# Weierstraß-Institut <br> für Angewandte Analysis und Stochastik 

im Forschungsverbund Berlin e.V.

Preprint
ISSN 0946 - 8633

# Stationary solutions to an energy model for semiconductor devices where the equations are defined on different domains 

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submitted: 23rd October 2006
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Preprint No. 1173
Berlin 2006


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#### Abstract

We discuss a stationary energy model from semiconductor modeling. We accept the more realistic assumption that the continuity equations for electrons and holes have to be considered only in a subdomain $\Omega_{0}$ of the domain of definition $\Omega$ of the energy balance equation and of the Poisson equation. Here $\Omega_{0}$ corresponds to the region of semiconducting material, $\Omega \backslash \Omega_{0}$ represents passive layers. Metals serving as contacts are modelled by Dirichlet boundary conditions.

We prove a local existence and uniqueness result for the two-dimensional stationary energy model. For this purpose we derive a $W^{1, p}$-regularity result for solutions of systems of elliptic equations with different regions of definition and use the Implicit Function Theorem.


## 1 Stationary energy models for semiconductor devices

Semiconductor devices are heterostructures consisting of various materials (different semiconducting materials, passive layers and metals as contacts, for example). A typical situation is shown in Fig. 1. Metals used as contacts are substituted by Dirichlet boundary conditions on a part $\Gamma_{D}$ of the boundary of the semiconducting material. In the domain $\Omega$ involving the passive layer $\left(\Omega_{1}\right)$ and semiconducting materials $\left(\Omega_{0}\right)$ we have to formulate a Poisson equation for the electrostatic potential and an energy balance equation with boundary conditions on $\Gamma:=\partial \Omega=\overline{\Gamma_{D}} \cup \overline{\Gamma_{N 0}} \cup \overline{\Gamma_{N 1}}$, where the subscripts $D$ and $N$ indicate the parts with Dirichlet and Neumann boundary conditions, respectively. Continuity equations for electrons and holes have to be taken into account only in the part $\Omega_{0}$, and here we must formulate boundary conditions on $\Gamma_{0}:=\partial \Omega_{0}=\overline{\Gamma_{D}} \cup \overline{\Gamma_{N 01}} \cup \overline{\Gamma_{N 0}}$. Especially on $\Gamma_{N 01}$, which corresponds to the interface between semiconducting material and passive layers, no-flux conditions have to be formulated. In this paper we restrict our considerations to the case that the Dirichlet parts of $\Gamma$ and $\Gamma_{0}$ coincide.
Let $T$ and $\varphi$ denote the lattice temperature and the electrostatic potential. Then the state equations for electrons and holes are given by the following expressions

$$
n=N(\cdot, T) F\left(\frac{\zeta_{n}+\varphi-E_{n}(\cdot, T)}{T}\right), p=P(\cdot, T) F\left(\frac{\zeta_{p}-\varphi+E_{p}(\cdot, T)}{T}\right) \quad \text { in } \Omega_{0},
$$

where $n$ and $p$ are the electron and hole densities, $N$ and $P$ are the effective densities of state, $\zeta_{n}$ and $\zeta_{p}$ are the electrochemical potentials, $E_{n}$ and $E_{p}$ are the energy band edges, respectively. The function $F$ arises from a distribution function (e.g. $F(y)=\mathrm{e}^{y}$ in the case of Boltzmann statistics or $F(y)=\mathcal{F}_{1 / 2}(y)$ in the case of Fermi-Dirac statistics). The electrostatic potential $\varphi$ fulfils the Poisson equation

$$
-\nabla \cdot(\varepsilon \nabla \varphi)=\left\{\begin{array}{ll}
f-n+p & \text { in } \Omega_{0}  \tag{1.1}\\
f & \text { in } \Omega_{1}
\end{array} .\right.
$$



Figure 1: Schematic picture of a modelled semiconductor device

Here $\varepsilon$ is the dielectric permittivity and $f$ is a given doping profile. Mixed boundary conditions on $\Gamma$ have to be prescribed. Next, we assume that the particle flux densities $j_{n}$, $j_{p}$ and the total energy flux density $j_{e}$ have the form (see e.g. Albinus, Gajewski, Hünlich [1])

$$
\begin{align*}
j_{n}= & -\left(\sigma_{n}(x, n, p, T)+\sigma_{n p}(x, n, p, T)\right)\left(\nabla \zeta_{n}+P_{n} \nabla T\right) \\
& -\sigma_{n p}(x, n, p, T)\left(\nabla \zeta_{p}+P_{p} \nabla T\right), \\
j_{p}= & -\sigma_{n p}(x, n, p, T)\left(\nabla \zeta_{n}+P_{n} \nabla T\right) \\
& -\left(\sigma_{p}(x, n, p, T)+\sigma_{n p}(x, n, p, T)\right)\left(\nabla \zeta_{p}+P_{p} \nabla T\right),  \tag{1.2}\\
j_{e}= & \begin{cases}-\kappa(x, n, p, T) \nabla T+\sum_{i=n, p}\left(\zeta_{i}+P_{i} T\right) j_{i}, & x \in \Omega_{0} \\
-\widetilde{\kappa}(x, T) \nabla T, & x \in \Omega_{1}\end{cases}
\end{align*}
$$

with conductivities $\kappa, \widetilde{\kappa}, \sigma_{n}, \sigma_{p}>0, \sigma_{n p} \geq 0$ and transported entropies $P_{n}, P_{p}$. The particle fluxes $j_{n}, j_{p}$ only occur in the domain $\Omega_{0}$ of the semiconducting material. A stationary energy model besides the Poisson equation (1.1) should contain two continuity equations for the densities $n$ and $p$ and a balance of the total energy

$$
\begin{equation*}
\nabla \cdot j_{n}=-R, \quad \nabla \cdot j_{p}=-R \quad \text { on } \Omega_{0}, \quad \nabla \cdot j_{e}=0 \quad \text { on } \Omega, \tag{1.3}
\end{equation*}
$$

where the net recombination rate $R$ has the form

$$
R=r(x, n, p, T)\left(\mathrm{e}^{\left(\zeta_{n}+\zeta_{p}\right) / T}-1\right) \quad \text { in } \Omega_{0}
$$

Suitable boundary conditions for $\zeta_{n}, \zeta_{p}$ resp. $j_{n}, j_{p}$ on $\Gamma_{0}$ should to be added. The energy balance equation $\nabla \cdot j_{e}=0$ with the corresponding flux term from (1.2) should be valid in the whole domain $\Omega$ and boundary conditions must be formulated on $\Gamma$.

In (1.2) on $\Omega_{0}$ we used the fluxes $\left(j_{n}, j_{p}, j_{e}\right)$ and the generalized forces $\left(\nabla \zeta_{n}, \nabla \zeta_{p}, \nabla T\right)$. In this setting Onsager relations are not valid. But this can be achieved by choosing other
generalized forces, namely $\left(\nabla\left[\zeta_{n} / T\right], \nabla\left[\zeta_{p} / T\right], \nabla[-1 / T]\right)$. Then

$$
\left(\begin{array}{c}
j_{n}  \tag{1.4}\\
j_{p} \\
j_{e}
\end{array}\right)=-\left(\begin{array}{lll}
\left(\sigma_{n}+\sigma_{n p}\right) T & \sigma_{n p} T & \rho_{n} \\
\sigma_{n p} T & \left(\sigma_{p}+\sigma_{n p}\right) T & \rho_{p} \\
\rho_{n} & \rho_{p} & \kappa T^{2}+\rho_{e}
\end{array}\right)\left(\begin{array}{c}
\nabla\left[\zeta_{n} / T\right] \\
\nabla\left[\zeta_{p} / T\right] \\
\nabla[-1 / T]
\end{array}\right) \quad \text { on } \Omega_{0}
$$

where

$$
\binom{\rho_{n}}{\rho_{p}}=\left(\begin{array}{ll}
\left(\sigma_{n}+\sigma_{n p}\right) T & \sigma_{n p} T \\
\sigma_{n p} T & \left(\sigma_{p}+\sigma_{n p}\right) T
\end{array}\right)\binom{\zeta_{n}+P_{n} T}{\zeta_{p}+P_{p} T}, \rho_{e}=\rho_{n}\left(\zeta_{n}+P_{n} T\right)+\rho_{p}\left(\zeta_{p}+P_{p} T\right) .
$$

Now the matrix in (1.4) is symmetric and positive definite for non-degenerated states.
Based on the foregoing arguments we use the variables

$$
z=\left(z_{1}, z_{2}, z_{3}, z_{4}\right)=\left(\frac{\zeta_{n}}{\left.T\right|_{\Omega_{0}}}, \frac{\zeta_{p}}{\left.T\right|_{\Omega_{0}}},-\frac{1}{T}, \varphi\right),
$$

where $z_{3}$ and $z_{4}$ live on $\Omega$ and $z_{1}$ and $z_{2}$ are defined on $\Omega_{0}$ only. With suitable functions $H_{n}, H_{p}$ we formulate the state equations on $\Omega_{0}$ in these new variables

$$
\begin{aligned}
& n(x)=N(x, T) F\left(\frac{\zeta_{n}+\varphi-E_{n}}{T}\right)=H_{n}(x, z), \\
& p(x)=P(x, T) F\left(\frac{\zeta_{p}-\varphi+E_{p}}{T}\right)=H_{p}(x, z) .
\end{aligned}
$$

Also the rate of generation-recombination of electrons and holes R can be expressed in the new variables

$$
R=r(x, n, p, T)\left(\mathrm{e}^{\left(\zeta_{n}+\zeta_{p}\right) / T}-1\right)=r\left(x, H_{n}(z), H_{p}(z),-1 / z_{3}\right)\left(\mathrm{e}^{z_{1}+z_{2}}-1\right)=R(x, z) .
$$

In summary, a stationary energy model for semiconductor devices can be written with suitable coefficient functions $a_{i k}(x, z), a_{i k}: \Omega_{0} \times \mathbb{R}^{2} \times(-\infty, 0) \times \mathbb{R} \rightarrow \mathbb{R}, i, k=1, \ldots, 3$, $\widetilde{a}_{33}\left(x, z_{3}\right), \widetilde{a}_{33}: \Omega_{1} \times(-\infty, 0) \rightarrow \mathbb{R}_{+}$and $\varepsilon(x), \varepsilon: \Omega \rightarrow \mathbb{R}_{+}$as

$$
-\nabla \cdot\left(\begin{array}{llll}
a_{11}(z) & a_{12}(z) & a_{13}(z) & 0  \tag{1.5}\\
a_{21}(z) & a_{22}(z) & a_{23}(z) & 0 \\
a_{31}(z) & a_{32}(z) & a_{33}(z) & 0 \\
0 & 0 & 0 & \varepsilon
\end{array}\right)\left(\begin{array}{l}
\nabla z_{1} \\
\nabla z_{2} \\
\nabla z_{3} \\
\nabla z_{4}
\end{array}\right)=\left(\begin{array}{l}
-R(z) \\
-R(z) \\
0 \\
f-H_{n}(z)+H_{p}(z)
\end{array}\right) \quad \text { on } \Omega_{0}
$$

and

$$
-\nabla \cdot\left(\begin{array}{ll}
\widetilde{a}_{33}\left(z_{3}\right) & 0  \tag{1.6}\\
0 & \varepsilon
\end{array}\right)\binom{\nabla z_{3}}{\nabla z_{4}}=\binom{0}{f} \quad \text { on } \Omega_{1}
$$

Here we have omitted the additional argument $x$ of the coefficient functions. We formulate the boundary conditions in terms of $z$ and the generalized forces $\nabla z$

$$
\begin{align*}
z_{i}=z_{i}^{D}, i=1, \ldots, 4, & \text { on } \Gamma_{D}, \\
\nu \cdot \sum_{k=1,2,3} a_{i k}(x, z) \nabla z_{k}=g_{i}^{N 0}, i=1,2,3, \nu \cdot\left(\varepsilon \nabla z_{4}\right)=g_{4}^{N 0} & \text { on } \Gamma_{N 0}, \\
\nu \cdot \widetilde{a}_{33}\left(z_{3}\right)=g_{3}^{N 1}, \nu \cdot\left(\varepsilon \nabla z_{4}\right)=g_{4}^{N 1} & \text { on } \Gamma_{N 1},  \tag{1.7}\\
\nu \cdot \sum_{k=1,2,3} a_{i k}(x, z) \nabla z_{k}=0, i=1,2, & \text { on } \Gamma_{N 01} .
\end{align*}
$$

Remark 1.1 Let us mention that for the energy model introduced above the $3 \times 3$-matrix $\left(a_{i k}(x, z)\right)$ for $x \in \Omega_{0}$ is symmetric and possesses the property that for each compact subset $K \subset \mathbb{R}^{2} \times(-\infty, 0) \times \mathbb{R}$ there exists a constant $a_{K}>0$ such that

$$
\begin{equation*}
\sum_{i, k=1,2,3} a_{i k}(x, z) \zeta_{i} \zeta_{k} \geq a_{K}\|t\|_{\mathbb{R}^{3}}^{2}, \quad x \in \Omega_{0}, \quad z \in K, \quad \zeta \in \mathbb{R}^{3} . \tag{1.8}
\end{equation*}
$$

If no electron-hole scattering is involved in the model (this means $\sigma_{n p} \equiv 0$ ), then the relations $a_{12}(x, z)=a_{21}(x, z)=0$ are fulfilled.

