alpha} x^{\alpha} .
\end{array}
$$

Then, using the inf notation in the statement of Lemma C.1,

$$
\begin{align*}
\inf _{P}\|f-P\|_{L^{\infty}\left(B_{1}\right)}+[f-P]_{C^{\gamma}\left(B_{1}\right)} & =\inf _{P_{1}, P_{2}}\left\|f-P_{1}-P_{2}\right\|_{L^{\infty}\left(B_{1}\right)}+\left[f-P_{1}-P_{2}\right]_{C^{\gamma}\left(B_{1}\right)} \\
& \leqslant \inf _{P_{2}}\left\|f-T_{f}-P_{2}\right\|_{L^{\infty}\left(B_{1}\right)}+\left[f-T_{f}-P_{2}\right]_{C^{\gamma}\left(B_{1}\right)} \\
& =\inf _{P_{2}}\left\|R_{f}-P_{2}\right\|_{L^{\infty}\left(B_{1}\right)}+\left[R_{f}-P_{2}\right]_{C^{\gamma}\left(B_{1}\right)}  \tag{С.2}\\
& =\inf _{P_{2}}\left\|R_{f-P_{2}}\right\|_{L^{\infty}\left(B_{1}\right)}+\left[R_{f-P_{2}}\right]_{C^{\gamma}\left(B_{1}\right)} .
\end{align*}
$$

Now, we observe that, for any function $g$ and any $x \in B_{1}$,

$$
[g]_{C^{\gamma}\left(B_{1}\right)} \geqslant \frac{\left|D^{m} g(x)-D^{m} g(0)\right|}{|x|^{\theta}} \geqslant\left|D^{m} g(x)-D^{m} g(0)\right|
$$

Since $D^{m} R_{h}(0)=0$ for any function $h$, we can apply the latter estimate with $g:=R_{f-P_{2}}$ and find that

$$
\left[R_{f-P_{2}}\right]_{C^{\gamma}\left(B_{1}\right)} \geqslant\left|D^{m} R_{f-P_{2}}(x)\right|
$$

and thus, taking supremum over $x \in B_{1}$,

$$
\begin{equation*}
\left[R_{f-P_{2}}\right]_{C^{\gamma}\left(B_{1}\right)} \geqslant\left\|D^{m} R_{f-P_{2}}\right\|_{L^{\infty}\left(B_{1}\right)} . \tag{C.3}
\end{equation*}
$$

Now we observe that, for any function $g$ with $g(0)=0$ one has that

$$
\|g\|_{L^{\infty}\left(B_{1}\right)}=\sup _{x \in B_{1}}|g(x)|=\sup _{x \in B_{1}}|g(x)-g(0)| \leqslant\|\nabla g\|_{L^{\infty}\left(B_{1}\right)}
$$

Since, for any function $h$, it holds that $D^{j} R_{h}(0)=0$ for any $j \in\{0, \ldots, m-1\}$, we can apply this estimate repeatedly and find that

$$
\left\|R_{h}\right\|_{L^{\infty}\left(B_{1}\right)} \leqslant C\left\|\nabla R_{h}\right\|_{L^{\infty}\left(B_{1}\right)} \leqslant \ldots \leqslant C\left\|D^{m} R_{h}\right\|_{L^{\infty}\left(B_{1}\right)}
$$

up to renaming $C>0$.
From this and (C.3), we obtain

$$
\left\|R_{f-P_{2}}\right\|_{L^{\infty}\left(B_{1}\right)} \leqslant C\left[R_{f-P_{2}}\right]_{C^{\gamma}\left(B_{1}\right)}
$$

So, we insert this information into (C.2) and we obtain

$$
\begin{align*}
\inf _{P} \| f & -P \|_{L^{\infty}\left(B_{1}\right)}+[f-P]_{C^{\gamma}\left(B_{1}\right)} \leqslant 2 \inf _{P_{2}}\left[R_{f-P_{2}}\right]_{C^{\gamma}\left(B_{1}\right)}  \tag{C.4}\\
& =2 \inf _{P_{2}}\left[R_{f}-R_{P_{2}}\right]_{C^{\gamma}\left(B_{1}\right)}=2 \inf _{P_{2}}\left[R_{f}-P_{2}\right]_{C^{\gamma}\left(B_{1}\right)}
\end{align*}
$$

We also remark that, since $\gamma>m$, it holds that

$$
\left[h-\bar{P}-P_{2}\right]_{C^{\gamma}\left(B_{1}\right)}=\left[h-P_{2}\right]_{C^{\gamma}\left(B_{1}\right)}
$$

for any function $h$ and any polynomial $\bar{P}$ of degree at most $m$, hence (C.4) gives that

$$
\inf _{P}\|f-P\|_{L^{\infty}\left(B_{1}\right)}+[f-P]_{C^{\gamma}\left(B_{1}\right)} \leqslant 2 \inf _{P_{2}}\left[R_{f}-\bar{P}-P_{2}\right]_{C^{\gamma}\left(B_{1}\right)}
$$

We choose now $\bar{P}:=\bar{Q}-T_{f}$, where $\bar{Q}$ is a generic polynomial of degree at most $m$. In this way, we obtain

$$
\inf _{P}\|f-P\|_{L^{\infty}\left(B_{1}\right)}+[f-P]_{C^{\gamma}\left(B_{1}\right)} \leqslant 2 \inf _{P_{2}}\left[R_{f}+T_{f}-\bar{Q}-P_{2}\right]_{C^{\gamma}\left(B_{1}\right)}=2 \inf _{P_{2}}\left[f-\bar{Q}-P_{2}\right]_{C^{\gamma}\left(B_{1}\right)}
$$

Since $\bar{Q}+P_{2}$ is now the generic polynomial of degree at most $k-1$ (notice indeed that $m \leqslant k-1$, in view of (C.1)), we obtain

$$
\inf _{P}\|f-P\|_{L^{\infty}\left(B_{1}\right)}+[f-P]_{C^{\gamma}\left(B_{1}\right)} \leqslant 2 \inf _{P}[f-P]_{C^{\gamma}\left(B_{1}\right)},
$$

as desired (recall (1.11)).

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[^1]:    ${ }^{1}$ For short, in the rest of the paper, the principal value notation in (1.1) will be tacitly understood and not repeated.

[^2]:    ${ }^{2}$ As customary, polynomials of negative degree are set to be zero.
    ${ }^{3}$ The choice of the particular cutoff in (1.3) has been made for the sake of concreteness. Other choices are indeed possible as well.

[^3]:    ${ }^{4}$ Throughout this paper, we will use the standard notation for the complementary set. Namely, given $X \subseteq \mathbb{R}^{n}$ we set $X^{c}:=\mathbb{R}^{n} \backslash X$.

[^4]:    ${ }^{5}$ We use the standard notation for the integer part of a real number. Namely, given $\varrho \in \mathbb{R}$, we denote by $\lfloor\varrho\rfloor:=\max \{m \in \mathbb{Z}$ s.t. $m \leqslant$ $\varrho\}$.