## 2 Assumptions

Definition 2.1 Let $V=\mathbb{R}^{2} \times(-\infty, 0) \times \mathbb{R}$. We say that a function $b: \Omega_{0} \times V \rightarrow \mathbb{R}$ is of the class $\left(\mathrm{D}_{0}\right)$ if it fulfils the following properties:
$z \mapsto b(x, z)$ is continuously differentiable for almost all $x \in \Omega_{0}$,
$x \mapsto b(x, z)$ is measurable for all $z \in V$.
For every compact subset $K \subset V$ there exists an $c_{K}>0$ such that $|b(x, z)| \leq c_{K}$ and $\left\|\partial_{z} b(x, z)\right\| \leq c_{K}$ for all $z \in K$ and almost all $x \in \Omega_{0}$.

For every compact subset $K \subset V$ and $\epsilon>0$ there exists a $\delta>0$ such that for all $z, \bar{z} \in K$ holds $|z-\bar{z}|<\delta \Rightarrow|b(x, z)-b(x, \bar{z})|<\epsilon$ and $\left|\partial_{z} b(x, z)-\partial_{z} b(x, \bar{z})\right|<\epsilon$ for almost all $x \in \Omega_{0}$.

We say, a function $b: \Omega_{1} \times V_{1} \rightarrow \mathbb{R}$ is of the class $\left(\mathrm{D}_{1}\right)$ if in the previous definition $V$ is substituted by $V_{1}=(-\infty, 0)$ and $\Omega_{0}$ is replaced by $\Omega_{1}$.

For the analytical investigations of (1.5), (1.6), (1.7) we formulate the following general assumptions:
$\Omega_{i}$ is a bounded Lipschitzian domain in $\mathbb{R}^{2}, \Gamma_{i}:=\partial \Omega_{i}, i=0,1$,
$\Omega_{0} \cap \Omega_{1}=\emptyset, \Gamma_{N 01} \subset \Gamma_{0} \cap \Gamma_{1}$,
$\Omega=: \Omega_{0} \cup \Omega_{1} \cup \Gamma_{N 01}$ is a bounded Lipschitzian domain in $\mathbb{R}^{2}, \Gamma:=\partial \Omega$,
$\Gamma_{N 0}, \Gamma_{N 01}, \Gamma_{D}$ are disjoint open subsets of $\Gamma_{0}, \operatorname{mes} \Gamma_{D}>0$,
$\Gamma_{0 N}:=\Gamma_{N 0} \cup \Gamma_{N 01} \cup\left(\overline{\Gamma_{N 0}} \cap \overline{\Gamma_{N 01}}\right)$ is open in $\Gamma_{0}$,
$\Gamma_{0}=\Gamma_{0 N} \cup \Gamma_{D} \cup\left(\overline{\Gamma_{0 N}} \cap \overline{\Gamma_{D}}\right), \overline{\Gamma_{0 N}} \cap \overline{\Gamma_{D}}$ consists of finitely many points,
$\Gamma_{N 0}, \Gamma_{N 1}, \Gamma_{D}$ are disjoint open subsets of $\Gamma$,
$\Gamma_{N}:=\Gamma_{N 0} \cup \Gamma_{N 1} \cup\left(\overline{\Gamma_{N 0}} \cap \overline{\Gamma_{N 1}}\right)$ is open in $\Gamma$,
$\Gamma=\Gamma_{N} \cup \Gamma_{D} \cup\left(\overline{\Gamma_{N}} \cap \overline{\Gamma_{D}}\right), \overline{\Gamma_{N}} \cap \overline{\Gamma_{D}}$ consists of finitely many points.
(A2) The functions $a_{i k}=a_{k i}: \Omega_{0} \times V \rightarrow \mathbb{R}$ are of the class $\left(\mathrm{D}_{0}\right), i, k=1,2,3$.
For every compact subset $K \subset V$ there exists an $a_{K}>0$ such that
$\sum_{i, k=1}^{3} a_{i k}(x, z) \xi_{i} \xi_{k} \geq a_{K}\|\xi\|^{2}$ for all $z \in K$, all $\xi \in \mathbb{R}^{3}$ and f.a.a. $x \in \Omega_{0}$.
The function $\widetilde{a}_{33}: \Omega_{1} \times V_{1} \rightarrow \mathbb{R}_{+}$is of the class $\left(\mathrm{D}_{1}\right)$.
For every $k>1$ there exists an $\widetilde{a}_{k}>0$ such that $\widetilde{a}_{33}(x, z) \geq \widetilde{a}_{k}$ for all $z \in[-k,-1 / k]$ and f.a.a. $x \in \Omega_{1}$.
(A3) $\varepsilon \in L^{\infty}(\Omega), 0<\varepsilon_{0} \leq \varepsilon(x) \leq \varepsilon^{0}<\infty$ a.e. in $\Omega$.
(A4) The functions $H_{i}: \Omega_{0} \times V \rightarrow \mathbb{R}_{+}, i=n, p$, are of the class $\left(\mathrm{D}_{0}\right)$, let $h_{0}=H_{n}-H_{p}: \Omega_{0} \times V \rightarrow \mathbb{R}, h_{0}\left(x, z_{1}, z_{2}, z_{3}, \cdot\right)$ is monotonic increasing for all $\left(z_{1}, \ldots, z_{4}\right) \in \mathbb{R}^{2} \times(-\infty, 0) \times \mathbb{R}$ and f.a.a. $x \in \Omega_{0}$.
$\left|h_{0}\left(x, z_{1}, \ldots, z_{4}\right)\right| \leq c_{k} \mathrm{e}^{c\left|z_{4}\right|}$ for all $\left(z_{1}, z_{2}, z_{3}\right) \in[-k, k]^{2} \times[-k,-1 / k]$,
$z_{4} \in \mathbb{R}$ and f.a.a. $x \in \Omega_{0}$.
(A5) $\quad R(x, z)=\widetilde{r}(x, z)\left(\mathrm{e}^{z_{1}+z_{2}}-1\right)$, where $\widetilde{r}: \Omega_{0} \times V \rightarrow \mathbb{R}_{+}$is of the class $\left(\mathrm{D}_{0}\right)$.
The data $z_{i}^{D}, g_{i}^{N 0}, g_{i}^{N 1}$ and $f$ in the system (1.5), (1.6), (1.7) are assumed to have at least the following properties. There exists a $p>2$, functions $z_{1}^{D}, z_{2}^{D} \in W^{1, p}\left(\Omega_{0}\right)$ and functions $z_{3}^{D}, z_{4}^{D} \in W^{1, p}(\Omega)$, such that $\left.z_{j}^{D}\right|_{\Gamma_{D}}=z_{j}^{D}, j=1, \ldots, 4$, and $z_{3}^{D}<0$ in $\Omega$. Moreover we suppose that $g_{i}^{N 0} \in L^{\infty}\left(\Gamma_{N 0}\right), i=1, \ldots, 4, g_{i}^{N 1} \in L^{\infty}\left(\Gamma_{N 1}\right), i=3,4$, and $f \in L^{\infty}(\Omega)$.

## 3 Weak formulation

In abbreviation we set

$$
G_{0}=\Omega_{0} \cup \Gamma_{0 N}, \quad G=\Omega \cup \Gamma_{N}
$$

Due to (A1), $G_{0}$ and $G$ are regular in the sense of Gröger [9]. In our analytical investigations we introduce the following names for the needed function spaces. Let $s \in[1, \infty)$,
$1 / s+1 / s^{\prime}=1$, then we define the spaces

$$
\begin{aligned}
X_{s} & =\left(W_{0}^{1, s}\left(G_{0}\right)\right)^{2} \times\left(W_{0}^{1, s}(G)\right)^{2}, \\
X_{s}^{*} & =\left(W^{-1, s^{\prime}}\left(G_{0}\right)\right)^{2} \times\left(W^{-1, s^{\prime}}(G)\right)^{2} \\
W_{s} & =\left(W^{1, s}\left(\Omega_{0}\right)\right)^{2} \times\left(W^{1, s}(\Omega)\right)^{2}, \\
Y_{\Omega_{0}}^{s} & =\left(L^{s}\left(\Omega_{0}\right)\right)^{3}, \quad Y_{\Omega}^{s}=\left(L^{s}(\Omega)\right)^{3}, \\
\mathcal{L}^{s} & =\left(Y_{\Omega_{0}}^{s}\right)^{2} \times\left(Y_{\Omega}^{s}\right)^{2}
\end{aligned}
$$

with the norms

$$
\begin{aligned}
& \|w\|_{W_{s}^{s}}^{s}=\left\|w_{1}\right\|_{W^{1, s}\left(\Omega_{0}\right)}^{s}+\left\|w_{2}\right\|_{W^{1, s}\left(\Omega_{0}\right)}^{s}+\left\|w_{3}\right\|_{W^{1, s}(\Omega)}^{s}+\left\|w_{4}\right\|_{W^{1, s}(\Omega)}^{s}, \quad w \in W_{s}, \\
& \|y\|_{\mathcal{L}^{s}}^{s}=\left\|y_{1}\right\|_{Y_{\Omega_{0}}^{s}}^{s}+\left\|y_{2}\right\|_{Y_{\Omega_{0}}^{s}}^{s}+\left\|y_{3}\right\|_{Y_{\Omega}^{s}}^{s}+\left\|y_{4}\right\|_{Y_{\Omega}^{s}}^{s}, \quad y \in \mathcal{L}^{s}, \\
& \|w\|_{W^{1, s}(\Omega)}^{s}=\int_{\Omega}\left(w^{2}+w_{x_{1}}^{2}+w_{x_{2}}^{2}\right)^{s / 2} \mathrm{~d} x, \quad w \in W^{1, s}(\Omega), \\
& \|y\|_{Y_{\Omega}^{s}}^{s}=\int_{\Omega}\left(\left(y^{1}\right)^{2}+\left(y^{2}\right)^{2}+\left(y^{3}\right)^{2}\right)^{s / 2} \mathrm{~d} x, \quad y=\left(y^{1}, y^{2}, y^{3}\right) \in Y_{\Omega}^{s}
\end{aligned}
$$

and similar for the function spaces working on $\Omega_{0}$. Note, that $W^{1, s}(\Omega)$ and $Y_{\Omega}^{s}$ are equipped with the norms used by Gröger [9].

We define the vectors

$$
z^{D}=\left(z_{1}^{D}, \ldots, z_{4}^{D}\right), \quad g=\left(g_{1}^{N 0}, \ldots, g_{4}^{N 0}, g_{3}^{N 1}, g_{4}^{N 1}\right), \quad w=\left(z^{D}, g, f\right),
$$

and we are looking for solutions of $(1.5),(1.6),(1.7)$ in the form

$$
z=Z+z^{D},
$$

where $z^{D}$ corresponds to a function fulfilling the Dirichlet boundary conditions and $Z$ represents the homogeneous part of the solution. Moreover, we use the notation $\mathcal{H}$ for the space of data, namely

$$
\mathcal{H}=W_{p} \times L^{\infty}\left(\Gamma_{N 0}\right)^{4} \times L^{\infty}\left(\Gamma_{N 1}\right)^{2} \times L^{\infty}(\Omega)
$$

Definition 3.1 Let $q \in(2, p]$ and $\tau>1$. We define subsets $M_{q, \tau} \subset X_{q} \times W_{p}$ as follows,

$$
\begin{align*}
M_{q, \tau}=\{ & \left(Z, z^{D}\right) \in X_{q} \times W_{p}:\left|Z_{i}+z_{i}^{D}\right|<\tau, i=1,2, \text { on } \Omega_{0}, \\
& \left.-\tau<Z_{3}+z_{3}^{D}<-\frac{1}{\tau}, \quad\left|Z_{4}+z_{4}^{D}\right|<\tau \text { on } \Omega\right\} . \tag{3.9}
\end{align*}
$$

Because of the continuous embedding of $W^{1, p}, W^{1, q}$ in the space of continuous functions the set $M_{q, \tau}$ is open in $X_{q} \times W_{p}$. Clearly, if $q_{2}>q_{1}$ then $M_{q_{2}, \tau} \subset M_{q_{1}, \tau}$. Moreover, we have $M_{q, \tau_{1}} \subset M_{q, \tau_{2}}$ for $\tau_{1}<\tau_{2}$.

We define the operator $F_{q, \tau}: M_{q, \tau} \times L^{\infty}\left(\Gamma_{N 0}\right)^{4} \times L^{\infty}\left(\Gamma_{N 1}\right)^{2} \times L^{\infty}(\Omega) \rightarrow X_{q^{\prime}}^{*}$ by

$$
\begin{aligned}
\left\langle F_{q, \tau}(Z, w), \psi\right\rangle_{X_{q^{\prime}}} & =\int_{\Omega_{0}}\left\{\sum_{i, k=1}^{3} a_{i k}(\cdot, z) \nabla z_{k} \cdot \nabla \psi_{i}+\varepsilon \nabla z_{4} \cdot \nabla \psi_{4}\right\} \mathrm{d} x \\
& +\int_{\Omega_{0}}\left\{R(\cdot, z)\left(\psi_{1}+\psi_{2}\right)+h_{0}(\cdot, z) \psi_{4}\right\} \mathrm{d} x-\int_{\Omega} f \psi_{4} \mathrm{~d} x \\
& +\int_{\Omega_{1}}\left\{\widetilde{a}_{33}\left(\cdot, z_{3}\right) \nabla z_{3} \cdot \nabla \psi_{3}+\varepsilon \nabla z_{4} \cdot \nabla \psi_{4}\right\} \mathrm{d} x \\
& -\int_{\Gamma_{N 0}} \sum_{i=1}^{4} g_{i}^{N 0} \psi_{i} \mathrm{~d} \Gamma-\int_{\Gamma_{N 1}} \sum_{i=3}^{4} g_{i}^{N 1} \psi_{i} \mathrm{~d} \Gamma, \quad \psi \in X_{q^{\prime}} .
\end{aligned}
$$

Here $q^{\prime}=q /(q-1)$ denotes the dual exponent of $q$. Using this notation a weak formulation of the system (1.5), (1.6), (1.7) is

## Problem (P):

Find $(q, \tau, Z, w)$ such that $q \in(2, p], \tau>1,(Z, w) \in X_{q} \times \mathcal{H}$,

$$
F_{q, \tau}(Z, w)=0, \quad\left(Z, z^{D}\right) \in M_{q, \tau} .
$$

Obviously, if $(q, \tau, Z, w)$ is a solution to (P) then $(\widetilde{q}, \widetilde{\tau}, Z, w)$ with $\widetilde{q} \in(2, q]$ and $\widetilde{\tau} \geq \tau$ is a solution to ( P ), too.

## 4 Analytical results

Lemma 4.1 We assume (A1) - (A5). For all parameters $\tau>1$, all exponents $q \in$ (2, $p]$ the operator $F_{q, \tau}: M_{q, \tau} \times L^{\infty}\left(\Gamma_{N 0}\right)^{4} \times L^{\infty}\left(\Gamma_{N 1}\right)^{2} \times L^{\infty}(\Omega) \rightarrow X_{q^{\prime}}^{*}$ is continuously differentiable.

Proof. Let $q \in(2, p]$ and $\tau>1$ be fixed. We split up the operator $F_{q, \tau}$ into a sum $F_{q, \tau}=$ $\sum_{i, k=1}^{3} A^{i k}+\widetilde{A}^{33}+A^{44}+A^{l}-B$, where $A^{i j}, \widetilde{A}^{33}, A^{44}, A^{l}: M_{q, \tau} \rightarrow X_{q^{\prime}}^{*}, B: L^{\infty}\left(\Gamma_{N 0}\right)^{4} \times$ $L^{\infty}\left(\Gamma_{N 1}\right)^{2} \times L^{\infty}(\Omega) \rightarrow X_{q^{\prime}}^{*}$,

$$
\begin{aligned}
\left\langle A^{i k}\left(Z, z^{D}\right), \psi\right\rangle_{X_{q^{\prime}}} & =\int_{\Omega_{0}} a_{i k}(\cdot, z) \nabla\left(Z_{k}+z_{k}^{D}\right) \cdot \nabla \psi_{i} \mathrm{~d} x, \quad i, k=1,2,3, \\
\left\langle\widetilde{A}^{33}\left(Z, z^{D}\right), \psi\right\rangle_{X_{q^{\prime}}} & =\int_{\Omega_{1}} \widetilde{a}_{33}\left(\cdot, z_{3}\right) \nabla\left(Z_{3}+z_{3}^{D}\right) \cdot \nabla \psi_{3} \mathrm{~d} x, \\
\left\langle A^{44}\left(Z, z^{D}\right), \psi\right\rangle_{X_{q^{\prime}}} & =\int_{\Omega} \varepsilon \nabla\left(Z_{4}+z_{4}^{D}\right) \cdot \nabla \psi_{4} \mathrm{~d} x, \\
\left\langle A^{l}\left(Z, z^{D}\right), \psi\right\rangle_{X_{q^{\prime}}} & =\int_{\Omega_{0}}\left\{R(\cdot, z)\left(\psi_{1}+\psi_{2}\right)+h_{0}(\cdot, z) \psi_{4}\right\} \mathrm{d} x, \\
\langle B(g, f), \psi\rangle_{X_{q^{\prime}}} & =\int_{\Omega} f \psi_{4} \mathrm{~d} x+\int_{\Gamma_{N 0}} \sum_{i=1}^{4} g_{i}^{N 0} \psi_{i} \mathrm{~d} \Gamma+\int_{\Gamma_{N 1}} \sum_{i=3}^{4} g_{i}^{N 1} \psi_{i} \mathrm{~d} \Gamma, \psi \in X_{q^{\prime}},
\end{aligned}
$$

where $z=Z+z^{D}$. Since $q>2$ the continuous differentiability of the operator $A^{l}$ is a direct consequence of the fact that $\widetilde{r}$ and $h_{0}$ are of the class ( $\mathrm{D}_{0}$ ), see (A4), (A5). The assertion for the operators $A^{44}$ and $B$ is verified by standard arguments. Now we do, as a representative of a non standard situation, the proof for a summand $A^{i k}$. First we show continuity. Let $\left(Z, z^{D}\right) \in M_{q, \tau}$ and let $\left(\bar{Z}, \bar{z}^{D}\right) \rightarrow 0$ in $X_{q} \times W_{p}$, then

$$
\begin{aligned}
& \left|\left\langle A^{i k}\left(Z+\bar{Z}, z^{D}+\bar{z}^{D}\right)-A^{i k}\left(Z, z^{D}\right), \psi\right\rangle_{X_{q^{\prime}}}\right| \\
& \leq \int_{\Omega_{0}}\left|a_{i k}(\cdot, z+\bar{z})-a_{i k}(\cdot, z)\left\|\nabla\left(Z_{k}+\bar{Z}_{k}+z_{k}^{D}+\bar{z}_{k}^{D}\right)\right\| \nabla \psi_{i}\right| \mathrm{d} x \\
& +\int_{\Omega_{0}}\left|a_{i k}(\cdot, z)\left\|\nabla\left(\bar{Z}_{k}+\bar{z}_{k}^{D}\right)\right\| \nabla \psi_{i}\right| \mathrm{d} x \\
& \leq c_{p}\left\|a_{i k}(z+\bar{z})-a_{i k}(z)\right\|_{L^{\infty}\left(\Omega_{0}\right)}\left(\|Z+\bar{Z}\|_{X_{q}}+\left\|z^{D}+\bar{z}^{D}\right\|_{W_{p}}\right)\|\psi\|_{X_{q^{\prime}}} \\
& +c_{p}\left\|a_{i k}(z)\right\|_{L^{\infty}\left(\Omega_{0}\right)}\left(\|\bar{Z}\|_{X_{q}}+\left\|\bar{z}^{D}\right\|_{W_{p}}\right)\|\psi\|_{X_{q^{\prime}}}
\end{aligned}
$$

Since the functions $a_{i k}$ belong to the class ( $\mathrm{D}_{0}$ ), see (A2), the continuity follows. Next, let $\left(Z, z^{D}\right) \in M_{q, \tau}$ be arbitrarily fixed. We prove that the operator $\bar{A}^{i k}\left(Z, z^{D}\right) \in \mathcal{L}\left(X_{q}, X_{q^{\prime}}^{*}\right)$,

$$
\begin{aligned}
\left\langle\bar{A}^{i k}\left(Z, z^{D}\right) \bar{Z}, \psi\right\rangle_{X_{q^{\prime}}} & =\int_{\Omega_{0}} \partial_{z} a_{i k}(\cdot, z) \cdot \bar{Z} \nabla\left(Z_{k}+z_{k}^{D}\right) \cdot \nabla \psi_{i} \mathrm{~d} x \\
& +\int_{\Omega_{0}} a_{i k}(\cdot, z) \nabla \bar{Z}_{k} \cdot \nabla \psi_{i} \mathrm{~d} x, \quad \psi \in X_{q^{\prime}}
\end{aligned}
$$

is the Fréchet derivative of $A^{i k}\left(Z, z^{D}\right)$ with respect to $Z$ : Let $\bar{Z} \rightarrow 0$ in $X_{q}$.

$$
\begin{aligned}
& \left|\left\langle A^{i k}\left(Z+\bar{Z}, z^{D}\right)-A^{i k}\left(Z, z^{D}\right)-\bar{A}^{i k}\left(Z, z^{D}\right) \bar{Z}, \psi\right\rangle_{X_{q^{\prime}}}\right| \\
& \leq \mid \int_{\Omega_{0}}\left(a_{i k}(\cdot, z+\bar{Z}) \nabla\left(z_{k}+\bar{Z}_{k}\right)-a_{i k}(\cdot, z) \nabla z_{k}\right) \cdot \nabla \psi_{i} \mathrm{~d} x \\
& \quad-\int_{\Omega_{0}}\left(\partial_{z} a_{i k}(\cdot, z) \cdot \bar{Z} \nabla z_{k}+a_{i k}(\cdot, z) \nabla \bar{Z}_{k}\right) \cdot \nabla \psi_{i} \mathrm{~d} x \mid \\
& \leq \int_{\Omega_{0}}\left|a_{i k}(\cdot, z+\bar{Z})-a_{i k}(\cdot, z)-\partial_{z} a_{i k}(\cdot, z) \cdot \bar{Z}\right|\left|\nabla z_{k} \| \nabla \psi_{i}\right| \mathrm{d} x \\
& +\int_{\Omega_{0}}\left|a_{i k}(\cdot, z+\bar{Z})-a_{i k}(\cdot, z)\right|\left|\nabla \bar{Z}_{k} \| \nabla \psi_{i}\right| \mathrm{d} x \\
& \leq c_{p}\left\|a_{i k}(z+\bar{Z})-a_{i k}(z)-\partial_{z} a_{i k}(z) \cdot \bar{Z}\right\|_{L^{\infty}\left(\Omega_{0}\right)}\left(\|Z\|_{X_{q}}+\left\|z^{D}\right\|_{W_{p}}\right)\|\psi\|_{X_{q^{\prime}}} \\
& +\left\|a_{i k}(z+\bar{Z})-a_{i k}(z)\right\|_{L^{\infty}\left(\Omega_{0}\right)}\|\bar{Z}\|_{X_{q}}\|\psi\|_{X_{q^{\prime}}}
\end{aligned}
$$

Exploiting, that $a_{i k}$ are of the class $\left(\mathrm{D}_{0}\right)$ and $\bar{Z} \rightarrow 0$ the last two lines converge to zero and differentiability with respect to $Z$ is shown. The continuity of this Fréchet derivative is guaranteed since the functions $a_{i k}$ are of the class $\left(\mathrm{D}_{0}\right)$. Similarly one can prove the continuous differentiability of $A^{i k}$ with respect to $z^{D}$. Substituting $\Omega_{0}$ by $\Omega_{1}$ we obtain the assertion for the operator $\widetilde{A}^{33}$ as a special case of the above if we take into account that $\widetilde{a}_{33}$ belongs to the class $\left(\mathrm{D}_{1}\right)$. Thus the sum $F_{q, \tau}$ of all the considered summands is continuously differentiable.

Especially we have

$$
\begin{align*}
\left\langle\partial_{Z} F_{q, \tau}(Z, w) \bar{Z}, \psi\right\rangle_{X_{q^{\prime}}} & =\int_{\Omega_{0}} \sum_{i, k=1}^{3}\left\{a_{i k}(\cdot, z) \nabla \bar{Z}_{k}+\partial_{z} a_{i k}(\cdot, z) \cdot \bar{Z} \nabla z_{k}\right\} \cdot \nabla \psi_{i} \mathrm{~d} x \\
& +\int_{\Omega_{0}}\left\{\partial_{z} R(\cdot, z) \cdot \bar{Z}\left(\psi_{1}+\psi_{2}\right)+\partial_{z} h_{0}(\cdot, z) \cdot \bar{Z} \psi_{4}\right\} \mathrm{d} x  \tag{4.10}\\
& +\int_{\Omega_{1}}\left\{\widetilde{a}_{33}\left(\cdot, z_{3}\right) \nabla \bar{Z}_{3}+\frac{\partial \widetilde{a}_{33}}{\partial z_{3}}\left(\cdot, z_{3}\right) \bar{Z}_{3} \nabla z_{3}\right\} \cdot \nabla \psi_{3} \mathrm{~d} x \\
& +\int_{\Omega} \varepsilon \nabla \bar{Z}_{4} \cdot \nabla \psi_{4} \mathrm{~d} x, \quad \psi \in X_{q^{\prime}} .
\end{align*}
$$

We define a set of data, which is compatible with thermodynamic equilibrium,

$$
\begin{aligned}
& Q:=\left\{w=\left(z^{D}, g, f\right) \in \mathcal{H}: z_{i}^{D}=\text { const }, g_{i}^{N 0}=0, i=1,2,3,\right. \\
&\left.g_{3}^{N 1}=0, z_{1}^{D}+z_{2}^{D}=0, z_{3}^{D}<0\right\} .
\end{aligned}
$$

Theorem 4.1 (Existence and uniqueness of thermodynamic equilibria). We make the assumptions (A1) - (A5). Let $w^{*}=\left(z^{D *}, g^{*}, f^{*}\right) \in Q$ be given.
i) Then there exist a $q_{0} \in(2, p]$, a constant $\tau>1$ and a function $Z_{4}^{*} \in W_{0}^{1, q_{0}}(G)$
such that $\left(Z^{*}, z^{D *}\right)=\left(\left(0,0,0, Z_{4}^{*}\right), z^{D *}\right) \in M_{q_{0}, \tau}$ and $F_{q_{0}, \tau}\left(Z^{*}, w^{*}\right)=0$.
In other words, $\left(q_{0}, \tau, Z^{*}, w^{*}\right)$ is a solution to ( P ).
ii) $z^{*}=Z^{*}+z^{D *}$ is a thermodynamic equilibrium of (1.5), (1.6), (1.7).
iii) If $\left(\widetilde{q}, \widetilde{\tau}, \widetilde{Z}, w^{*}\right)$ is a solution to (P), then $\widetilde{Z}=Z^{*}$ in $X_{\widehat{q}}$ with $\widehat{q}=\min \left\{q_{0}, \widetilde{q}\right\}$ holds.

Proof. 1. For $w^{*}=\left(z^{D *}, g^{*}, f^{*}\right) \in Q$ we define the function $h_{1}: \Omega_{0} \times \mathbb{R} \rightarrow \mathbb{R}$ by

$$
h_{1}(x, \phi)=h_{0}\left(x,(0,0,0, \phi)+z^{D *}(x)\right)
$$

and consider the operator $\mathcal{E}: H_{0}^{1}(G) \rightarrow H^{-1}(G)$,

$$
\begin{aligned}
\langle\mathcal{E}(\phi), \bar{\phi}\rangle_{H_{0}^{1}(G)} & =\int_{\Omega}\left\{\varepsilon \nabla\left(\phi+z_{4}^{D *}\right) \cdot \nabla \bar{\phi}-f^{*} \bar{\phi}\right\} \mathrm{d} x+\int_{\Omega_{0}} h_{1}(\cdot, \phi) \bar{\phi} \mathrm{d} x \\
& -\int_{\Gamma_{N 0}} g_{4}^{N 0 *} \bar{\phi} \mathrm{~d} \Gamma-\int_{\Gamma_{N 1}} g_{4}^{N 1 *} \bar{\phi} \mathrm{~d} \Gamma \quad \forall \bar{\phi} \in H_{0}^{1}(G) .
\end{aligned}
$$

For $\phi_{1}, \phi_{2} \in H_{0}^{1}(G)$ we have

$$
\begin{aligned}
& \left\langle\mathcal{E}\left(\phi_{1}\right)-\mathcal{E}\left(\phi_{2}\right), \phi_{1}-\phi_{2}\right\rangle_{H_{0}^{1}(G)} \\
& =\int_{\Omega} \varepsilon\left|\nabla\left(\phi_{1}-\phi_{2}\right)\right|^{2} \mathrm{~d} x+\int_{\Omega_{0}}\left(h_{1}\left(\cdot, \phi_{1}\right)-h_{1}\left(\cdot, \phi_{2}\right)\right)\left(\phi_{1}-\phi_{2}\right) \mathrm{d} x,
\end{aligned}
$$

and the properties (A1), (A3), (A4) of $\Gamma_{D}, \varepsilon$ and $h_{0}$ supply the strong monotonicity of the operator $\mathcal{E}$. Next we prove the hemicontinuity of $\mathcal{E}$. We have to show that the mapping
$t \mapsto\langle\mathcal{E}(\phi+t \widehat{\phi}), \bar{\phi}\rangle_{H_{0}^{1}(G)}$ for arbitrarily given $\phi, \widehat{\phi}, \bar{\phi} \in H_{0}^{1}(G)$ is continuous on $[0,1]$. Let $t_{0} \in[0,1], t_{n} \rightarrow t_{0}, t_{n} \in[0,1]$. Then

$$
\begin{align*}
& \left\langle\mathcal{E}\left(\phi+t_{n} \widehat{\phi}\right)-\mathcal{E}\left(\phi+t_{0} \widehat{\phi}\right), \bar{\phi}\right\rangle_{H_{0}^{1}(G)} \\
& \leq c\left|t_{n}-t_{0}\right|\|\widehat{\phi}\|_{H^{1}}\|\bar{\phi}\|_{H^{1}}+\left|\int_{\Omega_{0}}\left[h_{1}\left(\cdot, \phi+t_{n} \widehat{\phi}\right)-h_{1}\left(\cdot, \phi+t_{0} \widehat{\phi}\right)\right] \bar{\phi} \mathrm{d} x\right| \tag{4.11}
\end{align*}
$$

According to (A4) we have $h_{1}\left(x, \phi+t_{n} \widehat{\phi}\right) \rightarrow h_{1}\left(x, \phi+t_{0} \widehat{\phi}\right)$ and

$$
\left|h_{1}\left(x, \phi+t_{n} \widehat{\phi}\right)\right| \leq \widetilde{c} \mathrm{e}^{\widetilde{c}(|\phi|+|\widehat{\phi}|)} \text { for almost all } x \in \Omega_{0}
$$

Now we use the embedding result of Trudinger [12] for two dimensional Lipschitzian domains which tells us that

$$
\left\|\mathrm{e}^{|v|}\right\|_{L^{2}\left(\Omega_{0}\right)} \leq d\left(\|v\|_{H^{1}\left(\Omega_{0}\right)}\right) \quad \forall v \in H^{1}\left(\Omega_{0}\right)
$$

where $d: \mathbb{R}_{+} \rightarrow \mathbb{R}_{+}$is a continuous, monotone increasing function with $\lim _{y \rightarrow \infty} d(y)=\infty$. Since $\bar{\phi} \in L^{2}\left(\Omega_{0}\right)$ we get an integrable upper bound for the integrand in the last term in (4.11) and Lebesgue's Dominated Convergence Theorem leads to the hemicontinuity of $\mathcal{E}$. Since $\mathcal{E}$ is strongly monotone and hemicontinuous, there exists a unique solution $\phi \in H_{0}^{1}(G)$ of $\mathcal{E}(\phi)=0$. Especially we have $\|\phi\|_{H^{1}(\Omega)} \leq \widehat{c}$, where $\widehat{c}$ depends only on the data $w^{*}$.
2. Next we prove that this solution possesses more regularity. We define

$$
\begin{aligned}
\left\langle\mathcal{E}_{0}(\phi), \bar{\phi}\right\rangle_{H_{0}^{1}(G)} & =\int_{\Omega}\{\varepsilon \nabla \phi \cdot \nabla \bar{\phi}+\phi \bar{\phi}\} \mathrm{d} x \\
\langle\mathcal{T}, \bar{\phi}\rangle_{H_{0}^{1}(G)} & =\int_{\Omega}\left\{-\varepsilon \nabla z_{4}^{D *} \cdot \nabla \bar{\phi}+\left(f^{*}+\phi\right) \bar{\phi}\right\} \mathrm{d} x-\int_{\Omega_{0}} h_{1}(\cdot, \phi) \bar{\phi} \mathrm{d} x \\
& +\int_{\Gamma_{N 0}} g_{4}^{N 0 *} \bar{\phi} \mathrm{~d} \Gamma+\int_{\Gamma_{N 1}} g_{4}^{N 1 *} \bar{\phi} \mathrm{~d} \Gamma \quad \forall \bar{\phi} \in H_{0}^{1}(G) .
\end{aligned}
$$

Since $z_{4}^{D *} \in W^{1, p}(\Omega)$ is a fixed element there is a $\bar{c}>0$ such that $\left|z_{4}^{D *}\right| \leq \bar{c}$. From the properties (A4) of $h_{0}$ we find $\left|h_{1}(x, \phi)\right| \leq c\left(z^{D *}\right) \mathrm{e}^{c\left|z_{4}^{D *}+\phi\right|} \leq \widetilde{c}\left(z^{D *}\right) \mathrm{e}^{c \bar{c}|\phi|}$ f.a.a. $x \in \Omega_{0}$. Thus the embedding result of Trudinger mentioned in the first step of this proof yields

$$
\left\|h_{1}(\cdot, \phi)\right\|_{L^{2}\left(\Omega_{0}\right)} \leq \widetilde{c}\left(z^{D *}\right) d\left(\|\phi\|_{H^{1}\left(\Omega_{0}\right)}\right) \leq \widehat{c}
$$

Furthermore, using that $\left(z^{D *}, g^{*}, f^{*}\right) \in \mathcal{H}$ is fixed it results that $\mathcal{T} \in W^{-1, p}(G)$. Thus taking benefit from Grögers regularity result [9] applied to the equation $\mathcal{E}_{0}(\phi)=\mathcal{T}$ we obtain a $q_{0} \in(2, p]$ such that $\phi \in W^{1, q_{0}}(G)$ and $\|\phi\|_{W^{1, q_{0}}} \leq c_{q_{0}}\|\mathcal{T}\|_{W^{-1, p}(G)}$. Note that our assumption concerning the domain $\Omega$ and its boundary ensure that $G$ is regular in the sense of Gröger [9].
3. The continuous embedding $W^{1, q_{0}}(\Omega) \hookrightarrow C(\bar{\Omega})$ ensures that $\|\phi\|_{C(\bar{\Omega})} \leq c\left(q_{0}, w^{*}\right)$. Setting $Z_{i}^{*}=0, i=1,2,3, Z_{4}^{*}=\phi$ and using that $w^{*} \in Q$ we find a constant $\tau>1$ such that that $\left(Z^{*}, z^{D *}\right) \in M_{q_{0}, \tau}$ and $F_{q_{0}, \tau}\left(Z^{*}, w^{*}\right)=0$. In other words, $\left(q_{0}, \tau, Z^{*}, w^{*}\right)$ is a solution to Problem (P). Moreover, $z^{*}=Z^{*}+z^{D *}$ is a thermodynamic equilibrium of (1.5), (1.6), (1.7).
4. Uniqueness: Let $\left(\widetilde{q}, \widetilde{\tau}, \widetilde{Z}, w^{*}\right)$ be a solution to $\operatorname{Problem}(\mathrm{P})$ and let $\widetilde{z}=\widetilde{Z}+z^{D *}$. Then we have $\left(Z^{*}, z^{D *}\right) \in M_{q_{0}, \tau},\left(\widetilde{Z}, z^{D *}\right) \in M_{\tilde{q}, \tilde{\tau}}$ and $F_{q_{0}, \tau}\left(Z^{*}, w^{*}\right)=F_{\widetilde{q}, \widetilde{\tau}}\left(\widetilde{Z}, w^{*}\right)=0$. Let $\widehat{q}=\min \left\{q_{0}, \widetilde{q}\right\}, \widehat{\tau}=\max \{\tau, \widetilde{\tau}\}$. Then we have that $\left(Z^{*}, z^{D *}\right),\left(\widetilde{Z}, z^{D *}\right) \in M_{\widehat{q}, \widehat{\tau}}$ and $F_{\widehat{q}, \widehat{\tau}}\left(Z^{*}, w^{*}\right)=F_{\widehat{q}, \widehat{\tau}}\left(\widetilde{Z}, w^{*}\right)=0$. We test the last equation with $\left(\widetilde{Z}_{1}, \widetilde{Z}_{2}, \widetilde{Z}_{3}, 0\right)$. Since $w^{*}, w^{*}+\left(Z^{*}, 0,0\right) \in Q$ we obtain

$$
\begin{aligned}
0 & =\left\langle F_{\widehat{q}, \widehat{\tau}}\left(\widetilde{Z}, w^{*}\right)-F_{\widehat{q}, \widehat{\tau}}\left(Z^{*}, w^{*}\right),\left(\widetilde{Z}_{1}, \widetilde{Z}_{2}, \widetilde{Z}_{3}, 0\right)\right\rangle_{X_{q^{\prime}}} \\
& =\int_{\Omega_{0}} \sum_{i, k=1}^{3} a_{i k}(\cdot, \widetilde{z}) \nabla \widetilde{Z}_{k} \cdot \nabla \widetilde{Z}_{i} \mathrm{~d} x+\int_{\Omega_{1}} \widetilde{a}_{33}\left(\cdot, \widetilde{z}_{3}\right)\left|\nabla \widetilde{Z}_{3}\right|^{2} \mathrm{~d} x \\
& +\int_{\Omega_{0}} \widetilde{r}(\cdot, \widetilde{z})\left(\mathrm{e}^{\widetilde{Z}_{1}+\widetilde{Z}_{2}}-1\right)\left(\widetilde{Z}_{1}+\widetilde{Z}_{2}\right) \mathrm{d} x
\end{aligned}
$$

Exploiting the assumption (A5) for $\widetilde{r}$ and the fact that $\left(\mathrm{e}^{y}-1\right) y \geq 0$ we find

$$
\int_{\Omega_{0}} \sum_{i, k=1}^{3} a_{i k}(\cdot, \widetilde{z}) \nabla \widetilde{Z}_{k} \cdot \nabla \widetilde{Z}_{i} \mathrm{~d} x+\int_{\Omega_{1}} \widetilde{a}_{33}\left(\cdot, \widetilde{z}_{3}\right)\left|\nabla \widetilde{Z}_{3}\right|^{2} \mathrm{~d} x \leq 0
$$

According to (A2) we have $\widetilde{a}_{33}(x, \widetilde{z}) \geq c(\widetilde{z})>0$ and the matrix $\left(a_{i k}(x, \widetilde{z})\right)_{i, k=1,2,3}$ is strongly elliptic. Therefore we obtain $\nabla \widetilde{Z}_{i}=0, i=1,2,3$. And $\left|\Gamma_{D}\right|>0$ supplies that $\widetilde{Z}_{i}=0, i=1,2$, on $\Omega_{0}$ and $\widetilde{Z}_{3}=0$ on $\Omega$.
Finally, the test of $F_{\widehat{q}, \widehat{\tau}}\left(\widetilde{Z}, w^{*}\right)-F_{\widehat{q}, \widehat{\tau}}\left(Z^{*}, w^{*}\right)=0$ with $\left(0,0,0, \widetilde{Z}_{4}-Z_{4}^{*}\right)$ leads to $\widetilde{Z}_{4}=Z_{4}^{*}$, since the operator $\mathcal{E}$ is strongly monotone. In summary we find $\widetilde{Z}=Z^{*}$, which gives the last assertion.

Lemma 4.2 (Fredholm property of the linearization). We assume (A1) - (A5). Let $w^{*}=$ $\left(z^{D *}, g^{*}, f^{*}\right) \in Q$ be given. Let $\left(q_{0}, \tau, Z^{*}, w^{*}\right)$ be the equilibrium solution to Problem (P) (see Theorem 4.1) and let $z^{*}=Z^{*}+z^{D *}$. Then there exists a $q_{1} \in\left(2, q_{0}\right]$ such that the operator $\partial_{Z} F_{q_{1}, \tau}\left(Z^{*}, w^{*}\right)$ is a Fredholm operator of index zero.

Proof. Let $q \in\left(2, q_{0}\right]$ and $\bar{Z} \in X_{q}$. The linearization is given in (4.10) and has now to be calculated at $\left(Z^{*}, w^{*}\right)$. Since $\nabla z_{i}^{*}=0, i=1,2,3, \mathrm{e}^{z_{1}^{*}+z_{2}^{*}}=1$ and

$$
\partial_{z} R\left(\cdot, z^{*}\right) \cdot \bar{Z}=\partial_{z} \widetilde{r}\left(\cdot, z^{*}\right) \cdot \bar{Z}\left(\mathrm{e}^{z_{1}^{*}+z_{2}^{*}}-1\right)+\widetilde{r}\left(\cdot, z^{*}\right) \mathrm{e}^{z_{1}^{*}+z_{2}^{*}}\left(\bar{Z}_{1}+\bar{Z}_{2}\right)
$$

we obtain according to (4.10) that

$$
\begin{align*}
\left\langle\partial_{Z} F_{q, \tau}\left(Z^{*}, w^{*}\right) \bar{Z}, \psi\right\rangle_{X_{q^{\prime}}} & =\int_{\Omega_{0}}\left(\sum_{i, k=1}^{3} a_{i k}\left(\cdot, z^{*}\right) \nabla \bar{Z}_{k} \cdot \nabla \psi_{i}+\varepsilon \nabla \bar{Z}_{4} \cdot \nabla \psi_{4}\right) \mathrm{d} x \\
& +\int_{\Omega_{0}}\left(\widetilde{r}\left(\cdot, z^{*}\right)\left(\bar{Z}_{1}+\bar{Z}_{2}\right)\left(\psi_{1}+\psi_{2}\right)+\partial_{z} h_{0}\left(\cdot, z^{*}\right) \cdot \bar{Z} \psi_{4}\right) \mathrm{d} x  \tag{4.12}\\
& +\int_{\Omega_{1}}\left(\widetilde{a}_{33}\left(\cdot, z_{3}^{*}\right) \nabla \bar{Z}_{3} \cdot \nabla \psi_{3}+\varepsilon \nabla \bar{Z}_{4} \cdot \nabla \psi_{4}\right) \mathrm{d} x
\end{align*}
$$

Now we follow ideas in the proof of Theorem 4.1 of Recke [11]. For $q \in\left(2, q_{0}\right]$ we write $\partial_{Z} F_{q, \tau}\left(Z^{*}, w^{*}\right)$ as $\operatorname{sum} \partial_{Z} F_{q, \tau}\left(Z^{*}, w^{*}\right)=L_{q}+K_{q}$ with operators $L_{q}, K_{q}: X_{q} \rightarrow X_{q^{\prime}}^{*}$, where

$$
\begin{aligned}
\left\langle L_{q} \bar{Z}, \psi\right\rangle_{X_{q^{\prime}}} & =\int_{\Omega_{0}}\left(\sum_{i, k=1}^{3} a_{i k}\left(\cdot, z^{*}\right) \nabla \bar{Z}_{k} \cdot \nabla \psi_{i}+\varepsilon \nabla \bar{Z}_{4} \cdot \nabla \psi_{4}+\sum_{i=1}^{4} \bar{Z}_{i} \psi_{i}\right) \mathrm{d} x \\
& +\int_{\Omega_{1}}\left(\widetilde{a}_{33}\left(\cdot, z_{3}^{*}\right) \nabla \bar{Z}_{3} \cdot \nabla \psi_{3}+\varepsilon \nabla \bar{Z}_{4} \cdot \nabla \psi_{4}+\sum_{i=3}^{4} \bar{Z}_{i} \psi_{i}\right) \mathrm{d} x, \\
\left\langle K_{q} \bar{Z}, \psi\right\rangle_{X_{q^{\prime}}} & =\int_{\Omega_{0}}\left\{\widetilde{r}\left(\cdot, z^{*}\right)\left(\bar{Z}_{1}+\bar{Z}_{2}\right)\left(\psi_{1}+\psi_{2}\right)+\partial_{z} h_{0}\left(\cdot, z^{*}\right) \cdot \bar{Z} \psi_{4}-\sum_{i=1}^{4} \bar{Z}_{i} \psi_{i}\right\} \mathrm{d} x \\
& -\int_{\Omega_{1}} \sum_{i=3}^{4} \bar{Z}_{i} \psi_{i} \mathrm{~d} x, \quad \psi \in X_{q^{\prime}} .
\end{aligned}
$$

The operator $K_{q}$ is compact because of the compact embedding of $W^{1, q}(\Omega)$ into $L^{\infty}(\Omega)$. The operator $L_{q}$ is injective. Next, we apply Theorem 5.1 from Section 5 . We set $d_{i k}=$ $a_{i k}\left(\cdot, z^{*}\right), i, k=1,2,3, d_{4 k}=d_{\underline{k} 4}=0, \underset{\sim}{\underset{\sim}{d}}=1,2,3, d_{44}=\varepsilon, d_{i}=1, i=1, \ldots, 4$, in $\Omega_{0}$ and $\widetilde{d}_{33}=\widetilde{a}_{33}\left(\cdot, z_{3}^{*}\right), \widetilde{d}_{43}=\widetilde{d}_{34}=0, \widetilde{d}_{44}=\varepsilon, \widetilde{d}_{i}=1, i=3,4$, in $\Omega_{1}$. Due to our assumptions (A2), (A3) the properties (B) at the beginning of Section 5 are fulfilled. Since $L_{q}$ is the restriction of $\bar{A}$ (see (5.18)) to $X_{q}$, Theorem 5.1 guarantees the existence of an exponent $q_{1} \in\left(2, q_{0}\right]$ such that the operator $L_{q_{1}}$ is surjective. Then by Banach's open mapping theorem and Nikolsky's criterion for Fredholm operators the assertion of the lemma follows.

Lemma 4.3 (Injectivity of the linearization). We assume (A1) - (A5). Let the vector of data $w^{*}=\left(z^{D *}, g^{*}, f^{*}\right) \in Q$ be given, and let $\left(q_{0}, \tau, Z^{*}, w^{*}\right)$ be the equilibrium solution to Problem ( P ), and $z^{*}=Z^{*}+z^{D *}$ (see Theorem 4.1). Then the Fréchet derivative $\partial_{Z} F_{q_{1}, \tau}\left(Z^{*}, w^{*}\right): X_{q_{1}} \rightarrow X_{q_{1}^{\prime}}^{*}$ is injective, where $q_{1}$ is chosen as in Lemma 4.2.

Proof. It is sufficient to prove the injectivity of the operator on $X_{2}$. The derivative has the form (4.12). Let $\partial_{Z} F_{q_{1}, \tau}\left(Z^{*}, w^{*}\right) \bar{Z}=0, \bar{Z} \in X_{2}$.
We test this equation with $\psi=\left(\bar{Z}_{1}, \bar{Z}_{2}, \bar{Z}_{3}, 0\right)$ and take into account the strong ellipticity condition for $\left(a_{i k}\left(x, z^{*}\right)\right)_{i, k=1,2,3}$, the fact that $\left|\Gamma_{D}\right|>0$ and the property that $\widetilde{r}\left(z^{*}\right) \geq 0$ and get that $\bar{Z}_{i}=0, i=1,2,3$. Next, we use the test function $\psi=\left(0,0,0, \bar{Z}_{4}\right)$ and obtain

$$
\int_{\Omega}\left\{\varepsilon\left|\nabla \bar{Z}_{4}\right|^{2}+\frac{\partial}{\partial z_{4}} h_{0}\left(\cdot, z^{*}\right) \bar{Z}_{4}^{2}\right\} \mathrm{d} x=0 .
$$

Since $h_{0}$ is continuously differentiable and monotonic increasing in the argument $z_{4}$ (see (A4)) we have $\frac{\partial}{\partial z_{4}} h_{0}\left(x, z^{*}\right) \geq 0$ a.e. on $\Omega$ which together with $\varepsilon \geq \varepsilon_{0}$ a.e. on $\Omega$ and $\left|\Gamma_{D}\right|>0$ leads to $\bar{Z}_{4}=0$. Thus the injectivity of $\partial_{Z} F_{q_{1}, \tau}\left(Z^{*}, w^{*}\right): X_{q_{1}} \rightarrow X_{q_{1}^{\prime}}^{*}$ follows, too.

Theorem 4.2 (Local existence and uniqueness of steady states). We assume (A1) (A5). Let $w^{*}=\left(z^{D *}, g^{*}, f^{*}\right) \in Q$ be given, and let $\left(q_{0}, \tau, Z^{*}, w^{*}\right)$ be the equilibrium solution to Problem (P), and $z^{*}=Z^{*}+z^{D *}$ (see Theorem 4.1).

Then there exists a $q_{1} \in\left(2, q_{0}\right]$ such that the following assertion holds: There exist neighbourhoods $U \subset X_{q_{1}}$ of $Z^{*}$ and $W \subset \mathcal{H}$ of $w^{*}=\left(z^{D *}, g^{*}, f^{*}\right)$ and a $C^{1}$-map $\Phi: W \rightarrow U$ such that $Z=\Phi(w)$ iff

$$
F_{q_{1}, \tau}(Z, w)=0, \quad\left(Z, z^{D}\right) \in M_{q_{1}, \tau}, \quad Z \in U, \quad w=\left(z^{D}, g, f\right) \in W
$$

Proof. According to Lemma 4.2 and Lemma 4.3 there exists a $q_{1}$ such that the operator $\partial_{Z} F_{q_{1}, \tau}\left(Z^{*}, w^{*}\right): X_{q_{1}} \rightarrow X_{q_{1}^{\prime}}^{*}$ is an injective Fredholm Operator of index zero. Therefore the assertion of the theorem is a direct consequence of the Implicit Function Theorem.

Finally, let us draw a conclusion from Theorem 4.2. First, we define the sets

$$
\begin{aligned}
& Q_{1}=\left\{w=\left(z^{D}, g, f\right) \in \mathcal{H}: g_{i}^{N 0}=0, i=1,2,3, g_{3}^{N 1}=0\right. \\
&\left.\int_{\Gamma_{D}}\left(z_{1}^{D}+z_{2}^{D}\right) \mathrm{d} \Gamma=0, z_{3}^{D}<0\right\} \\
& Q_{2}=\left\{w=\left(z^{D}, g, f\right) \in \mathcal{H}: z_{3}^{D}<0\right\}
\end{aligned}
$$

Obviously $Q \subset Q_{1} \subset Q_{2}$ holds, but $Q_{1}$ and $Q_{2}$ contain also elements which are not compatible with thermodynamic equilibria.

Corollary 4.1 We assume (A1) - (A5).
i) Let $w=\left(z^{D}, g, f\right) \in Q_{1}$ be given. Then there are constants $q \in(2, p], \tau>1, \epsilon>0$ such that the following assertions hold: If

$$
\begin{equation*}
\left\|\nabla z_{i}^{D}\right\|_{L^{p}\left(\Omega_{0}\right)}<\epsilon, \quad i=1,2, \quad\left\|\nabla z_{3}^{D}\right\|_{L^{p}(\Omega)}<\epsilon \tag{4.13}
\end{equation*}
$$

then there exists a $Z \in X_{q}$ such that $(q, \tau, Z, w)$ is a solution to $(\mathrm{P})$. This solution lies in a neighbourhood of an equilibrium solution $\left(q, \tau, Z^{*}, w^{*}\right)$ to $(\mathrm{P})$, and in this neighbourhood there are no solutions $(q, \tau, \widetilde{Z}, w)$ with $\widetilde{Z} \neq Z$.
ii) Let $w=\left(z^{D}, g, f\right) \in Q_{2}$ be given. Then there are constants $q \in(2, p], \tau>1, \epsilon>0$ such that the following assertions hold: If

$$
\begin{align*}
& \left\|\nabla z_{i}^{D}\right\|_{L^{p}\left(\Omega_{0}\right)}<\epsilon, \quad i=1,2, \quad\left\|\nabla z_{3}^{D}\right\|_{L^{p}(\Omega)}<\epsilon \\
& \left\|z_{1}^{D}+z_{2}^{D}\right\|_{L^{1}\left(\Gamma_{D}\right)}<\epsilon,  \tag{4.14}\\
& \left\|g_{i}^{N 0}\right\|_{L^{\infty}\left(\Gamma_{N 0}\right)} \leq \epsilon, \quad i=1,2,3, \quad\left\|g_{3}^{N 1}\right\|_{L^{\infty}\left(\Gamma_{N 1}\right)} \leq \epsilon
\end{align*}
$$

then there exists a $Z \in X_{q}$ such that $(q, \tau, Z, w)$ is a solution to $(\mathrm{P})$. This solution lies in a neighbourhood of an equilibrium solution $\left(q, \tau, Z^{*}, w^{*}\right)$ to $(\mathrm{P})$, and in this neighbourhood there are no solutions $(q, \tau, \widetilde{Z}, w)$ with $\widetilde{Z} \neq Z$.

Proof. 1. Let $w=\left(z^{D}, g, f\right) \in Q_{1}$ be given. We define

$$
z_{i}^{D *}=\frac{1}{\left|\Gamma_{D}\right|} \int_{\Gamma_{D}} z_{i}^{D} \mathrm{~d} \Gamma, i=1,2,3, \quad z_{4}^{D *}=z_{4}^{D}, \quad w^{*}=\left(z^{D *}, g, f\right)
$$

and find that $w^{*} \in Q$. Let $\left(q_{0}, \tau, Z^{*}, w^{*}\right)$ be the corresponding equilibrium solution to ( P ). Because of Theorem 4.2 there exist constants $q \in\left(2, q_{0}\right], \epsilon^{\prime}>0$ such that the equation $F_{q, \tau}(Z, w)=0$ has a locally unique solution $Z \in X_{q}$ if

$$
\begin{equation*}
\left\|w-w^{*}\right\|_{\mathcal{H}}=\sum_{i=1}^{2}\left\|z_{i}^{D}-z_{i}^{D *}\right\|_{W^{1, p}\left(\Omega_{0}\right)}+\left\|z_{3}^{D}-z_{3}^{D *}\right\|_{W^{1, p}(\Omega)}<\epsilon^{\prime} \tag{4.15}
\end{equation*}
$$

Since for $i=1,2,3$ the mean values of $z_{i}^{D}-z_{i}^{D *}$ on $\Gamma_{D}$ vanish we can apply the Friedrich inequality to obtain

$$
\begin{aligned}
& \left\|z_{i}^{D}-z_{i}^{D *}\right\|_{W^{1, p}\left(\Omega_{0}\right)} \leq c\left\|\nabla z_{i}^{D}\right\|_{L^{p}\left(\Omega_{0}\right)}, \quad i=1,2, \\
& \left\|z_{3}^{D}-z_{3}^{D *}\right\|_{W^{1, p}(\Omega)} \leq c\left\|\nabla z_{3}^{D}\right\|_{L^{p}(\Omega)} .
\end{aligned}
$$

Choosing $\epsilon$ in (4.13) sufficiently small the inequality (4.15) can be fulfilled.
2. We decompose $\mathbb{R}^{2}=\mathcal{S} \oplus \mathcal{S}^{\perp}$, where $\mathcal{S}=\operatorname{span}\{(1,1)\}, \mathcal{S}^{\perp}=\operatorname{span}\{(1,-1)\}$. The corresponding projection operators are denoted by $\Pi_{\mathcal{S}}: \mathbb{R}^{2} \rightarrow \mathcal{S}$ and $\Pi_{\mathcal{S}^{\perp}}: \mathbb{R}^{2} \rightarrow \mathcal{S}^{\perp}$. Obviously, there is a constant $c>0$ such that

$$
\begin{equation*}
\left\|\lambda-\Pi_{\mathcal{S}^{\perp}} \lambda\right\|_{\mathbb{R}^{2}}=\left\|\Pi_{\mathcal{S}} \lambda\right\|_{\mathbb{R}^{2}} \leq c\left|\lambda_{1}+\lambda_{2}\right| \quad \forall \lambda \in \mathbb{R}^{2} . \tag{4.16}
\end{equation*}
$$

Let $w=\left(z^{D}, g, f\right) \in Q_{2}$ be given. We define

$$
\begin{aligned}
& \bar{z}_{i}^{D}=\frac{1}{\left|\Gamma_{D}\right|} \int_{\Gamma_{D}} z_{i}^{D} \mathrm{~d} \Gamma, i=1,2,3, \\
& z^{D *}=\left(z_{1}^{D *}, z_{2}^{D *}, z_{3}^{D *}, z_{4}^{D *}\right)=\left(\Pi_{\mathcal{S}^{\perp}}\left(\bar{z}_{1}^{D}, \bar{z}_{2}^{D}\right), \bar{z}_{3}^{D}, z_{4}^{D}\right), \\
& w^{*}=\left(z^{D *},\left(0,0,0, g_{4}^{N 0}, 0, g_{4}^{N 1}\right), f\right)
\end{aligned}
$$

and find again that $w^{*} \in Q$. Let $\left(q_{0}, \tau, Z^{*}, w^{*}\right)$ be the corresponding equilibrium solution to (P). Because of Theorem 4.2 there are constants $q \in\left(2, q_{0}\right], \epsilon^{\prime}>0$ such that the equation $F_{q, \tau}(Z, w)=0$ has a locally unique solution $Z \in X_{q}$ if

$$
\begin{align*}
\left\|w-w^{*}\right\|_{\mathcal{H}} & =\sum_{i=1}^{2}\left\{\left\|z_{i}^{D}-z_{i}^{D *}\right\|_{W^{1, p}\left(\Omega_{0}\right)}+\left\|g_{i}\right\|_{L^{\infty}\left(\Gamma_{N 0}\right)}\right\}  \tag{4.17}\\
& +\left\|z_{3}^{D}-z_{3}^{D *}\right\|_{W^{1, p}(\Omega)}+\left\|g_{3}^{N 0}\right\|_{L^{\infty}\left(\Gamma_{N 0}\right)}+\left\|g_{3}^{N 1}\right\|_{L^{\infty}\left(\Gamma_{N 1}\right)}<\epsilon^{\prime} .
\end{align*}
$$

From the Friedrich inequality and inequality (4.16) it follows that

$$
\begin{aligned}
\left\|w-w^{*}\right\|_{\mathcal{H}} \leq c( & \sum_{i=1}^{2}\left\{\left\|\nabla z_{i}^{D}\right\|_{L^{p}\left(\Omega_{0}\right)}+\left\|g_{i}^{N 0}\right\|_{L^{\infty}\left(\Gamma_{N 0}\right)}\right\}+\left\|z_{1}^{D}+z_{2}^{D}\right\|_{L^{1}\left(\Gamma_{D}\right)} \\
& \left.+\left\|\nabla z_{3}^{D}\right\|_{L^{p}(\Omega)}+\left\|g_{3}^{N 0}\right\|_{L^{\infty}\left(\Gamma_{N 0}\right)}+\left\|g_{3}^{N 1}\right\|_{L^{\infty}\left(\Gamma_{N 1}\right)}\right),
\end{aligned}
$$

and $\epsilon$ in (4.14) can be chosen such that (4.17) is fulfilled.
The assertions of Corollary 4.1 can be interpreted as follows. Let the source terms for the Poisson equation (i.e. $f, z_{4}^{D}, g_{4}^{N 0}, g_{4}^{N 1}$ ) be given. Then the stationary energy model
has a solution, if the driving forces for the fluxes induced by the boundary data (i.e. the gradients $\left.\nabla z_{1}^{D}, \nabla z_{2}^{D}, \nabla z_{3}^{D}\right)$, the driving forces for the generation-recombination of electrons and holes on the boundary (i.e. the affinities $z_{1}^{D}+z_{2}^{D}$ on $\Gamma_{D}$ ) and the prescribed fluxes on the boundary (i.e. $g_{1}^{N 0}, g_{2}^{N 0}, g_{3}^{N 0}$ and $g_{3}^{N 1}$ ) are small enough. This solution is locally unique.

Remark 4.1 If all equations are defined on the same domain $\Omega$ and mixed boundary conditions are formulated on $\Gamma_{D}$ and $\Gamma_{N}$ analogous results concerning the stationary energy model (1.5), (1.6), (1.7) are obtained by setting formally $\Omega_{0}=\Omega, \Omega_{1}=\emptyset, \Gamma_{N 01}=$ $\Gamma_{N 1}=\emptyset, \Gamma_{N 0}=\Gamma_{N}$ and $G_{0}=G$.

Remark 4.2 Theorem 4.2 gives a local existence and uniqueness result for the stationary energy model (1.5), (1.6), (1.7) for semiconductor devices in two space dimensions. Moreover, the different domains of definition of the relevant model equations are taken into account. For the case that $\Omega$ and $\Omega_{0}$ coincide we have investigated an energy model containing incompletely ionized impurities in [8] and a multi species version of the above energy model in [7].

Remark 4.3 Gröger, Recke [10] study quasilinear second order elliptic systems given on the same domain, where for the divers equations the partition of the mixed boundary conditions into Dirichlet and Neumann parts differs. There is shown that such boundary value problems with triangular main part generate Fredholm maps between appropriate Sobolev-Campanato spaces and that the Implicit Function Theorem can be applied to this situation.

Remark 4.4 If in the energy model (1.1), (1.3) the temperature is considered as a constant positive parameter and the balance equation for the density of the total energy is omitted, then the remaining equations form a drift-diffusion model (van Roosbroeck equations). For the case that $\Omega$ and $\Omega_{0}$ coincide there is a lot of papers dealing with this model (e.g. Chen, Jüngel [2] (here electron hole scattering is involved), [3, 4, 5] and papers cited there). But Gajewski, Gröger [6] considered the Poisson equation in a larger domain $\Omega$ containing the domain of definition $\Omega_{0} \subset \Omega$ of the continuity equations, too.

## 5 A surjectivity result for a system of second order linear elliptic equations defined on different domains

First, we collect some results concerning equivalent norms on cross products of spaces, its duals and on properties of the duality map on cross products (see Lemmata 5.1, 5.2, 5.3). These results enable us to adapt results of Gröger [9] to systems of elliptic equations with different domains of definition. Second, we state a surjectivity property of operators related to strongly coupled linear elliptic equations with homogeneous mixed boundary conditions and different domains of definition. We use the notation, spaces and norms of

Section 3. We consider the operator $\bar{A}: X_{2} \rightarrow X_{2}^{*}$ defined by

$$
\begin{align*}
\langle\bar{A} z, \bar{z}\rangle_{X_{2}} & =\int_{\Omega_{0}}\left\{\sum_{i, k=1}^{4} d_{i k} \nabla z_{k} \cdot \nabla \bar{z}_{i}+\sum_{i=1}^{4} d_{i} z_{i} \bar{z}_{i}\right\} \mathrm{d} x  \tag{5.18}\\
& +\int_{\Omega_{1}}\left\{\sum_{i, k=3}^{4} \widetilde{d}_{i k} \nabla z_{k} \cdot \nabla \bar{z}_{i}+\sum_{i=3}^{4} \widetilde{d}_{i} z_{i} \bar{z}_{i}\right\} \mathrm{d} x, \quad z, \bar{z} \in X_{2}
\end{align*}
$$

Concerning the coefficient functions we suppose
(B) $\quad d_{i k}, d_{i} \in L^{\infty}\left(\Omega_{0}\right), i, k=1, \ldots, 4, \widetilde{d}_{i k}, \widetilde{d}_{i} \in L^{\infty}\left(\Omega_{1}\right), i, k=3,4$.

There exist $M, m>0$ such that

$$
\begin{aligned}
& \sum_{i, k=1}^{4} d_{i k} t_{k} t_{i} \geq m|t|_{\mathbb{R}^{4}}^{2}, \quad \sum_{i=1}^{4}\left|\sum_{k=1}^{4} d_{i k} t_{k}\right|^{2} \leq M^{2}|t|_{\mathbb{R}^{4}}^{2} \forall t \in \mathbb{R}^{4}, \text { a.e. on } \Omega_{0} \\
& \sum_{i, k=3}^{4} \widetilde{d}_{i k} t_{k} t_{i} \geq m|t|_{\mathbb{R}^{2}}^{2}, \quad \sum_{i=3}^{4}\left|\sum_{k=3}^{4} \widetilde{d}_{i k} t_{k}\right|^{2} \leq M^{2}|t|_{\mathbb{R}^{2}}^{2} \forall t \in \mathbb{R}^{2}, \text { a.e. on } \Omega_{1} \\
& m \leq d_{i} \leq M, i=1, \ldots, 4, \text { a.e. on } \Omega_{0}, \quad m \leq \widetilde{d}_{i} \leq M, i=3,4, \text { a.e. on } \Omega_{1} .
\end{aligned}
$$

For $s \geq 2$ the operator $\bar{A}$ maps $X_{s}$ continuously into $X_{s^{\prime}}^{*}$. In Theorem 5.1 we show that for $s \geq 2$ and sufficiently near to 2 the operator $\bar{A}$ from $X_{s}$ to $X_{s^{\prime}}^{*}$ is onto, too. We start with some preliminary results.

Lemma 5.1 Let $X$ be a Banach space with norm $\|\cdot\|$, and let $\|\cdot\|_{0}$ be an equivalent norm,

$$
c_{1}\|u\| \leq\|u\|_{0} \leq c_{2}\|u\| \quad \forall u \in X
$$

Let $\|\cdot\|_{*}$ and $\|\cdot\|_{0 *}$ denote the canonical norms in the dual space $X^{*}$. Then

$$
\frac{1}{c_{2}}\|h\|_{*} \leq\|h\|_{0 *} \leq \frac{1}{c_{1}}\|h\|_{*} \quad \forall h \in X^{*}
$$

Lemma 5.2 For all $k \in \mathbb{N}$, all $a=\left(a_{1}, \ldots, a_{k}\right) \in \mathbb{R}_{+}^{k}$ and all $p \in(1, \infty)$ there holds the estimate

$$
c_{1}(p)\left(\sum_{i=1}^{k} a_{i}^{2}\right)^{\frac{p}{2}} \leq \sum_{i=1}^{k} a_{i}^{p} \leq c_{2}(p)\left(\sum_{i=1}^{k} a_{i}^{2}\right)^{\frac{p}{2}}
$$

where

$$
\begin{array}{lll}
p<2: & c_{1}(p)=1, & c_{2}(p)=k^{1-\frac{p}{2}} \\
p=2: & c_{1}(p)=1, & c_{2}(p)=1 \\
p>2: & c_{1}(p)=k^{1-\frac{p}{2}}, & c_{2}(p)=1
\end{array}
$$

Note that for every fixed $k \in \mathbb{N}$ the functions $c_{1}$ and $c_{2}$ are continuous functions of $p$ and that $c_{1}(p), c_{2}(p) \rightarrow 1$ if $p \rightarrow 2$.

Lemma 5.3 Let $p \geq 2, p^{\prime}$ the dual exponent and let $B_{i, p}, B_{i, p^{\prime}}^{*}, i=1, \ldots, m$, be a scale of Banach spaces. On the cross products $B_{p}=B_{1, p} \times \cdots \times B_{m, p}$ and $B_{p^{\prime}}^{*}=B_{1, p^{\prime}}^{*} \times \cdots \times B_{m, p^{\prime}}^{*}$ we use the norms

$$
\|u\|_{B_{p}}^{p}=\sum_{i=1}^{m}\left\|u_{i}\right\|_{B_{i, p}}^{p} \text { analogously } B_{p^{\prime}}, \quad\|h\|_{B_{p}^{*}}^{p^{\prime}}=\sum_{i=1}^{m}\left\|h_{i}\right\|_{B_{i, p}^{*}}^{p^{\prime}} \text { analogously } B_{p^{\prime}}^{*} .
$$

Suppose that $D_{i}: B_{i, p^{\prime}}^{*} \rightarrow B_{i, p}$ are linear continuous maps with $\left\|D_{i}\right\|=M_{i, p}$. Then $D: B_{p^{\prime}}^{*} \rightarrow B_{p}$ with $D h=\left(D_{1} h_{1}, \ldots, D_{m} h_{m}\right)$ is a linear continuous map with

$$
\|D\| \leq \max _{i=1, \ldots, m}\left\{M_{i, p}\right\} .
$$

Proof. Because of

$$
\|D\|=\sup _{h \in B_{p^{\prime}}^{*},\|h\|_{B_{p^{\prime}}^{*}} \leq 1}\|D h\|_{B_{p}}=\sup _{h \in B_{p^{\prime}}^{*},\|h\|_{B_{p^{\prime}}^{*}} \leq 1 \psi \in B_{p}^{*},\|\psi\|_{B_{p}^{*} \leq 1}}\langle\psi, D h\rangle_{B_{p}}
$$

and the estimate

$$
\begin{aligned}
\langle\psi, D h\rangle_{B_{p}} & =\sum_{i=1}^{m}\left\langle\psi_{i}, D_{i} h_{i}\right\rangle_{B_{i, p}} \leq \sum_{i=1}^{m} M_{i, p}\left\|\psi_{i}\right\|_{B_{i, p}^{*}}\left\|h_{i}\right\|_{B_{i, p^{\prime}}^{*}} \\
& \leq \max _{i=1, \ldots, m} M_{i, p} \sum_{i=1}^{m}\left\|\psi_{i}\right\|_{B_{i, p}^{*}}\left\|h_{i}\right\|_{B_{i, p^{\prime}}^{*}}^{*} \\
& \leq \max _{i=1, \ldots, m} M_{i, p}\left(\sum_{i=1}^{m}\left\|\psi_{i}\right\|_{B_{i, p}^{*}}^{p^{\prime}}\right)^{\frac{1}{p^{\prime}}}\left(\sum_{i=1}^{m}\left\|h_{i}\right\|_{B_{i, p^{\prime}}^{*}}^{p}\right)^{\frac{1}{p}} \\
& \leq \max _{i=1, \ldots, m} M_{i, p}\|\psi\|_{B_{p}^{*}}\|h\|_{B_{p^{\prime}}^{*}}^{*}
\end{aligned}
$$

we obtain $\|D\| \leq \max _{i=1, \ldots, m} M_{i, p}$.
Remember the definition of function spaces at the beginning of Section 3. We define the operator $L_{G}: W_{0}^{1,2}(G) \rightarrow L^{2}(\Omega)^{3}=Y_{\Omega}^{2}$ by $L_{G} y=(y, \nabla y), y \in W_{0}^{1,2}(G)$. Then $L_{G}^{*} L_{G}=J_{G}$, where $J_{G}$ denotes the duality map of the space $W_{0}^{1,2}(G)$,

$$
\left\langle J_{G} y, \phi\right\rangle_{W_{0}^{1,2}(G)}=\int_{\Omega}(y \phi+\nabla y \cdot \nabla \phi) \mathrm{d} x, \quad y, \phi \in W_{0}^{1,2}(G) .
$$

If $s>2$ then $L_{G}$ maps $W_{0}^{1, s}(G)$ continuously into $Y_{\Omega}^{s}$, and $L_{G}^{*}$ maps $Y_{\Omega}^{s}$ continuously into $W_{0}^{1, s^{\prime}}(G)^{*}$. Moreover, for $s>2$ we obtain that $J_{G}$ maps $W_{0}^{1, s}(G)$ into $W_{0}^{1, s^{\prime}}(G)^{*}$ and that $J_{G}$ is continuous as a map from $W_{0}^{1, s}(G)$ into $W_{0}^{1, s^{\prime}}(G)^{*}$. We use $M_{s}^{G}$ as abbreviation for

$$
M_{s}^{G}=\sup \left\{\|y\|_{W_{0}^{1, s}(G)}: y \in W_{0}^{1, s}(G),\left\|J_{G} y\right\|_{W_{0}^{1, s^{\prime}}(G)^{*}} \leq 1\right\} .
$$

Since by assumption (A1) the set $G \subset \mathbb{R}^{2}$ is regular in the sense of Gröger [9] there exists $r_{G}>2$ such that $J_{G}$ maps $W_{0}^{1, r_{G}}(G)$ onto $W_{0}^{1, r_{G}^{\prime}}(G)^{*}$. Moreover, $M_{2}^{G}=1$, and for $s \in\left[2, r_{G}\right]$ the mappings are onto, too, and we have

$$
\begin{equation*}
M_{s}^{G} \leq M_{r_{G}}^{G}, \quad \text { where } \theta \text { is given by the relation } \quad \frac{1}{s}=\frac{1-\theta}{2}+\frac{\theta}{r_{G}} \tag{5.19}
\end{equation*}
$$

(see Sect. 3 and Lemma 1 in [9]).
Analogously we define for the regular set $G_{0}$ operators $L_{G_{0}}, J_{G_{0}}$ and obtain a corresponding exponent $r_{G_{0}}$ and quantities $M_{s}^{G_{0}}$. Now we define the four component operators $L, J$ working componentwise

$$
\begin{array}{lll}
L: X_{2} \rightarrow \mathcal{L}^{2}, & L z=\left(L_{G_{0}} z_{1}, L_{G_{0}} z_{2}, L_{G} z_{3}, L_{G} z_{4}\right), & z \in X_{2}, \\
L^{*}: \mathcal{L}^{2} \rightarrow X_{2}^{*}, & L^{*} u=\left(L_{G_{0}}^{*} u_{1}, L_{G_{0}}^{*} u_{2}, L_{G}^{*} u_{3}, L_{G}^{*} u_{4}\right), & u \in \mathcal{L}^{2}, \\
J: X_{2} \rightarrow X_{2}^{*}, & J z=\left(J_{G_{0}} z_{1}, J_{G_{0}} z_{2}, J_{G} z_{3}, J_{G} z_{4}\right), & z \in X_{2} .
\end{array}
$$

Note that for $s>2$ the (restricted) operators $L: X_{s} \rightarrow \mathcal{L}^{s}$ as well as $L^{*}: \mathcal{L}^{s} \rightarrow X_{s^{\prime}}^{*}$ are linear continuous maps with norm less or equal to one. Moreover, it results that $J$ maps $X_{s}$ into $X_{s^{\prime}}^{*}$ and that $J$ is continuous as a map from $X_{s}$ into $X_{s^{\prime}}^{*}$, too. We will use $M_{s}$ as abbreviation for

$$
M_{s}=\sup \left\{\|z\|_{X_{s}}: z \in X_{s},\|J z\|_{X_{s^{\prime}}^{*}} \leq 1\right\} .
$$

Let $\widehat{r}:=\min \left\{r_{G}, r_{G_{0}}\right\}$. Then

$$
\begin{align*}
M_{\widehat{r}}^{G_{0}}=\left(M_{r_{G_{0}}}^{G_{0}}\right)^{\widehat{\theta}}, & \text { where } \frac{1}{\widehat{r}}=\frac{\widehat{\theta}}{r_{G_{0}}}+\frac{1-\widehat{\theta}}{2}, \\
M_{\widehat{r}}^{G}=\left(M_{r_{G}}^{G}\right)^{\tilde{\theta}}, & \text { where } \frac{1}{\widehat{r}}=\frac{\widetilde{\theta}}{r_{G}}+\frac{1-\widetilde{\theta}}{2} . \tag{5.20}
\end{align*}
$$

Lemma 5.4 We assume (A1). For $\widehat{r}$ the map $J$ is from $X_{\widehat{r}}$ onto $X_{\widehat{r}^{\prime}}^{*}$. Moreover, for all $s \in[2, \widehat{r}]$ the estimate

$$
M_{s} \leq \max \left\{\left(M_{\widehat{r}}^{G_{0}}\right)^{\theta},\left(M_{\widehat{r}}^{G}\right)^{\theta}\right\} \quad \text { with } \frac{1}{s}=\frac{\theta}{\widehat{r}}+\frac{1-\theta}{2}
$$

is fulfilled.

Proof. For $s \in[2, \widehat{r}]$ the onto-properties of $J_{G_{0}}$ and $J_{G}$ supply the onto-property of the four component map $J$. The proof of the inequality is based on Lemma 5.3 and uses (5.19), (5.20). Setting $m=4$,

$$
\begin{array}{llll}
B_{i, s}=W_{0}^{1, s}\left(G_{0}\right), & D_{i}=\left(J_{G_{0}}\right)^{-1}: B_{i, s^{\prime}}^{*} \rightarrow B_{i, s}, & M_{i, s}=\left(M_{\widehat{r}}^{G_{0}}\right)^{\theta}, & i=1,2, \\
B_{i, s}=W_{0}^{1, s}(G), & D_{i}=\left(J_{G}\right)^{-1}: B_{i, s^{\prime}}^{*} \rightarrow B_{i, s}, & M_{i, s}=\left(M_{\widehat{r}}^{G}\right)^{\theta}, & i=3,4,
\end{array}
$$

where

$$
\frac{1}{s}=\frac{\theta}{\widehat{r}}+\frac{1-\theta}{2}
$$

we can apply Lemma 5.3. Then the assertion of the lemma follows.
According to Lemma 5.4 it results $M_{2}=1$ and the quantity $M_{s}$ depends continuously on $s$ such that $M_{s} \rightarrow 1$ as $s \rightarrow 2$.

We introduce the function $b=\left(b_{1}, b_{2}, b_{3}, b_{4}\right)$, where $b_{i}: \Omega_{0} \times\left(\mathbb{R}^{3}\right)^{4} \rightarrow \mathbb{R}^{3}, i=1,2, b_{i}: \Omega \times$ $\left(\mathbb{R}^{3}\right)^{4} \rightarrow \mathbb{R}^{3}, i=3,4$, are defined by

$$
\begin{aligned}
b_{i}\left(x, \eta_{1}, \eta_{2}, \eta_{3}, \eta_{4}\right)= & \left(d_{i}(x) \eta_{i}^{1}, \sum_{k=1}^{4} d_{i k}(x) \eta_{k}^{2}, \sum_{k=1}^{4} d_{i k}(x) \eta_{k}^{3}\right), \quad i=1,2 \\
b_{i}\left(x, \eta_{1}, \eta_{2}, \eta_{3}, \eta_{4}\right)= & \left\{\begin{array}{ll}
\left(d_{i}(x) \eta_{i}^{1}, \sum_{k=1}^{4} d_{i k}(x) \eta_{k}^{2}, \sum_{k=1}^{4} d_{i k}(x) \eta_{k}^{3}\right) & \text { if } x \in \Omega_{0} \\
\left(\widetilde{d}_{i}(x) \eta_{i}^{1}, \sum_{k=3}^{4} \widetilde{d}_{i k}(x) \eta_{i}^{2}, \sum_{k=3}^{4} \widetilde{d}_{i k}(x) \eta_{i}^{3}\right) & \text { if } x \in \Omega \backslash \Omega_{0}
\end{array} \quad i=3,4,\right. \\
\eta= & \left(\eta_{1}, \eta_{2}, \eta_{3}, \eta_{4}\right) \in\left(\mathbb{R}^{3}\right)^{4}, \eta_{i}=\left(\eta_{i}^{1}, \eta_{i}^{2}, \eta_{i}^{3}\right), i=1, \ldots, 4
\end{aligned}
$$

Here $d_{i k}, \widetilde{d}_{i k}, d_{i}$ and $\widetilde{d}_{i}$ are the coefficient functions from (5.18). $\mathbb{R}^{3}$ as well as $\left(\mathbb{R}^{3}\right)^{4}$ is considered with the usual Euclidean norm. Clearly, $b$ is linear in the argument $\eta$ and according to assumption (B) the estimates

$$
\begin{gather*}
b(x, \eta) \cdot \eta \geq m|\eta|_{\left(\mathbb{R}^{3}\right)^{4}}^{2},  \tag{5.21}\\
|b(x, \eta)|_{\left(\mathbb{R}^{3}\right)^{4}}^{2} \leq M^{2}|\eta|_{\left(\mathbb{R}^{3}\right)^{4}}^{2} \quad \forall x \in \Omega_{0}, \\
b_{3}(x, \eta) \cdot \eta_{3}+b_{4}(x, \eta) \cdot \eta_{4} \geq m\left(\left|\eta_{3}\right|_{\mathbb{R}^{3}}^{2}+\left|\eta_{4}\right|_{\mathbb{R}^{3}}^{2}\right), \\
\left|b_{3}(x, \eta)\right|_{\mathbb{R}^{3}}^{2}+\left|b_{4}(x, \eta)\right|_{\mathbb{R}^{3}}^{2} \leq M^{2}\left(\left|\eta_{3}\right|_{\mathbb{R}^{3}}^{2}+\left|\eta_{4}\right|_{\mathbb{R}^{3}}^{2}\right) \quad \forall x \in \Omega_{1} \tag{5.22}
\end{gather*}
$$

are fulfilled. We set $\alpha=m / M^{2}$ and define on $\mathcal{L}^{2}$ the operator $B_{2}$ by

$$
\left(B_{2} y\right)(x)=y(x)-\alpha b(x, y(x)), \quad y \in \mathcal{L}^{2}
$$

Now we restrict this operator $B_{2}$ to the space $\mathcal{L}^{s}$ with $s>2$ and obtain a linear mapping $B_{s}=\left.B_{2}\right|_{\mathcal{L}^{s}}$ from $\mathcal{L}^{s}$ into itself. In the next estimate we make use of an equivalent norm of $\mathcal{L}^{s}$ :

$$
\|y\|_{0, \mathcal{L}^{s}}=\left(\int_{\Omega_{0}}\left(|y(x)|_{\left(\mathbb{R}^{3}\right)^{4}}^{2}\right)^{s / 2} \mathrm{~d} x+\int_{\Omega_{1}}\left(\left|y_{3}(x)\right|_{\mathbb{R}^{3}}^{2}+\left|y_{4}(x)\right|_{\mathbb{R}^{3}}^{2}\right)^{s / 2} \mathrm{~d} x\right)^{1 / s}, \quad y \in \mathcal{L}^{s}
$$

Using $(5.21),(5.22)$ the norm of the mapping $B_{s}$ can be estimated as follows

$$
\begin{aligned}
\left\|B_{s} y\right\|_{0, \mathcal{L}^{s}}^{s} & =\int_{\Omega_{0}}\left(\left|\left(B_{s} y\right)(x)\right|_{\left(\mathbb{R}^{3}\right)^{4}}^{2}\right)^{s / 2} \mathrm{~d} x+\int_{\Omega_{1}}\left(\left|\left(B_{s} y\right)_{3}(x)\right|_{\mathbb{R}^{3}}^{2}+\left|\left(B_{s} y\right)_{4}(x)\right|_{\mathbb{R}^{3}}^{2}\right)^{s / 2} \mathrm{~d} x \\
& =\int_{\Omega_{0}}\left(|y|_{\left(\mathbb{R}^{3}\right)^{4}}^{2}+\alpha^{2}|b(\cdot, y(\cdot))|_{\left(\mathbb{R}^{3}\right)^{4}}^{2}-2 \alpha b(x, y(\cdot)) \cdot y\right)^{s / 2} \mathrm{~d} x \\
& +\int_{\Omega_{1}}\left(\sum_{i=3,4}\left(\left|y_{i}(x)\right|_{\mathbb{R}^{3}}^{2}+\alpha^{2}\left|b_{i}(\cdot, y(\cdot))\right|_{\mathbb{R}^{3}}^{2}-2 \alpha b_{i}(\cdot, y(\cdot)) \cdot y_{i}\right)\right)^{s / 2} \mathrm{~d} x \\
& \leq\left(1-\frac{m^{2}}{M^{2}}\right)^{s / 2}\left(\int_{\Omega_{0}}\left(|y(x)|_{\left.\left(\mathbb{R}^{3}\right)^{4}\right)^{s / 2}}^{2} \mathrm{~d} x+\int_{\Omega_{1}}\left(\left|y_{3}(x)\right|_{\mathbb{R}^{3}}^{2}+\left|y_{4}(x)\right|_{\mathbb{R}^{3}}^{2}\right)^{s / 2} \mathrm{~d} x\right)\right. \\
& \leq\left(1-\frac{m^{2}}{M^{2}}\right)^{s / 2}\|y\|_{0, \mathcal{L}^{s}}^{s} \quad \forall y \in \mathcal{L}^{s} .
\end{aligned}
$$

Lemma 5.2 ensures the estimate

$$
4^{1 / s-1 / 2}\|y\|_{0, \mathcal{L}^{s}} \leq\|y\|_{\mathcal{L}^{s}} \leq\|y\|_{0, \mathcal{L}^{s}} \quad \forall y \in \mathcal{L}^{s}
$$

which leads to

$$
\begin{align*}
\left\|B_{s} y\right\|_{\mathcal{L}^{s}} \leq\left\|B_{s} y\right\|_{0, \mathcal{L}^{s}} & \leq\left(1-\frac{m^{2}}{M^{2}}\right)^{1 / 2}\|y\|_{0, \mathcal{L}^{s}}  \tag{5.23}\\
& \leq 4^{1 / 2-1 / s}\left(1-\frac{m^{2}}{M^{2}}\right)^{1 / 2}\|y\|_{\mathcal{L}^{s}} \quad \forall y \in \mathcal{L}^{s} .
\end{align*}
$$

Theorem 5.1 We suppose (A1) and (B). Then, the operator $\bar{A}$ defined in (5.18) maps $X_{s}$ onto the space $X_{s^{\prime}}^{*}$ provided that $s \in\left[2, q_{0}\right]$ and

$$
4^{1 / 2-1 / s} M_{s}\left(1-\frac{m^{2}}{M^{2}}\right)^{1 / 2}<1
$$

In particular, there exists a $q_{1} \in\left(2, q_{0}\right]$ such that $\bar{A}$ maps $X_{q_{1}}$ onto the space $X_{q_{1}}^{*}$.
Proof. Here we adapt the proof of Theorem 1 in Gröger [9] to strongly coupled systems of elliptic equations with different domains of definition. Note that for $z \in X_{s}$ we have $\frac{m}{M^{2}} J^{-1} \bar{A} z=z-J^{-1} L^{*} B_{s} L z$. For every fixed $h \in X_{s^{\prime}}^{*}, s \in[2, q]$, we define the operator $Q_{h}: X_{s} \rightarrow X_{s}$ by

$$
Q_{h} z:=J^{-1}\left(L^{*} B_{s} L z+\frac{m}{M^{2}} h\right)=z-\frac{m}{M^{2}} J^{-1}(\bar{A} z-h), \quad z \in X_{s} .
$$

Due to the properties of the operators $B_{s}, L, L^{*}$ and $J^{-1}$ (in particular see (5.23) and Lemma 5.4) we find

$$
\begin{aligned}
\left\|Q_{h} z-Q_{h} \bar{z}\right\|_{X_{s}} & \leq M_{s}\left\|L^{*}\right\|_{\mathcal{L}\left(\mathcal{L}^{s}, X_{s^{\prime}}^{*}\right)}\left\|B_{s}\right\|_{\mathcal{L}\left(\mathcal{L}^{s}, \mathcal{L}^{s}\right)}\|L\|_{\mathcal{L}\left(X_{s}, \mathcal{L}^{s}\right)}\|z-\bar{z}\|_{X_{s}} \\
& \leq 4^{1 / 2-1 / s} M_{s}\left(1-\frac{m^{2}}{M^{2}}\right)^{1 / 2}\|z-\bar{z}\|_{X_{s}} .
\end{aligned}
$$

Note that $4^{1 / 2-1 / s} M_{s}\left(1-\frac{m^{2}}{M^{2}}\right)^{1 / 2}$ continuously depends on $s$ and

$$
4^{1 / 2-1 / s} M_{s}\left(1-\frac{m^{2}}{M^{2}}\right)^{1 / 2} \rightarrow\left(1-\frac{m^{2}}{M^{2}}\right)^{1 / 2}<1 \text { for } s \rightarrow 2
$$

Thus, there exists an exponent $s_{0} \in\left(2, q_{0}\right]$ such that for all $s \in\left[2, s_{0}\right)$, we have

$$
4^{1 / 2-1 / s} M_{s}\left(1-\frac{m^{2}}{M^{2}}\right)^{1 / 2}<1
$$

which guarantees that $Q_{h}: X_{s} \rightarrow X_{s}$ is strictly contractive. According to the definition of $Q_{h}$ the fixed point $z \in X_{s}$ is a solution of $\bar{A} z=h$. Therefore $\bar{A}$ maps the space $X_{s}$ onto $X_{s^{\prime}}^{*}$.

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[^0]:    2000 Mathematics Subject Classification. 35J55, 35A07, 35R05, 80A20.
    Key words and phrases. Energy models; mass, charge and energy transport in heterostructures; strongly coupled elliptic systems; mixed boundary conditions; Implicit Function Theorem; existence; uniqueness; regularity.

